

Providence - November 6th 2009

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Travelling Pulses for the  
Discrete FitzHugh-Nagumo System

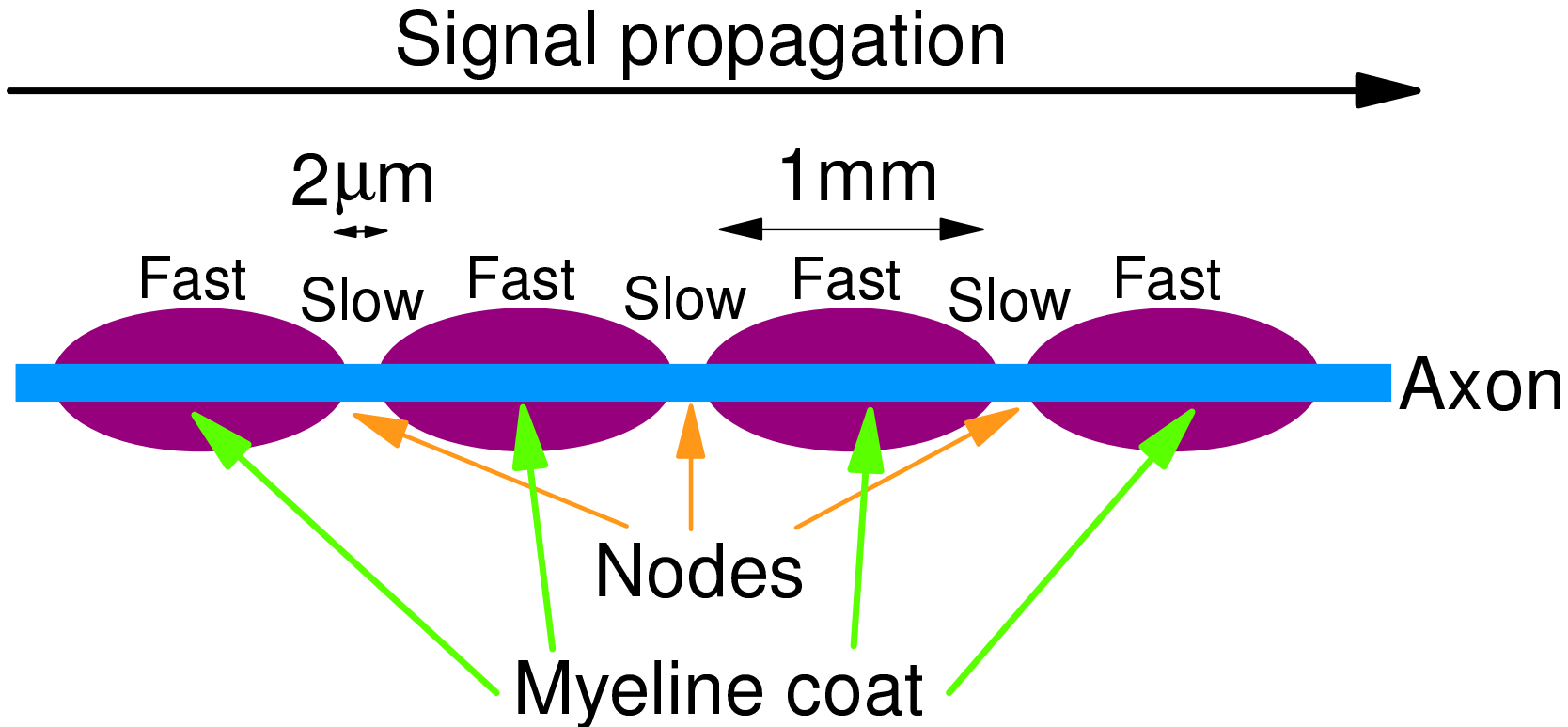


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(Joint work with B. Sandstede )

# Signal Propagation through Nerves

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Nerve fibres carry signals over large distances (meter range).

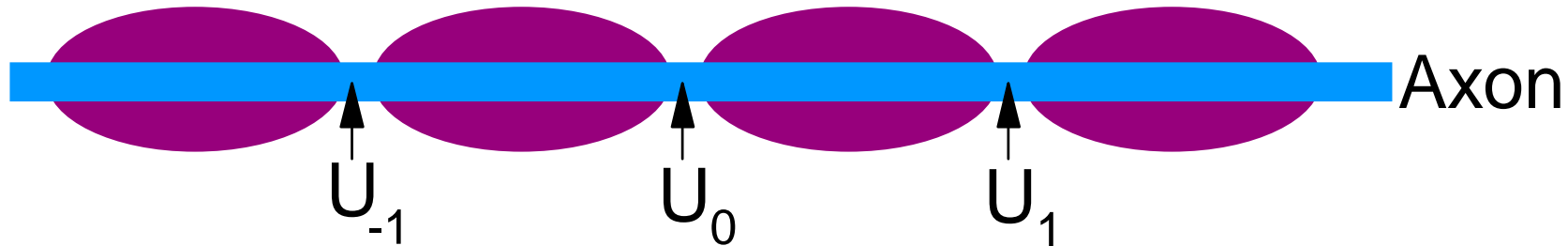


- Fiber has myeline coating with periodic gaps called *nodes of Ranvier* .
- Fast propagation in coated regions, but signal loses strength rapidly (mm-range)
- Slow propagation in gaps, but signal chemically reinforced.

## Signal Propagation: The Model

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One is interested in the potential  $U_j$  at the node sites.



Signals appear to "hop" from one node to the next [Lillie, 1925].

Ionic current has sodium and potassium component.

Electro-chemical analysis leads to the two component LDE [Keener and Sneyd, 1998]

$$\begin{aligned}\dot{U}_j(t) &= U_{j+1}(t) + U_{j-1}(t) - 2U_j(t) + g(U_j(t); a) - W_j(t), \\ \dot{W}_j(t) &= \epsilon[U_j(t) - \gamma W_j(t)],\end{aligned}$$

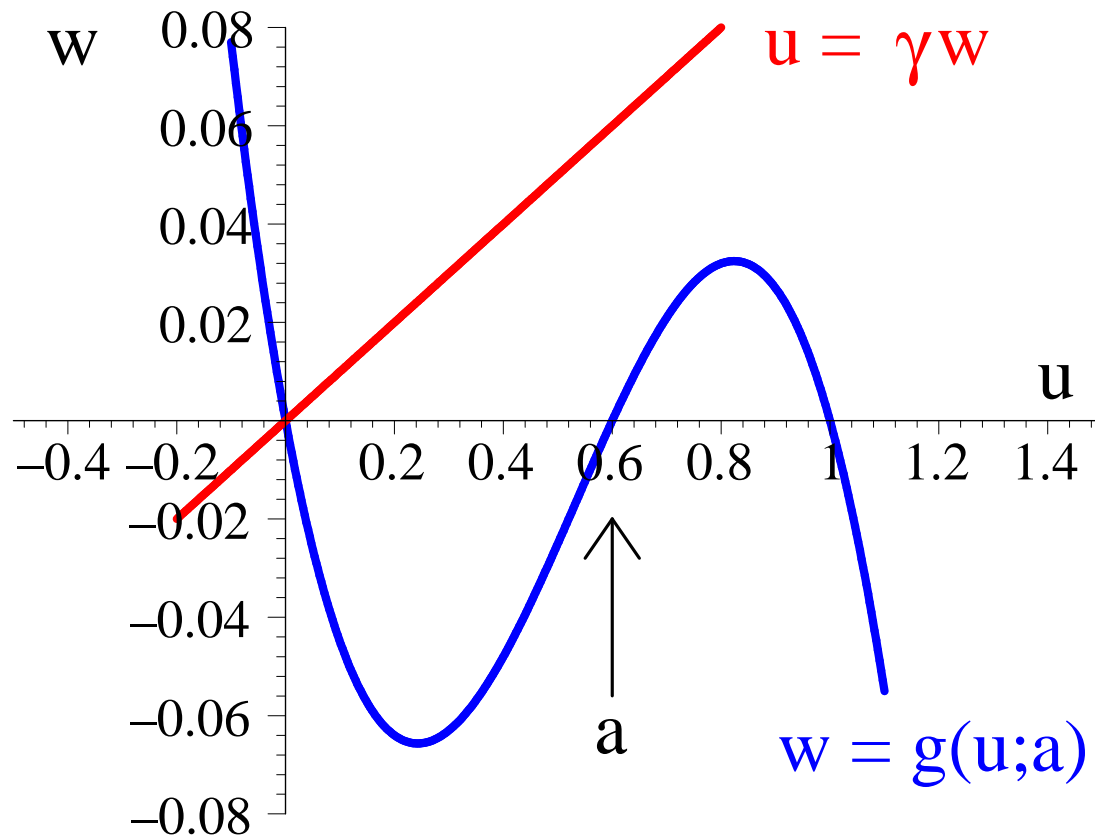
posed on a 1-dimension lattice, i.e.  $j \in \mathbb{Z}$ .

Potassium recovery encoded in second equation.

# Signal Propagation: Nonlinearity

Recall the dynamics:

$$\begin{aligned}\dot{U}_j(t) &= U_{j+1}(t) + U_{j-1}(t) - 2U_j(t) + g(U_j(t); a) - W_j(t), \\ \dot{W}_j(t) &= \epsilon[U_j(t) - \gamma W_j(t)].\end{aligned}$$



Bistable nonlinearity  $g$  given by

$$g(u; a) = u(a - u)(u - 1).$$

Parameter  $\gamma > 0$  small so

$$w \neq g(\gamma w; a)$$

$$w = g(u; a) \text{ for } w \neq 0.$$

# Signal Propagation: FitzHugh-Nagumo PDE

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The discrete FitzHugh-Nagumo system arises by discretizing the FH-N PDE

$$\begin{aligned}U_t &= U_{xx} + g(U; a) - W, \\W_t &= \epsilon[U - \gamma W].\end{aligned}$$

- Many authors have studied this equation.
- Starting point: travelling wave Ansatz

$$(U, W)(x, t) = (u, w)(x + ct).$$

This Ansatz yields the ODE

$$\begin{aligned}u' &= v, \\v' &= cv - g(u; a) + w, \\w' &= \frac{\epsilon}{c}(u - \gamma w).\end{aligned}$$

This slow-fast system has served as a prototype for development of geometric singular perturbation theory.

# Signal Propagation: FitzHugh-Nagumo PDE

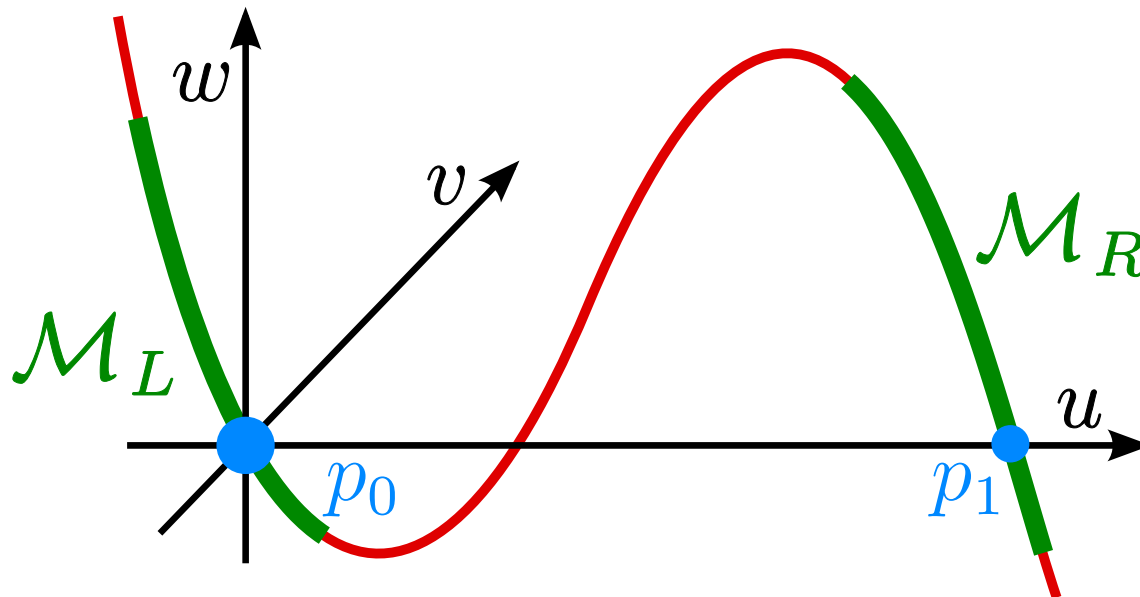
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Choosing  $\epsilon = 0$ , we find

$$\begin{aligned}u' &= v, \\v' &= cv - g(u; a) + w, \\w' &= 0,\end{aligned}$$

admitting an equilibria-manifold  $\mathcal{M} = (u, 0, g(u; a))$ .

Write  $p_0 = (0, 0, 0)$  and  $p_1 = (1, 0, 0)$  and choose  $p_0 \in \mathcal{M}_L \subset \mathcal{M}$  and  $p_1 \in \mathcal{M}_R \subset \mathcal{M}$ ; avoiding knees of the cubic.



# Signal Propagation: FitzHugh-Nagumo PDE

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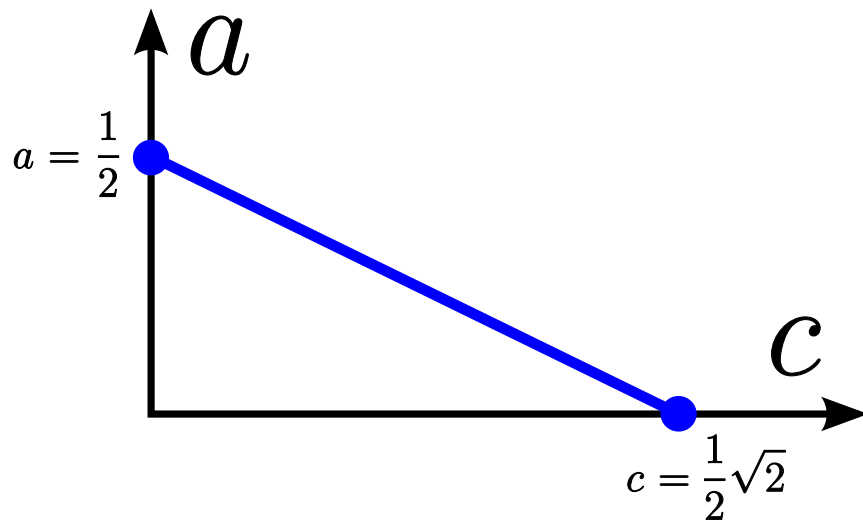
Heteroclinics  $p_0 \rightarrow p_1$  must solve

$$\begin{aligned}u' &= v, \\v' &= cv - g(u; a),\end{aligned}$$

and satisfy  $u(-\infty) = 0$  and  $u(+\infty) = 1$ .

These correspond to travelling pulses of the Nagumo PDE

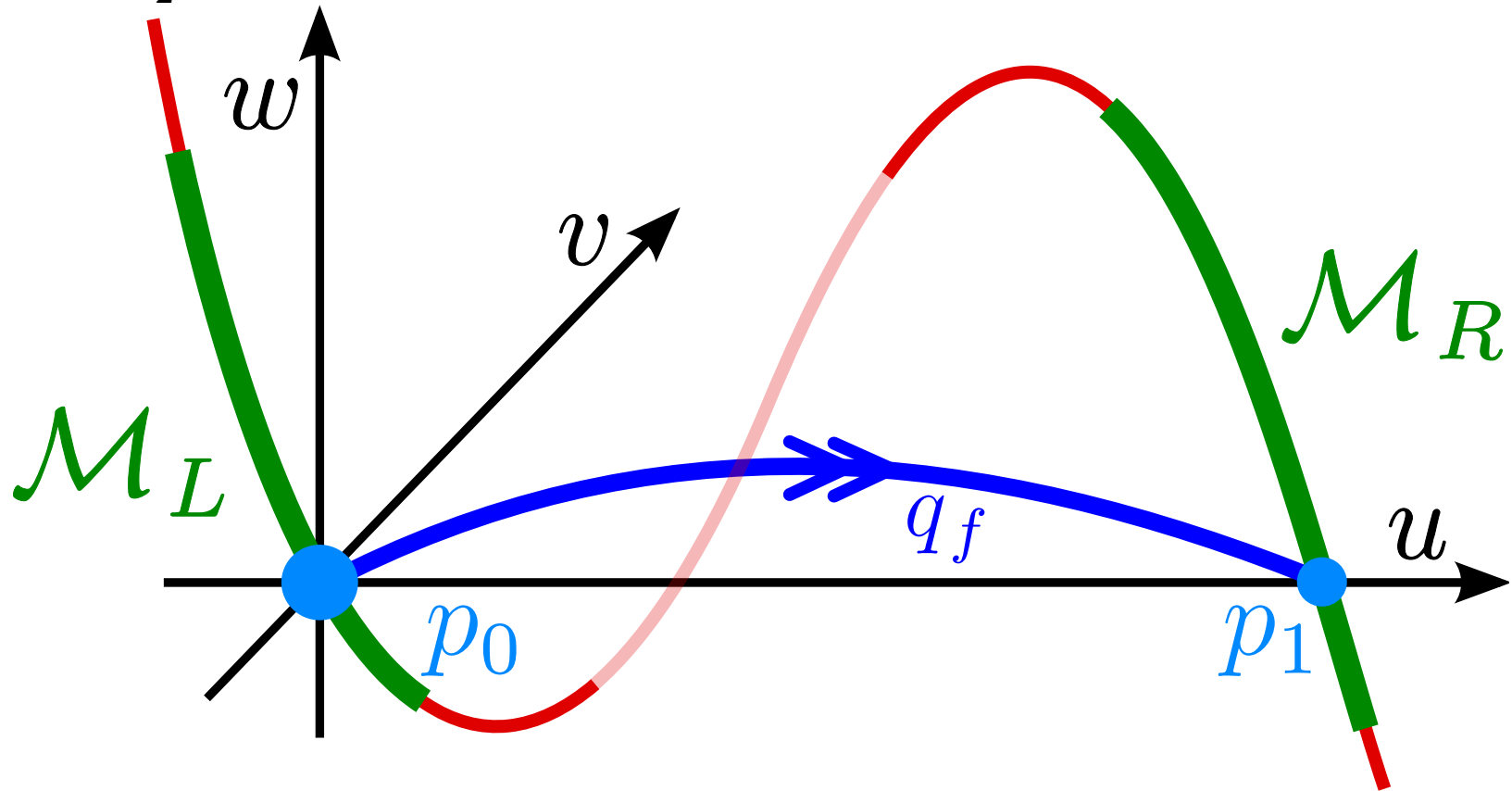
$$U_t = U_{xx} + g(U; a).$$



Existence of such pulses is well-known; explicit calculations are possible for the cubic  $g$ .

# Signal Propagation: FitzHugh-Nagumo PDE

Fix  $0 < a < \frac{1}{2}$ ; there exists wave speed  $c_*$  and front  $q_f$ :



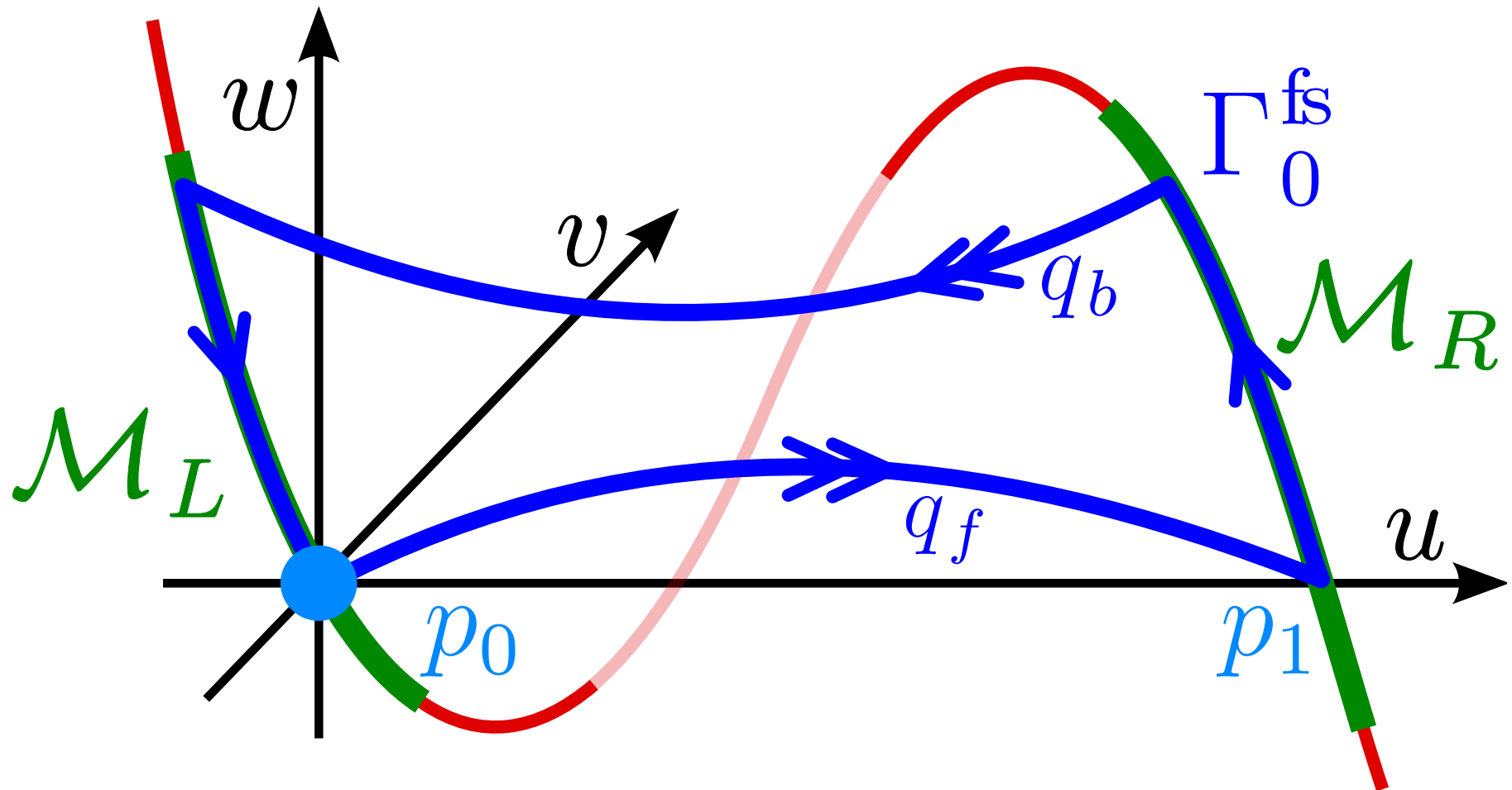
We now need to go back from  $\mathcal{M}_R$  to  $\mathcal{M}_L$ .

Cubic is mirror symmetric around inflection point  $\longrightarrow$  there exists  $w_*$  and profile  $q_b$  connecting  $\mathcal{M}_R$  to  $\mathcal{M}_L$  for same wave speed  $c = c_*$ .



# Signal Propagation: FitzHugh-Nagumo PDE

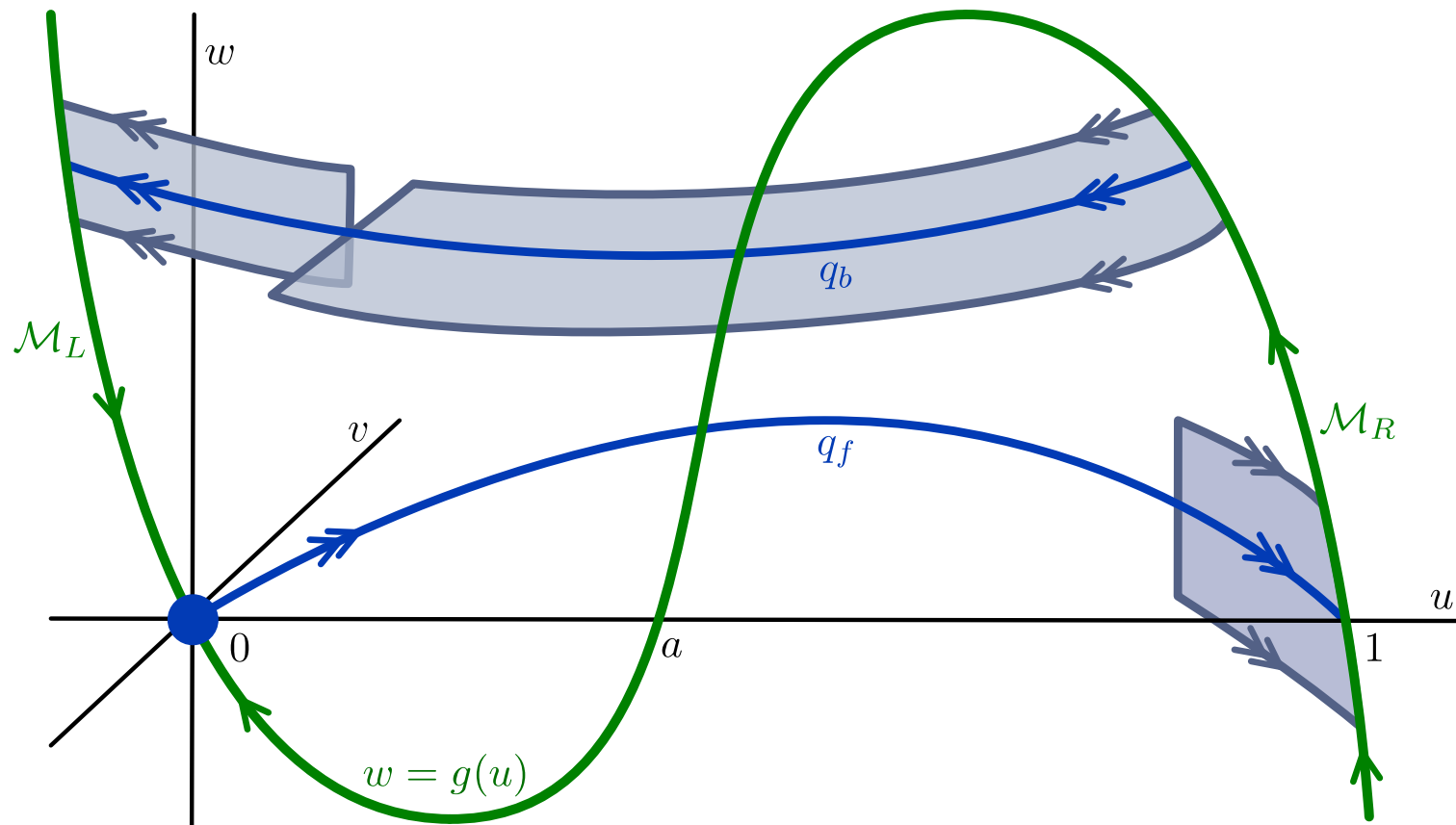
Connecting the pieces we find a fast  $[c_* > 0]$  singular homoclinic orbit  $\Gamma_0^{\text{fs}}$ .



**Classic Theorem:** For sufficiently small  $\epsilon > 0$ , there is a [locally unique] travelling pulse solution to FH-N PDE that winds around  $\Gamma_0^{\text{fs}}$  once, with wavespeed  $c < c_*$ .

# Signal Propagation: FitzHugh-Nagumo PDE

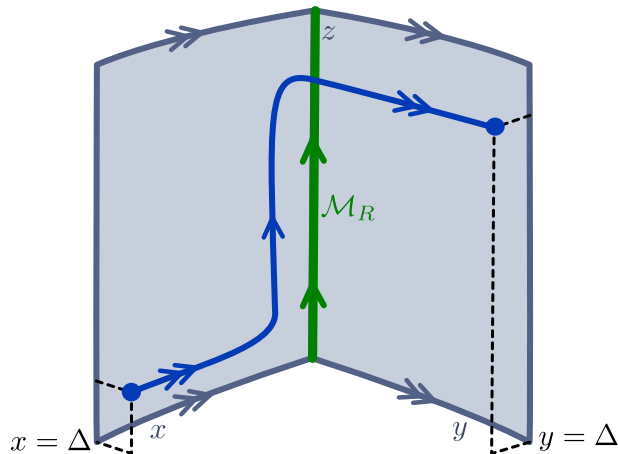
- First proofs given by Carpenter and Hastings [1976].
- 'Modern' proof developed by Jones and coworkers based on transverse intersection of manifolds  $\mathcal{W}^u(0)$  and  $\mathcal{W}^s(\mathcal{M}_L)$ .



Main difficulty: track  $\mathcal{W}^u(0)$  as it spends time  $O(\epsilon^{-1})$  near  $\mathcal{M}_R$ .

# FitzHugh-Nagumo PDE: Exchange Lemma

Exchange Lemma is key tool to track  $\mathcal{W}^u(0)$  near  $\mathcal{M}_R$ .



Fenichel coordinates:

$$\begin{aligned} x' &= -A^s(x, y, z)x \\ y' &= A^u(x, y, z)y \\ z' &= \epsilon[1 + B(x, y, z)xy], \end{aligned}$$

with  $A^s, A^u > \eta > 0$ ;  $A^s, A^u, B$  smooth and bounded.

- Fix small  $\Delta > 0$ .
- Pick  $z_0 \in \mathbb{R}$ ,  $T$  large and  $\epsilon > 0$  small
- Find solution with

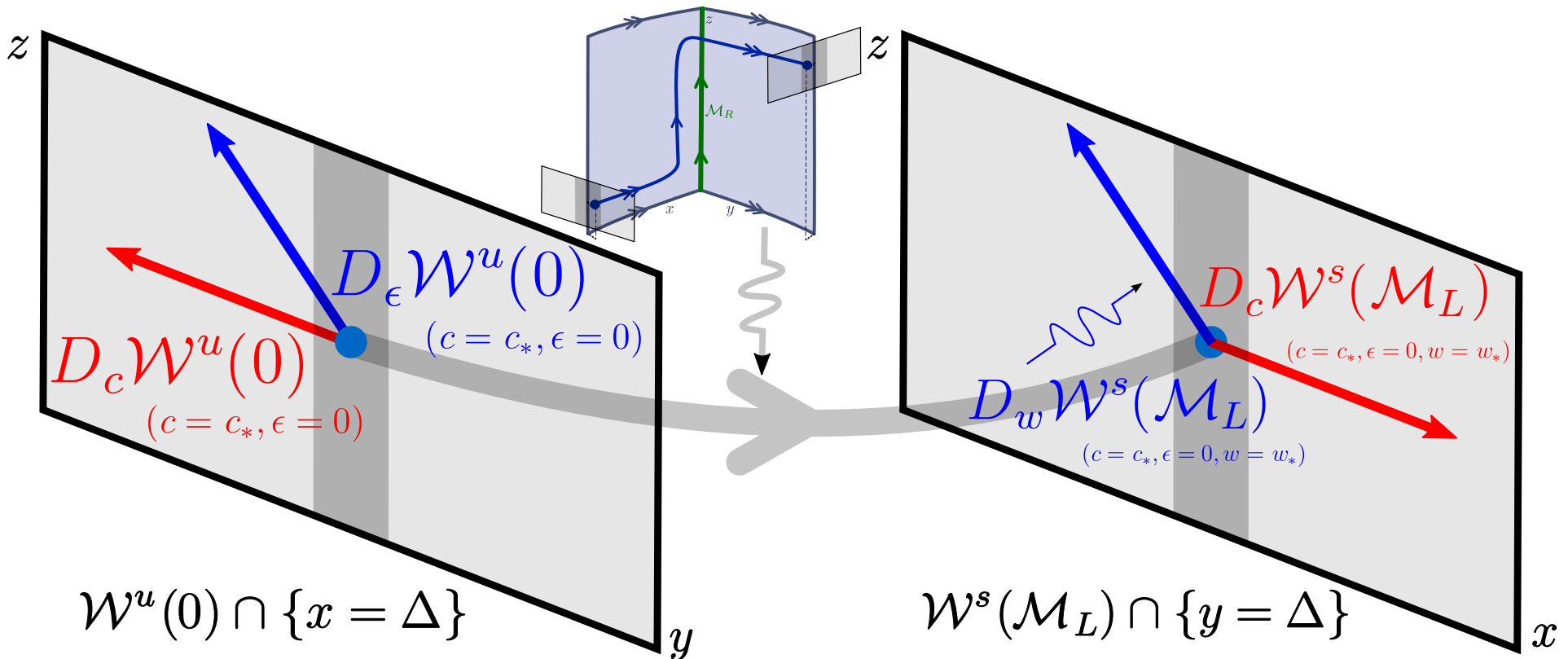
$$x(0) = \Delta, \quad z(0) = z_0, \quad y(T) = \Delta$$

- Exchange Lemma: unique solution exists, bounds:

$$|y(0)| + |x(T)| + |z(T) - z_0 - \epsilon T| = O(e^{-\eta T})$$

# FitzHugh-Nagumo PDE: Exchange Lemma

The problem can now be decomposed into two parts:



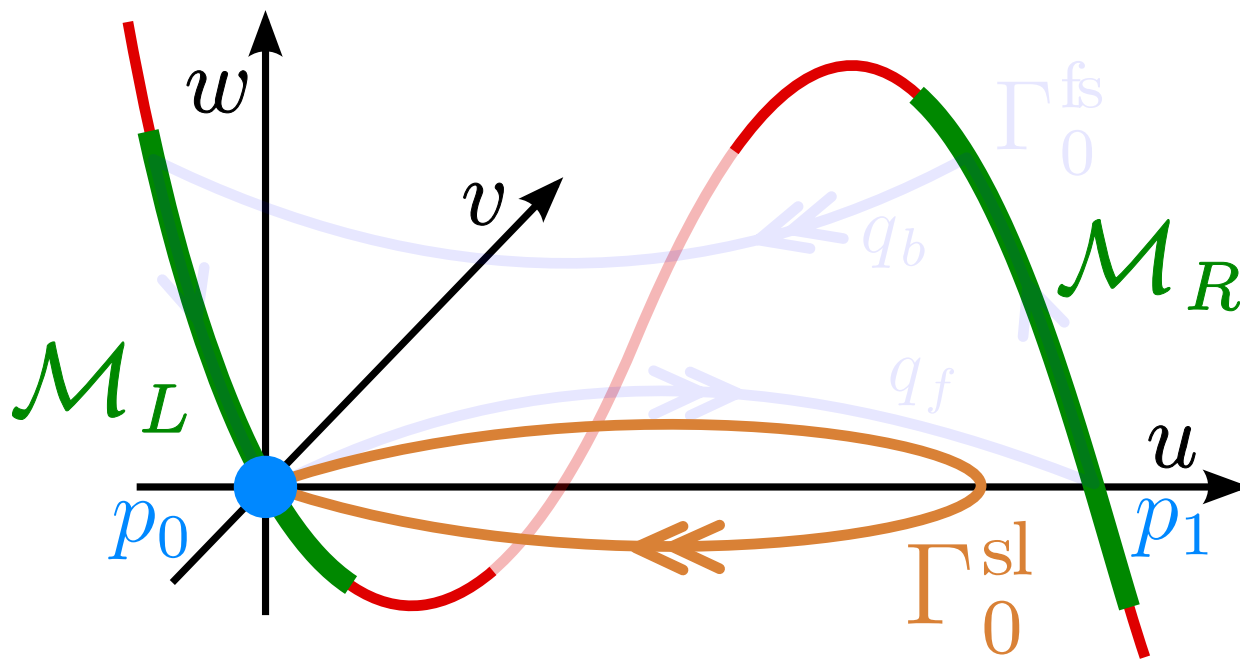
- Intersection  $\mathcal{W}^u(0) \cap \{x = \Delta\}$  can be studied separately from intersection  $\mathcal{W}^s(\mathcal{M}_L) \cap \{y = \Delta\}$ .
- Melnikov identities yield signs of  $D_c \mathcal{W}^u(0)$  etc.
- Exchange Lemma used to link pieces together.

# FitzHugh-Nagumo PDE: Slow Pulses

Recall the travelling wave ODE

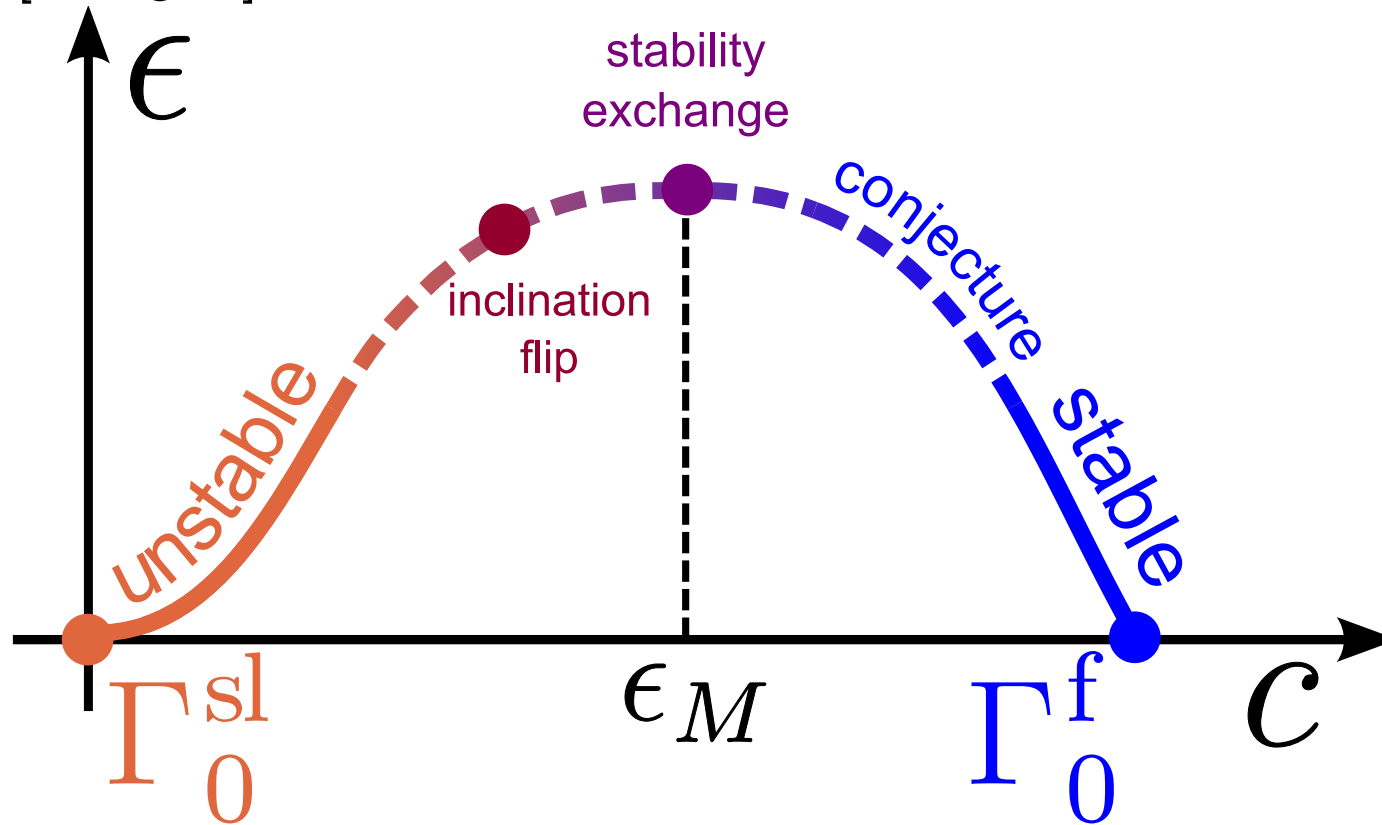
$$\begin{aligned}u' &= v, \\v' &= cv - g(u; a) + w, \\w' &= \frac{\epsilon}{c}(u - \gamma w).\end{aligned}$$

In the singular limit  $c \rightarrow 0$  and  $\frac{\epsilon}{c} \rightarrow 0$ , one finds an additional slow-singular orbit  $\Gamma_0^{\text{sl}}$ .



# FitzHugh-Nagumo PDE: Status

Conjecture [Yanagida]: fast and slow branches are connected.



- Sandstede, Krupa, Szmolyan (1997): for  $a \approx \frac{1}{2}$ , conjecture is true. Inclination-flip somewhere along connecting curve.
- Jones, Yanagida (1984): fast waves are asymptotically stable for full PDE.
- Flores (1991): slow waves are unstable.
- Sandstede: stability change at maximum of curve.

## Discrete FitzHugh-Nagumo LDE

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We return to the discrete FitzHugh-Nagumo system

$$\begin{aligned}\dot{U}_j(t) &= U_{j+1}(t) + U_{j-1}(t) - 2U_j(t) + g(U_j(t); a) - W_j(t), \\ \dot{W}_j(t) &= \epsilon[U_j(t) - \gamma W_j(t)].\end{aligned}$$

Travelling wave Ansatz  $(U_j, W_j)(t) = (u, w)(j + ct)$  leads to

$$\begin{aligned}cu'(\xi) &= u(\xi + 1) + u(\xi - 1) - 2u(\xi) + g(u(\xi); a) - w(\xi), \\ cw'(\xi) &= \epsilon[u(\xi) - \gamma w(\xi)].\end{aligned}$$

This is a singularly perturbed functional differential equation of mixed type (MFDE).

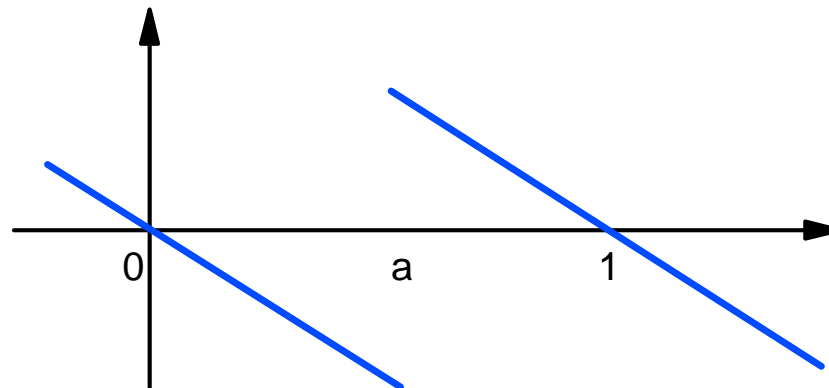
## Discrete FitzHugh-Nagumo - Previous work

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Two main directions for previous work on discrete FitzHugh-Nagumo LDE

$$\begin{aligned}\dot{U}_j(t) &= U_{j+1}(t) + U_{j-1}(t) - 2U_j(t) + g(U_j(t); a) - W_j(t), \\ \dot{W}_j(t) &= \epsilon[U_j(t) - \gamma W_j(t)].\end{aligned}$$

- Rigorous results for specially prepared nonlinearities
  - Chen + Hastings: nonlinearity vanishes identically on critical regions of  $U$  and  $W$ .
  - Tonnelier; Elmer and Van Vleck: explicit calculations with Fourier series for McKean sawtooth caricature:



- Carpio and coworkers: formal results using asymptotic techniques.



# Discrete FitzHugh-Nagumo LDE

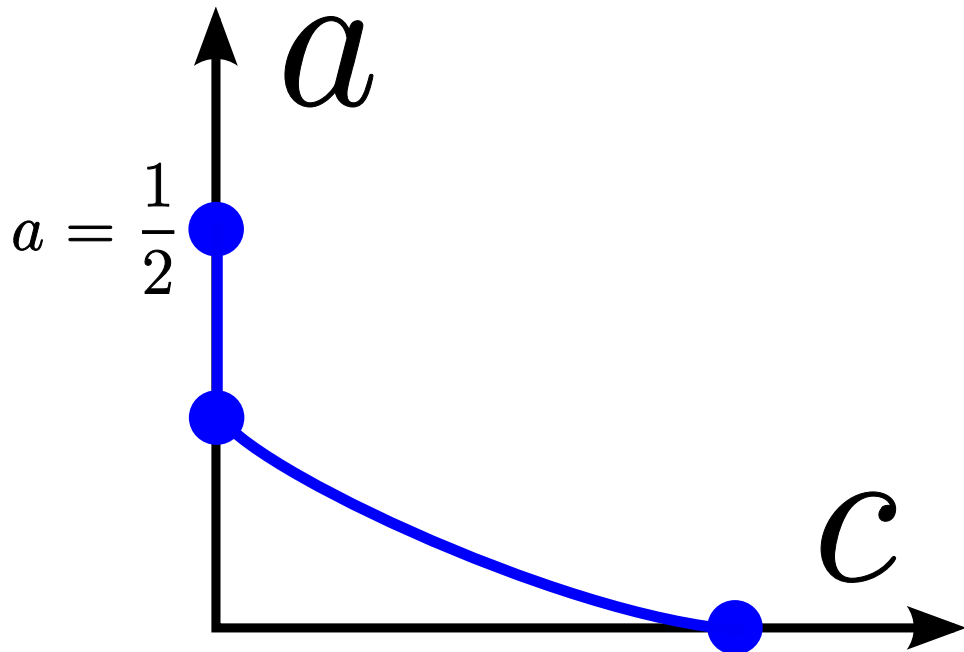
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For  $\epsilon = 0$  and  $w = 0$ , we obtain the discrete Nagumo LDE

$$\dot{U}_j(t) = \alpha[U_{j+1}(t) + U_{j-1}(t) - 2U_j(t)] + g(U_j(t); a),$$

with travelling pulse MFDE

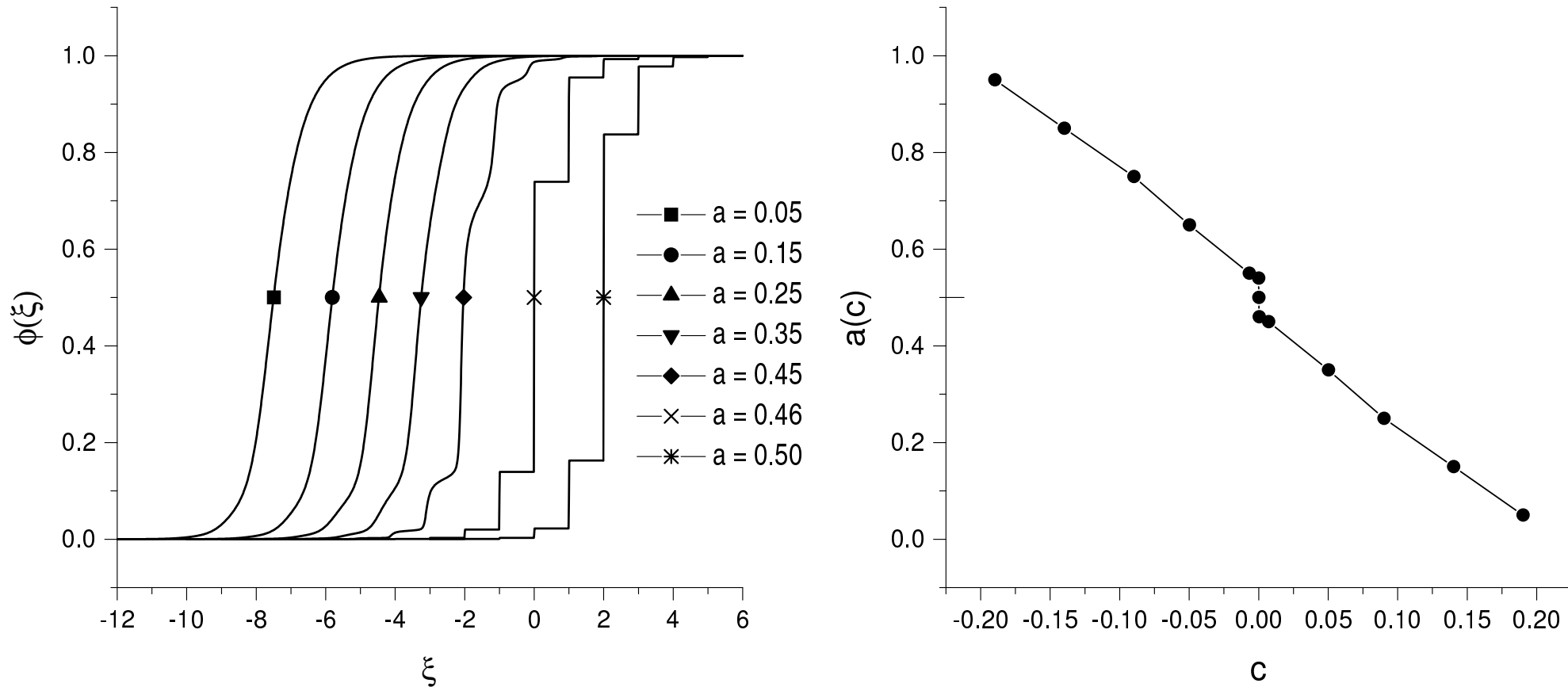
$$cu'(\xi) = \alpha[u(\xi + 1) + u(\xi - 1) - 2u(\xi)] + g(u(\xi); a).$$



- This problem becomes singular in the  $c \rightarrow 0$  limit, in contrast with the Nagumo PDE case.
- Keener (1987) + Mallet-Paret (1999): pick  $\alpha > 0$  small;  $c = 0$  for  $a$  in **nonempty** interval  $[a_*, \frac{1}{2}]$ .

# Discrete FitzHugh-Nagumo LDE - Propagation failure

Travelling waves for the discrete Nagumo equation [ $\alpha = 0.1$ ] connecting  $0 \rightarrow 1$ .



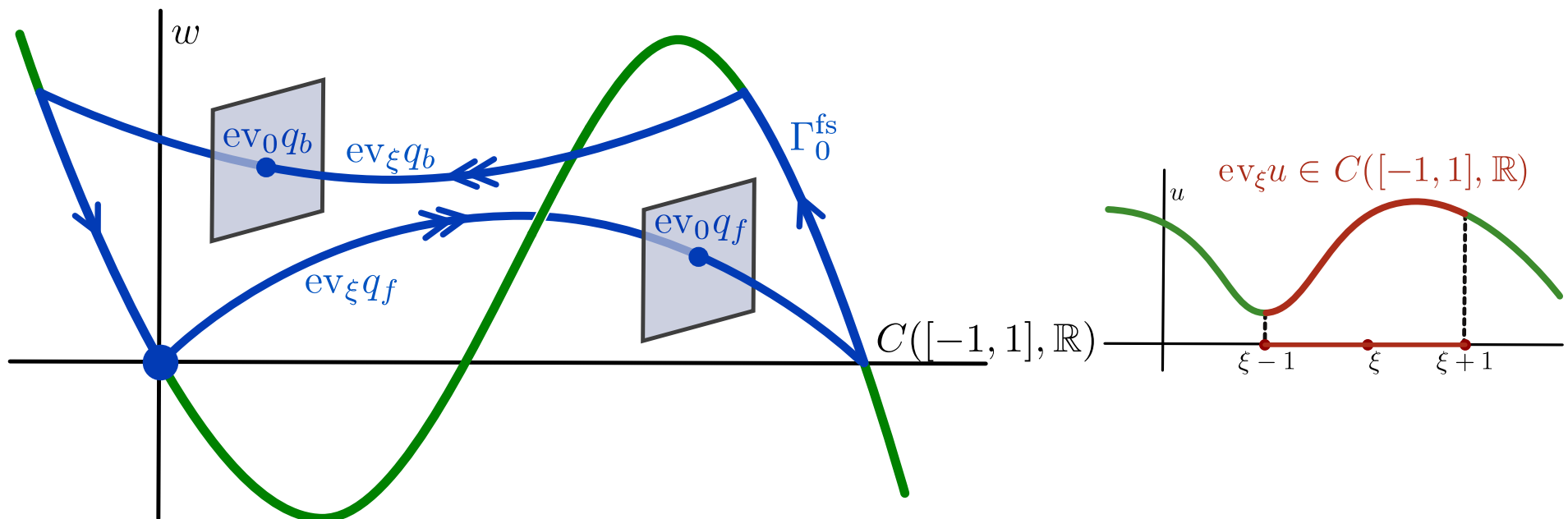
- Note that  $c = 0$  for all  $a \in [0.46, 0.54]$ . Propagation failure!
- Observe the discontinuities in the wave profiles in this region.
- Gaps cause "energy barrier" that signal must overcome.

# Discrete FitzHugh-Nagumo LDE - Fast Pulses

- Focus on fast-solutions to discrete FHN bifurcating from  $\Gamma_0^{\text{fs}}$ ,

$$\begin{aligned}
 cu'(\xi) &= u(\xi + 1) + u(\xi - 1) - 2u(\xi) + g(u(\xi); a) - w(\xi), \\
 cw'(\xi) &= \epsilon[u(\xi) - \gamma w(\xi)].
 \end{aligned}$$

- Unclear how to treat slow-solutions in propagation failure regime.



# Mixed Type Functional Differential Equations (MFDEs)

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Let us first study the Nagumo travelling wave MFDE

$$u'(\xi) = u(\xi + 1) + u(\xi - 1) - 2u(\xi) + g(u(\xi); a).$$

- Theory for MFDEs started developing  $\sim$  10 years ago.
- MFDEs generalize delay equations, e.g.

$$u'(\xi) = u(\xi - 1) + g(u(\xi)),$$

which have been used for more than half a century.

- Time lags naturally in many modelling applications.
- Delay equations: functional-analytic setup developed in past three decades.

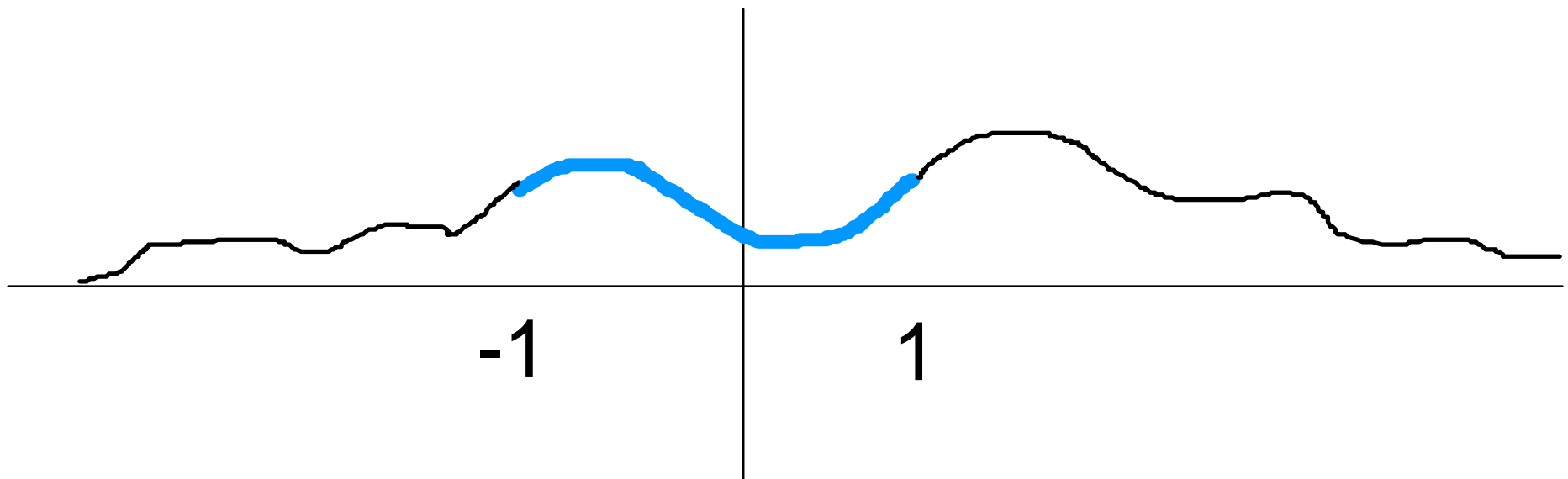
# MFDEs

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Recall our prototype MFDE

$$u'(\xi) = u(\xi + 1) + u(\xi - 1) - 2u(\xi) + g(u(\xi); a).$$

Such equations differ from ODEs and delay equations in a fundamental way.



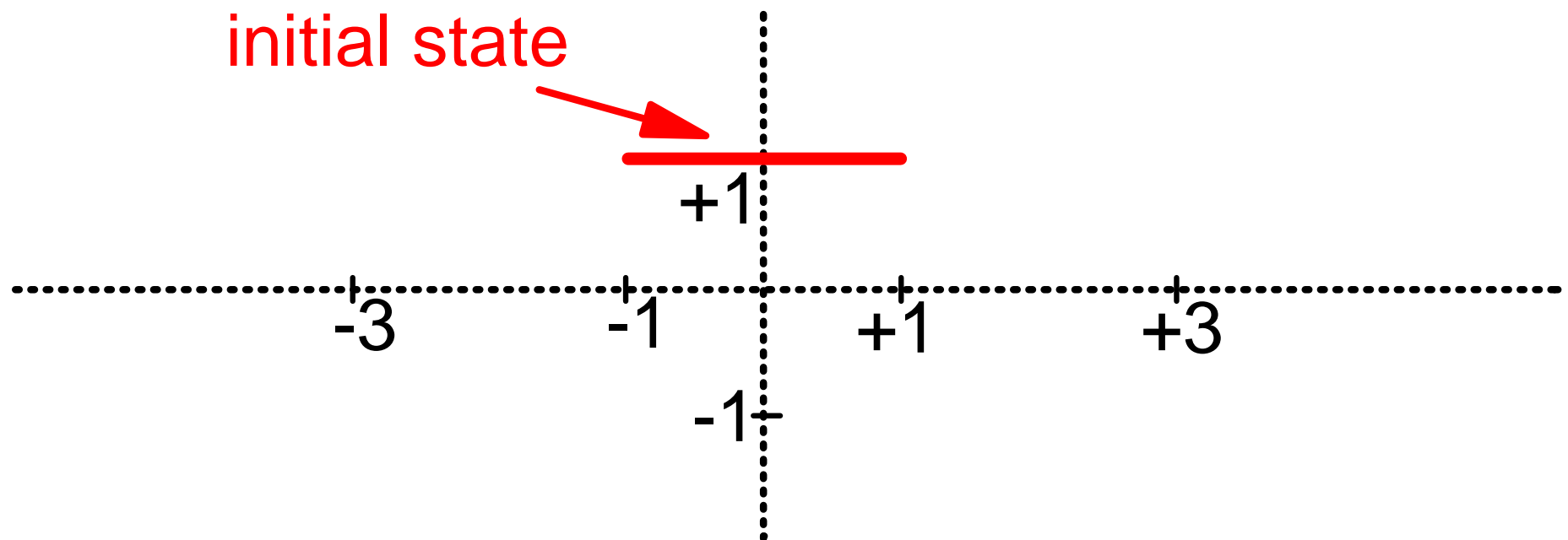
Problem I: Statespace is infinite dimensional: need to specify an initial **function** on  $[-1, 1]$ .

## Problem II: Ill-posedness

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Consider the homogeneous MFDE

$$v'(\xi) = v(\xi - 1) + v(\xi + 1).$$



(Example due to Rustichini )

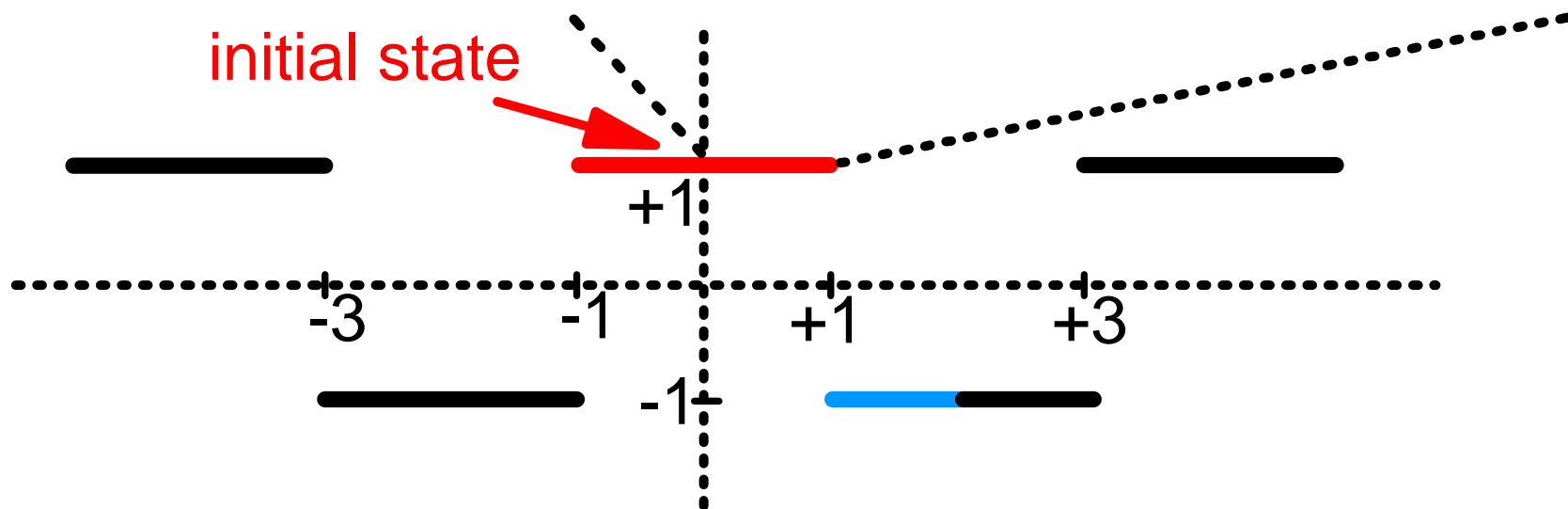
## Problem II: Ill-posedness

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Consider the homogeneous MFDE

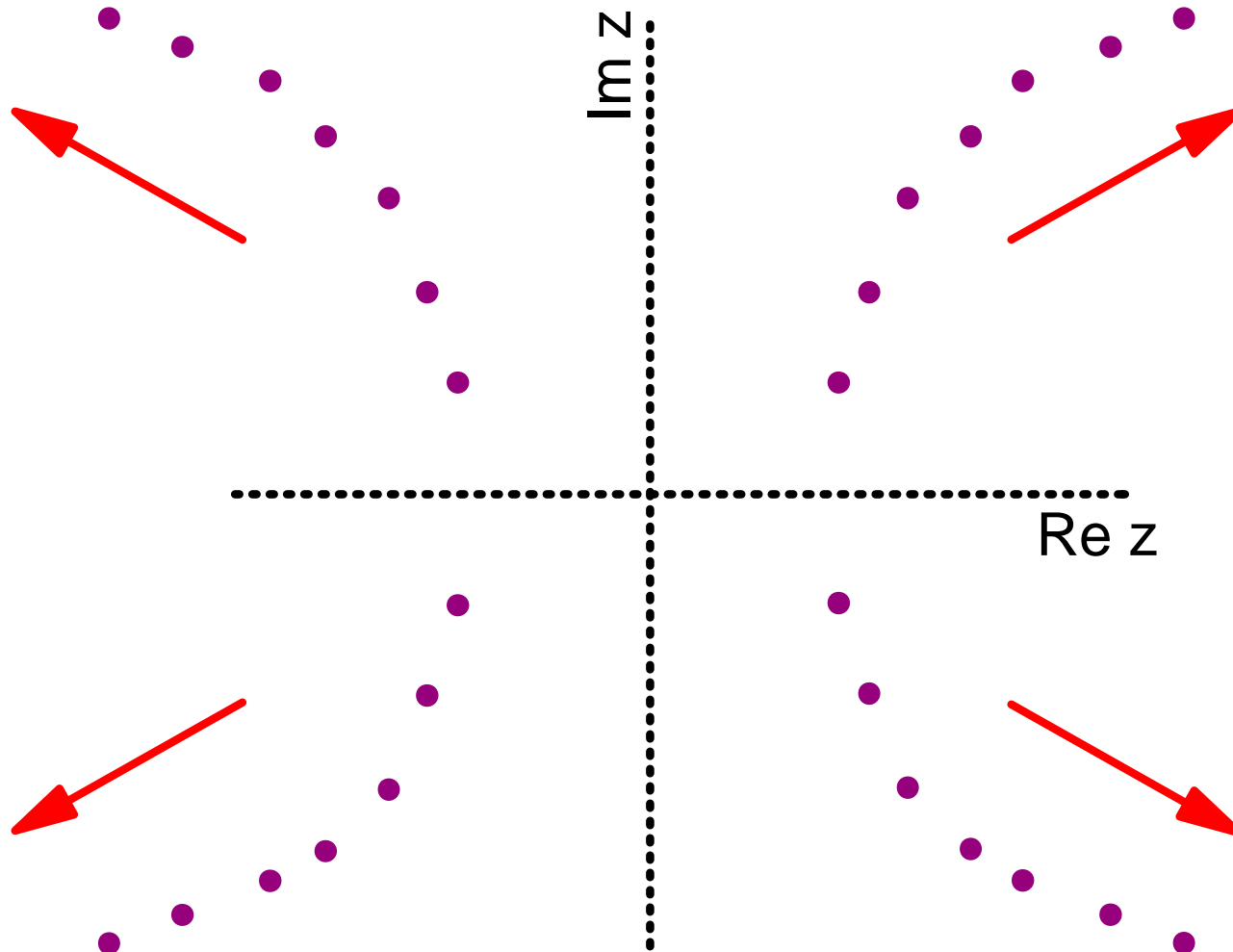
$$v'(\xi) = v(\xi - 1) + v(\xi + 1).$$

$$v'(\xi) = 0, v(\xi - 1) = 1 \Rightarrow v(\xi + 1) = -1$$



- Continuity lost  $\implies$  ill-defined as an initial value problem.

## Ill-posedness: What is going on?



Substitution of  $e^{z\xi}$  into

$$v'(\xi) = v(\xi - 1) + v(\xi + 1),$$

yields the characteristic equation

$$\Delta(z) := z - e^{-z} - e^z = 0.$$

- The problem is infinite dimensional (as for delay equations).
- There is no exponential bound possible for solutions, at both  $\pm\infty$  (unlike delay equations)!

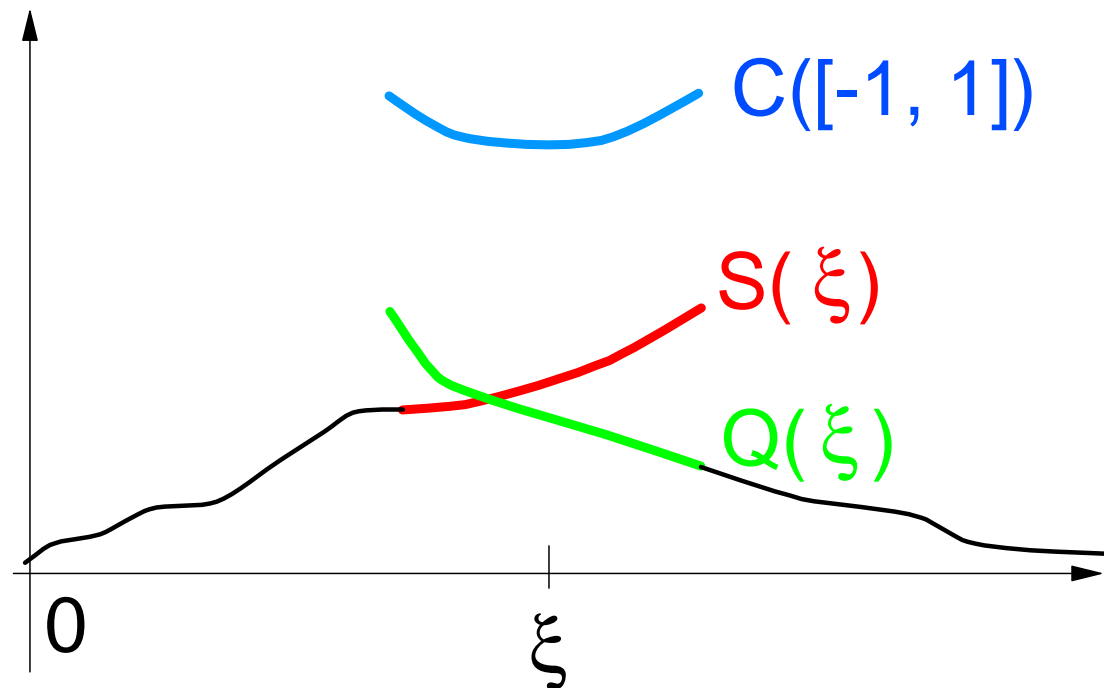


# Exponential Dichotomies

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Exponential dichotomies are the method of choice for ill-posed problems. Consider the linearization around some function  $q$ ,

$$v'(\xi) = v(\xi + 1) + v(\xi - 1) - 2v(\xi) + g'(q(\xi))v(\xi).$$



H. + Verduyn Lunel (2008): For  $\xi \geq 0$ , we have  $C([-1, 1], \mathbb{R}) = Q(\xi) \oplus S(\xi)$ .

Exponential decay for forward-solutions and backward-solutions.

# Exponential Dichotomies - Inhomogeneous system

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Consider the inhomogeneous system

$$v'(\xi) = v(\xi + 1) + v(\xi - 1) - 2v(\xi) + g'(q(\xi))v(\xi) + f(\xi).$$

Recall the splitting  $C([-1, 1], \mathbb{R}) = Q(\xi) \oplus S(\xi)$ .

Usually, exponential dichotomies can be used to construct a variation-of-constants formula

$$v \sim \int_0^\xi T(\xi, \xi') \Pi_{Q(\xi')} f(\xi') d\xi' + \int_\infty^\xi T(\xi, \xi') \Pi_{S(\xi')} f(\xi') d\xi',$$

where  $T$  should be seen as an evolution operator.

However, since  $f : \mathbb{R} \rightarrow \mathbb{C}^n$  does not map into the state space  $C([-1, 1])$  complications arise.

- Delay equations: sun-star calculus based upon semigroup properties
- Mixed type equations: unclear how to mimic this construction for  $C([-1, 1])$ . Possibilities on space  $L^2([-1, 1])$ , but technical complications.

# Inhomogeneous systems

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Mallet-Paret (1998) considered operator  $\Lambda : BC^1(\mathbb{R}, \mathbb{R}) \rightarrow BC(\mathbb{R}, \mathbb{R})$ ,

$$[\Lambda v](\xi) = v'(\xi) - [v(\xi + 1) + v(\xi - 1) - 2v(\xi)] - g'(q(\xi))v(\xi).$$

- $\Lambda$  is a Fredholm operator:
  - Kernel is finite dimensional
  - Range is closed and has finite dimensional codimension
- Range  $\mathcal{R}(\Lambda)$  can be explicitly characterized:

$$\mathcal{R}(\Lambda) = \left\{ f \in BC(\mathbb{R}, \mathbb{R}) \mid \int_{-\infty}^{\infty} d(\xi)^* f(\xi) d\xi = 0 \text{ for all } d \in \mathcal{K}(\Lambda^*) \right\},$$

with adjoint given by

$$[\Lambda^* v](\xi) = v'(\xi) + [v(\xi + 1) + v(\xi - 1) - 2v(\xi)] + g'(q(\xi))v(\xi).$$

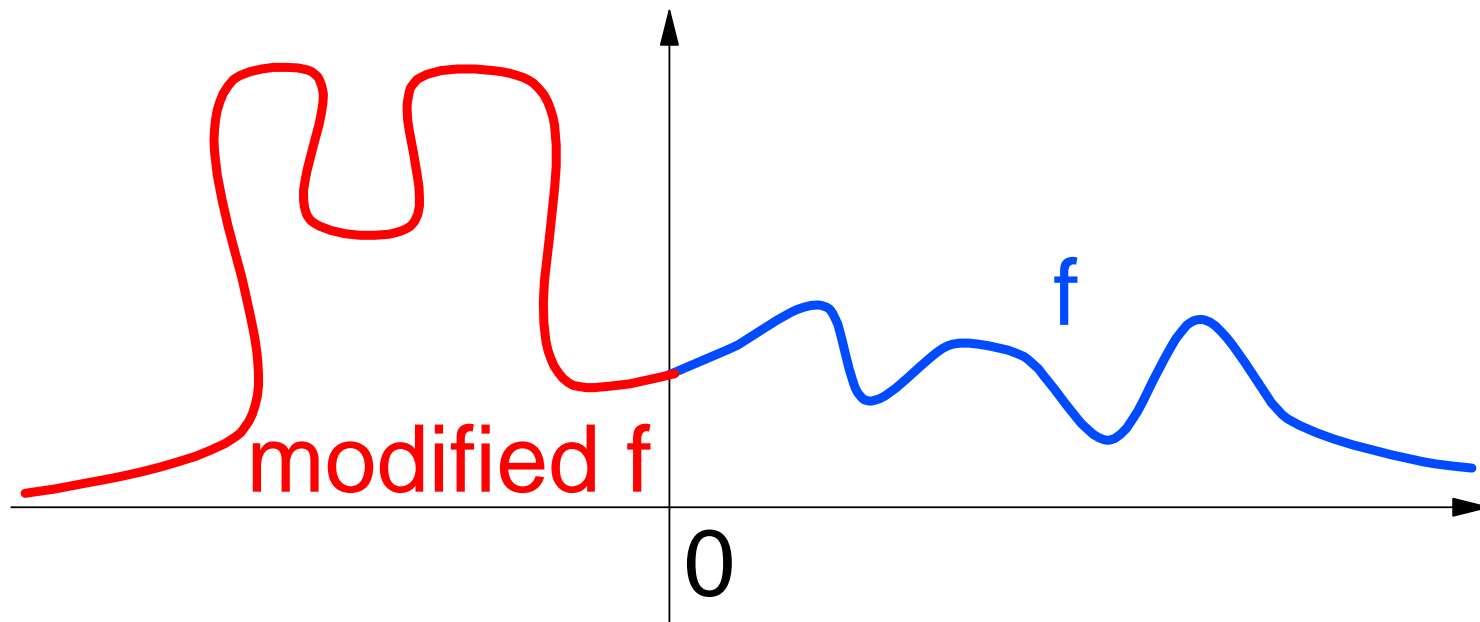
## Inhomogeneous systems - II

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In general  $\mathcal{R}(\Lambda) \neq BC(\mathbb{R}, \mathbb{R})$ , with again

$$[\Lambda v](\xi) = v'(\xi) - [v(\xi + 1) + v(\xi - 1) - 2v(\xi)] - g'(q(\xi))v(\xi).$$

**Important property** Any solution to  $\Lambda^*v = 0$  with  $ev_\xi v = 0$  for some  $\xi$ , has  $v = 0$  everywhere.



For any  $f$ , solve  $\Lambda v = f$  on  $[0, \infty)$ , by modifying  $f$  on  $\mathbb{R}_-$ .

# The program

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Recall the singularly perturbed MFDE

$$\begin{aligned}cu'(\xi) &= u(\xi + 1) + u(\xi - 1) - 2u(\xi) + g(u(\xi); a) - w(\xi), \\cw'(\xi) &= \epsilon[u(\xi) - \gamma w(\xi)].\end{aligned}$$

Main goal: lift geometric singular perturbation theory to MFDEs.

- Persistence of slow manifold  $\mathcal{M}_R$  for  $\epsilon > 0$  relies on Fenichel's first thm.
- Almost every proof relies on geometric Hadamard-graph transform.
- Exchange Lemma: Fenichel coordinates unavailable in infinite dimensions.
- Unstable / stable manifolds will be infinite dimensional. How to track intersections?

Main ingredients:

- Isolate suitable finite dimensional subspaces of  $C([-1, 1], \mathbb{R})$ .
- Provide firm analytical underpinning for geometrical constructions.

# The program

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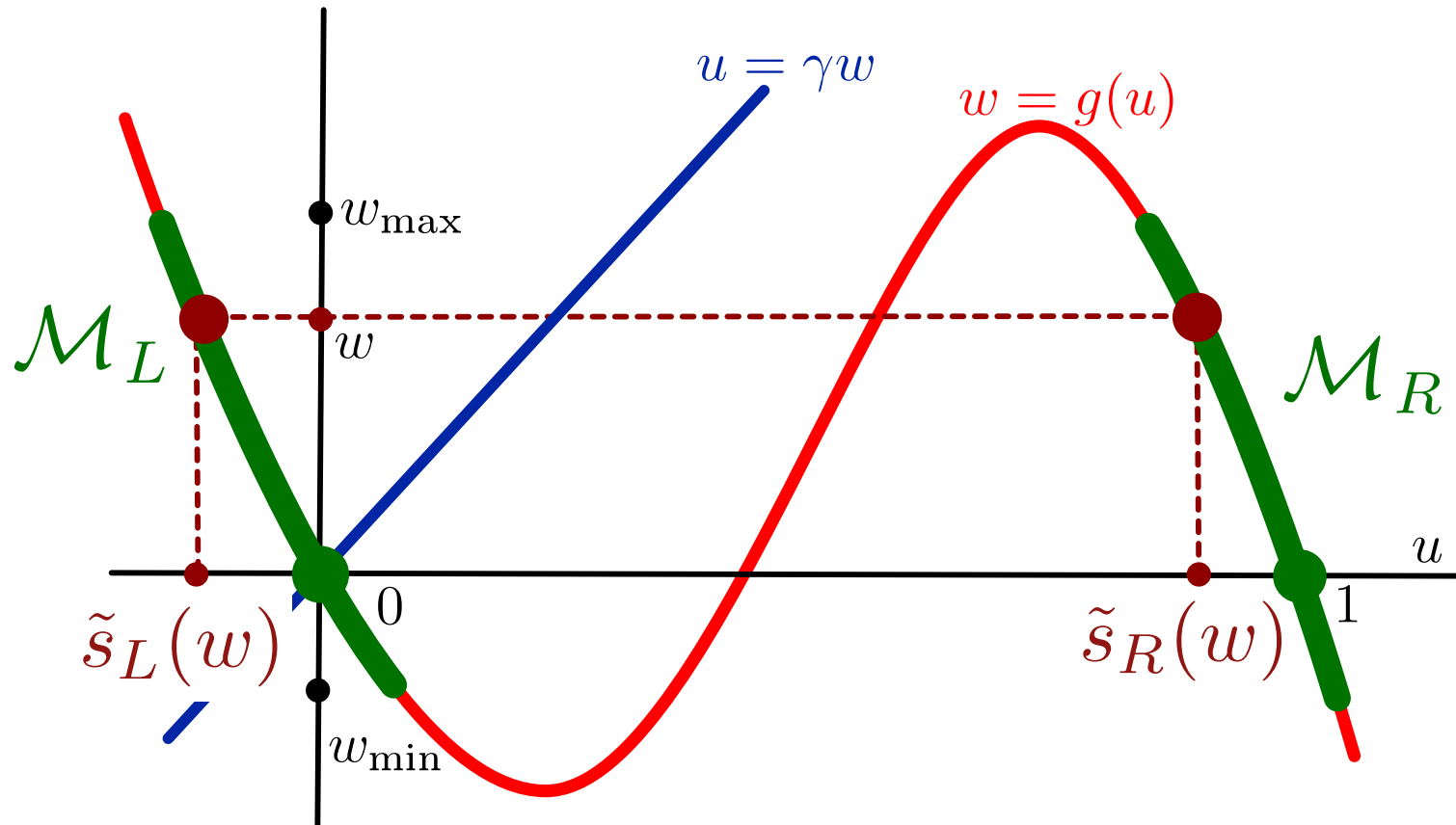
Recall the singularly perturbed MFDE

$$\begin{aligned}cu'(\xi) &= u(\xi + 1) + u(\xi - 1) - 2u(\xi) + g(u(\xi); a) - w(\xi), \\cw'(\xi) &= \epsilon[u(\xi) - \gamma w(\xi)].\end{aligned}$$

- Step 1: Persistence of  $\mathcal{M}_L$  and  $\mathcal{M}_R$  for  $\epsilon > 0$ .
- Step 2: How do  $q_f$  and  $q_b$  break as  $\epsilon \approx 0$  and  $c \approx c_*$ ?
- Step 3: Connect broken front and back solutions as they pass near  $\mathcal{M}_R(c, \epsilon)$ .
- Step 4: Set up and solve two-dimensional nonlinear bifurcation equations to repair front and backs and find  $c(\epsilon)$ .

# The program: Step 1 - Persistence of Slow Manifolds

Introduce function  $\tilde{s}_R$  such that  $g(\tilde{s}_R(w)) = w$ .



We have  $\mathcal{M}_R = \{(\tilde{s}_R(w), w)\}$  for  $w \in [w_{\min}, w_{\max}]$ .

**Goal:** find functions  $s_R(w, c, \epsilon)$  so that the manifold  $\mathcal{M}_R(c, \epsilon) = \{(s_R(w, c, \epsilon), w)\}$  is invariant.

## The program: Step 1 - Persistence of Slow Manifolds

---

Idea based upon Sakamoto (1990): find solution  $(u, w)$  with  $w(0) = w_0$  and

$$u(\xi) = \tilde{s}_R(w(\xi)) + v(\xi),$$

with **small**  $v$  and write  $s_R(w_0, c, \epsilon) = u(0)$ . Need to solve

$$\begin{aligned} cv'(\xi) &= L\left(\tilde{s}_R(w(\xi))\right) \text{ev}_\xi v + \mathcal{R}_{\text{nl}}(v, w, c, \epsilon)(\xi), \\ cw'(\xi) &= \epsilon[\tilde{s}_R(w(\xi)) + v(\xi) - \gamma w(\xi)] \end{aligned}$$

with nonlinear  $\mathcal{R}_{\text{nl}}$  and linear operator  $L(u) : C([-1, 1], \mathbb{R}) \rightarrow \mathbb{R}$  given by

$$L(u) \text{ev}_\xi v = v(\xi + 1) + v(\xi - 1) - 2v(\xi) + g'(\mathbf{u})v(\xi).$$

Note that  $w' = O(\epsilon)$ , so linear part **varies slowly**.

- Equation for  $w$  with  $w(0) = w_0$  can be solved  $\longrightarrow W(v, c, \epsilon, w_0)$ .
- Suppose that operator  $\mathcal{K}(w, c)$  solves linear  $v$ -problem  $\longrightarrow$  fixed point problem

$$v = \mathcal{K}(W(v, c, \epsilon, w_0), c) \mathcal{R}_{\text{nl}}(v, W(v, c, \epsilon, w_0), c, \epsilon)$$



## The program: Step 1 - Persistence of Slow Manifolds

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Key ingredient is the construction of solution operator  $\mathcal{K}(w, c)$  for linear systems

$$cv'(\xi) = L\left(\tilde{s}_R(w(\xi))\right)ev_\xi v + f(\xi).$$

Use the fact that for each fixed  $w_0 \in [w_{\min}, w_{\max}]$ , the system

$$cv'(\xi) = L\left(\tilde{s}_R(w_0)\right)ev_\xi v + f(\xi),$$

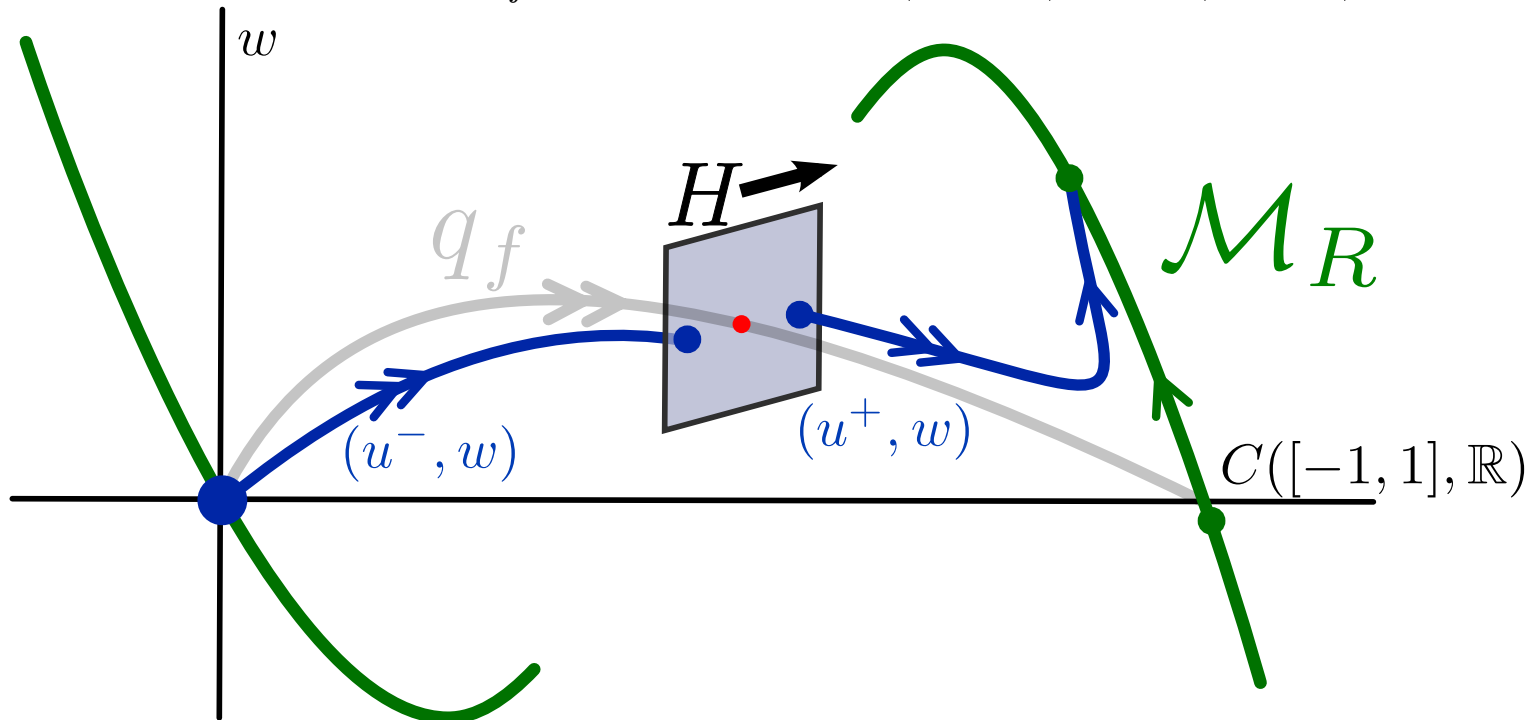
can be solved;  $v = \mathcal{K}_{\text{fx}}(w_0, c)f$  [Mallet-Paret 1998]. Can now define approximate solution operator

$$[\mathcal{K}_{\text{apx}}(w, c)f](\xi) = \int_{\xi - \frac{1}{2}}^{\xi + \frac{1}{2}} [\mathcal{K}_{\text{fx}}(w(\zeta), c)f](\xi) d\zeta.$$

If  $w'$  is small, the error is small and can be corrected;  $\mathcal{K}_{\text{apx}} \rightarrow \mathcal{K}$ .

## The program: Step 2 - Breaking the front

Varying  $\epsilon$  and  $c$  breaks orbit  $q_f$  into two parts  $(u^-, w)$  and  $(u^+, w)$ .



Hyperplane  $H$  transverse to orbit  $q_f$  at  $\xi = 0$ , i.e.,

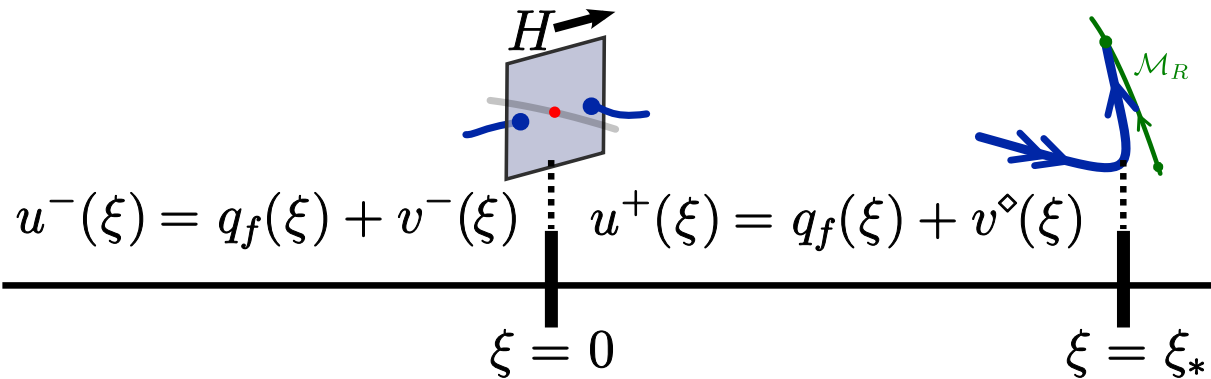
$$C([-1, 1], \mathbb{R}) = \text{ev}_0 q_f + H \oplus \text{span}\{\text{ev}_0 q'_f\}.$$

- Perturbation  $u^+$  from  $q_f$  is large as  $\xi \rightarrow \infty$ .
- Hyperplane  $H$  is infinite dimensional

## The program: Step 2 - Breaking the front

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To control size of perturbation, split up real line into three separate parts.

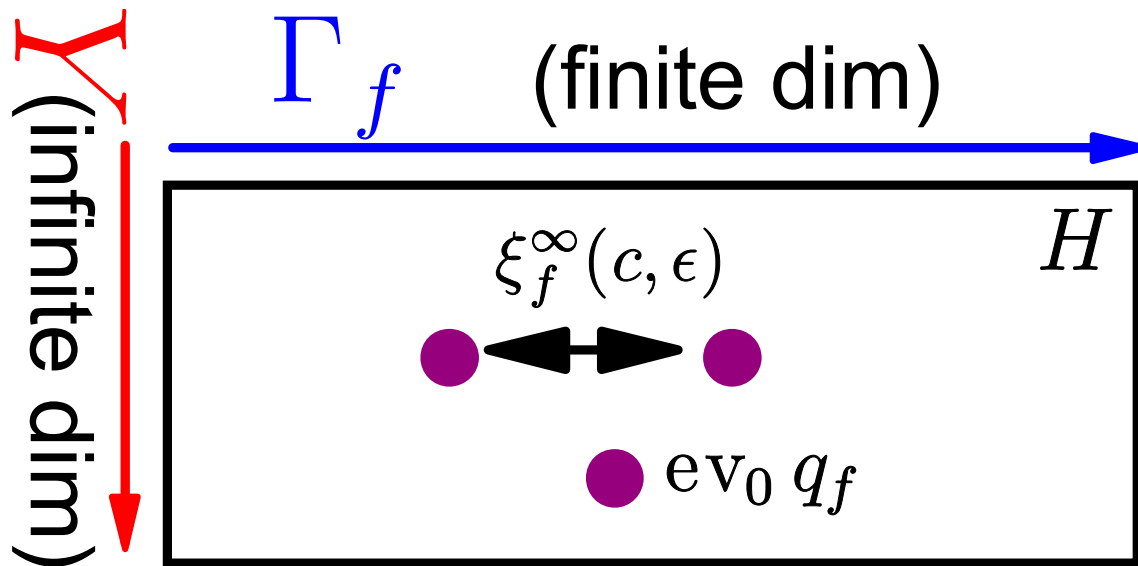


- The functions  $v^-$ ,  $v^\diamond$  and  $w|_{(-\infty, \xi_*]}$  are small.

## The program: Step 2 - Breaking the front

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We need to study the remaining gap in  $H$ . Call this gap  $\xi_f^\infty(c, \epsilon)$ .



**Main Goal:** Reduce problem to finite dimensions.

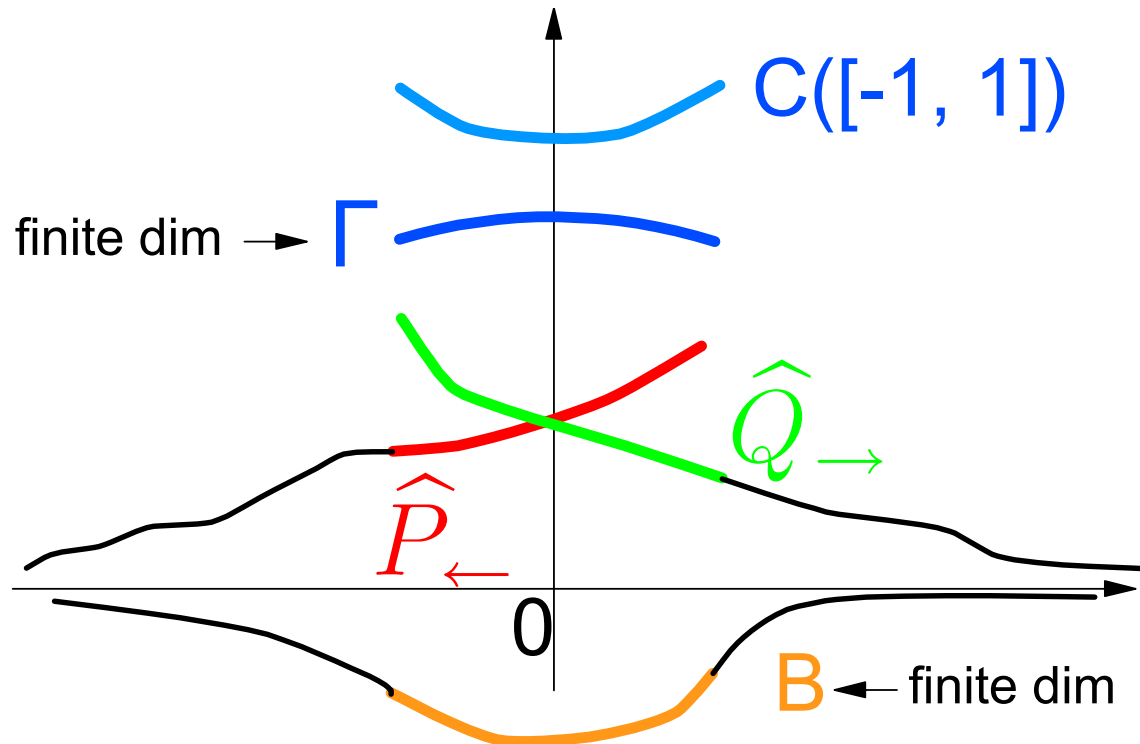
To do this, we will need to split  $H = ev_0 q_f + Y \oplus \Gamma_f$ , with  $\Gamma_f$  **finite** dimensional.

In addition, need to make sure that the "gaps"  $\xi_f^\infty(c, \epsilon)$  are all in  $\Gamma$ .

## The program: Step 2 - Breaking the front

Construction based upon exponential dichotomies on  $\mathbb{R}$  for

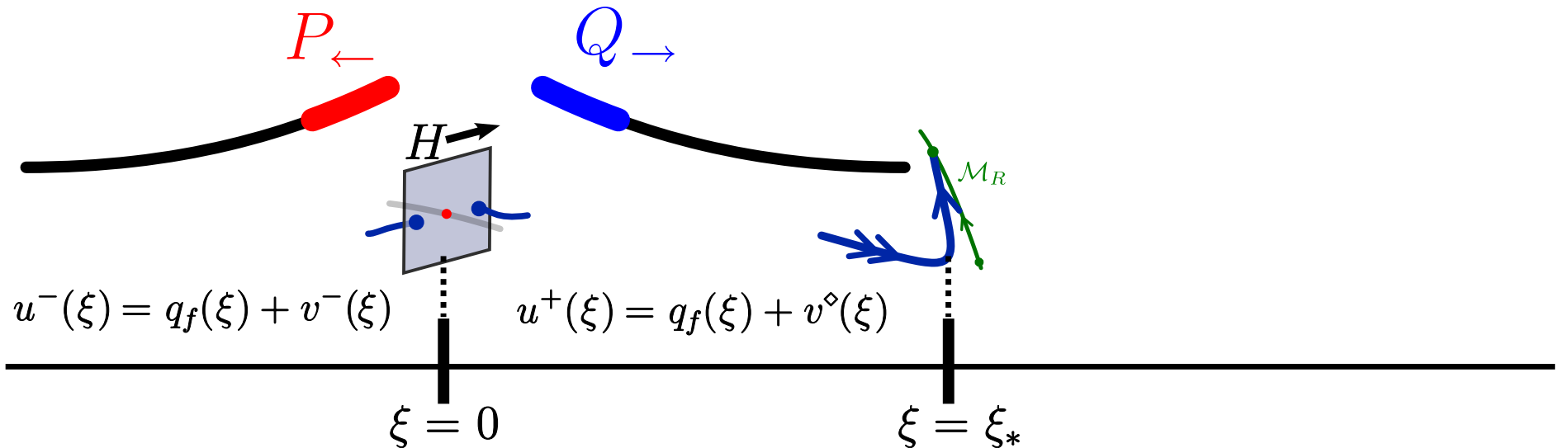
$$v'(\xi) = v(\xi + 1) + v(\xi - 1) - 2v(\xi) + g'(q_f(\xi))v(\xi).$$



Mallet-Paret + Verduyn Lunel (2001):  $C([-1, 1], \mathbb{R}) = \hat{P}_{\leftarrow} \oplus \hat{Q}_{\rightarrow} \oplus B \oplus \Gamma$ .

We have  $ev_0 q' \in B$ . Can use  $Y = \hat{P}_{\leftarrow} \oplus \hat{Q}_{\rightarrow}$ . The space  $\Gamma$  can be explicitly characterized using special integral inner product (Hale inn. pr.).

## The program: Step 2 - Breaking the front



Can use remaining freedom to ensure that gap is in  $\Gamma$ , since

$$C([-1, 1], \mathbb{R}) = \text{ev}_0 q_f + \hat{P}_\leftarrow \oplus \hat{Q}_\rightarrow \oplus \{\text{ev}_0 q'_f\} \oplus \Gamma$$

At  $c = 0$  and  $\epsilon = 0$ , we have Melnikov identities such as

$$D_c \langle \text{ev}_0 d, \xi_f^\infty \rangle_{\text{Hale}} = - \int_{-\infty}^{\xi_*} d(\xi') q'_f(\xi) d\xi' + O(e^{-\eta_* \xi_*}),$$

for  $d$  that solves adjoint  $-cd'(\xi) = \alpha[d(\xi + 1) + d(\xi - 1) - 2d(\xi)] + g'(q_f(\xi))v(\xi)$ .



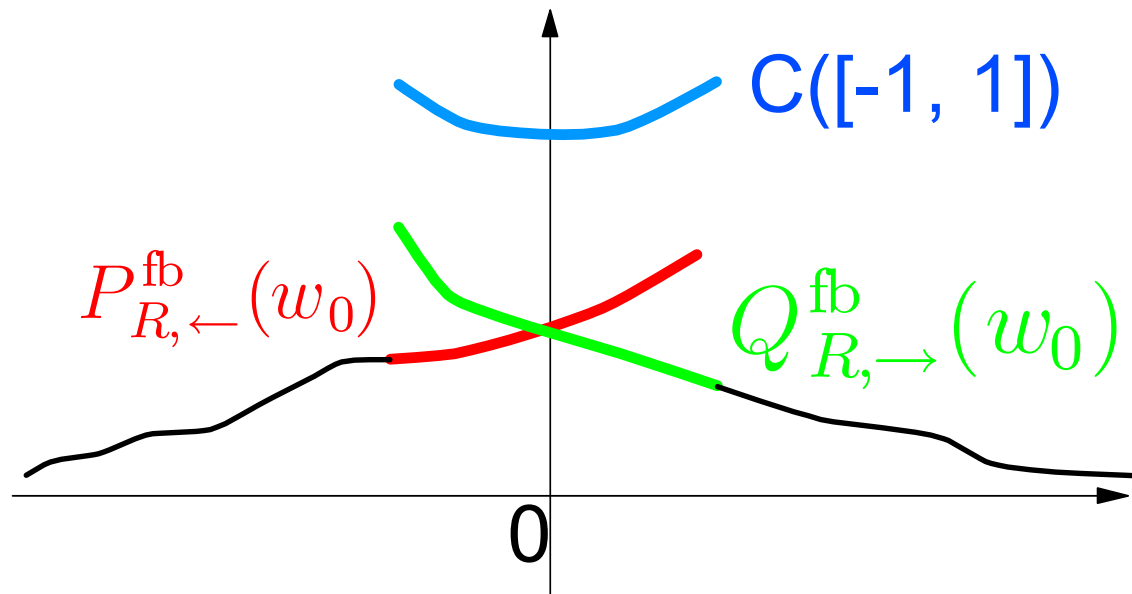
## The program: Step 2 - Breaking the front

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Must understand linearization near slow manifold  $\mathcal{M}_R(c, \epsilon)$ .

First fix  $w_0 \in [w_{\min}, w_{\max}]$  and consider **constant coefficient** linearization

$$v'(\xi) = v(\xi + 1) + v(\xi - 1) - 2v(\xi) + g'(\tilde{s}_R(w_0))v(\xi)$$



Mallet-Paret + Verduyn Lunel (2001):  $C([-1, 1], \mathbb{R}) = P_{R, \leftarrow}^{\text{fb}}(w_0) \oplus Q_{R, \rightarrow}^{\text{fb}}(w_0)$ .



## The program: Step 2 - Breaking the front

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Now consider  $w \in C^1(\mathbb{R}, [w_{\min}, w_{\max}])$  that has very small  $\|w'\|_\infty$  and  $w(0) = w_0$ .

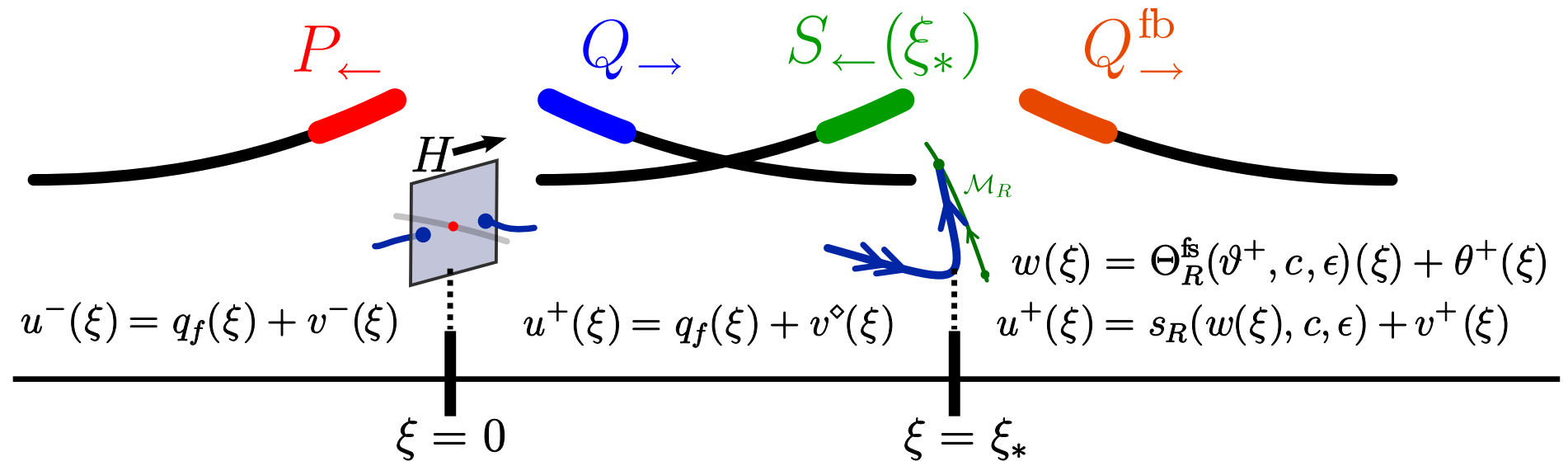
Consider linearization

$$v'(\xi) = v(\xi + 1) + v(\xi - 1) - 2v(\xi) + g'(\tilde{s}_R(w(\xi)))v(\xi). \quad (1)$$

Main idea:

- For any  $\phi \in Q_{R,\rightarrow}^{\text{fb}}(w_0)$ , there exists  $v \in C([-1, \infty), \mathbb{R})$  that solves (1) with  $\Pi_{Q_{R,\rightarrow}^{\text{fb}}(w_0)} \text{ev}_0 v = \phi$ .
- Any bounded solution to (1) can be written in this form.

## The program: Step 2 - Breaking the front



Gap at  $\mathcal{M}_R$  can be completely closed, since

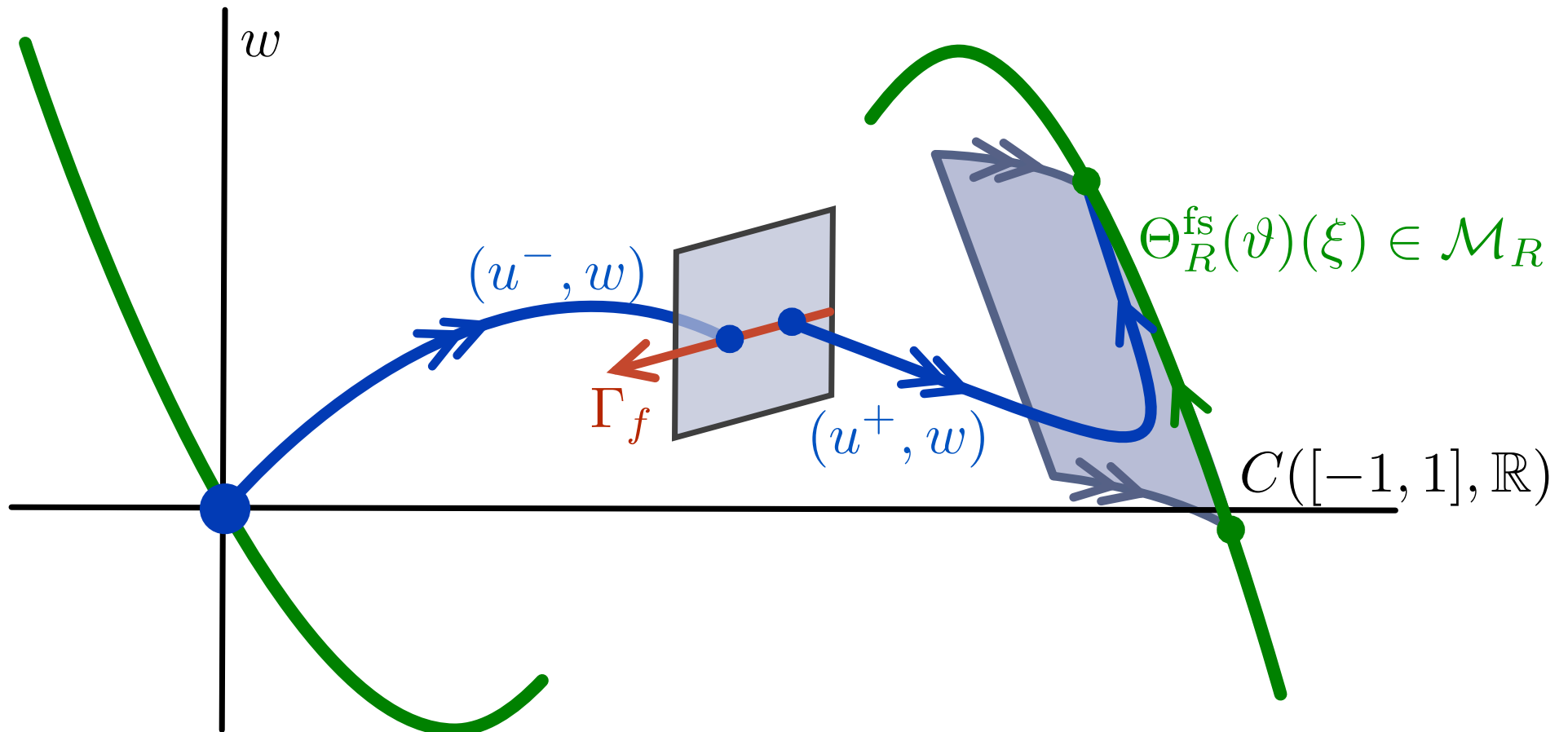
$$S_{\leftarrow}(\xi_*) \approx P_{R,\leftarrow}^{fb}(0)$$

and

$$C([-1, 1], \mathbb{R}) = P_{R,\leftarrow}^{fb}(0) \oplus Q_{R,\rightarrow}^{fb}(0).$$

## The program: Step 2 - Breaking the front

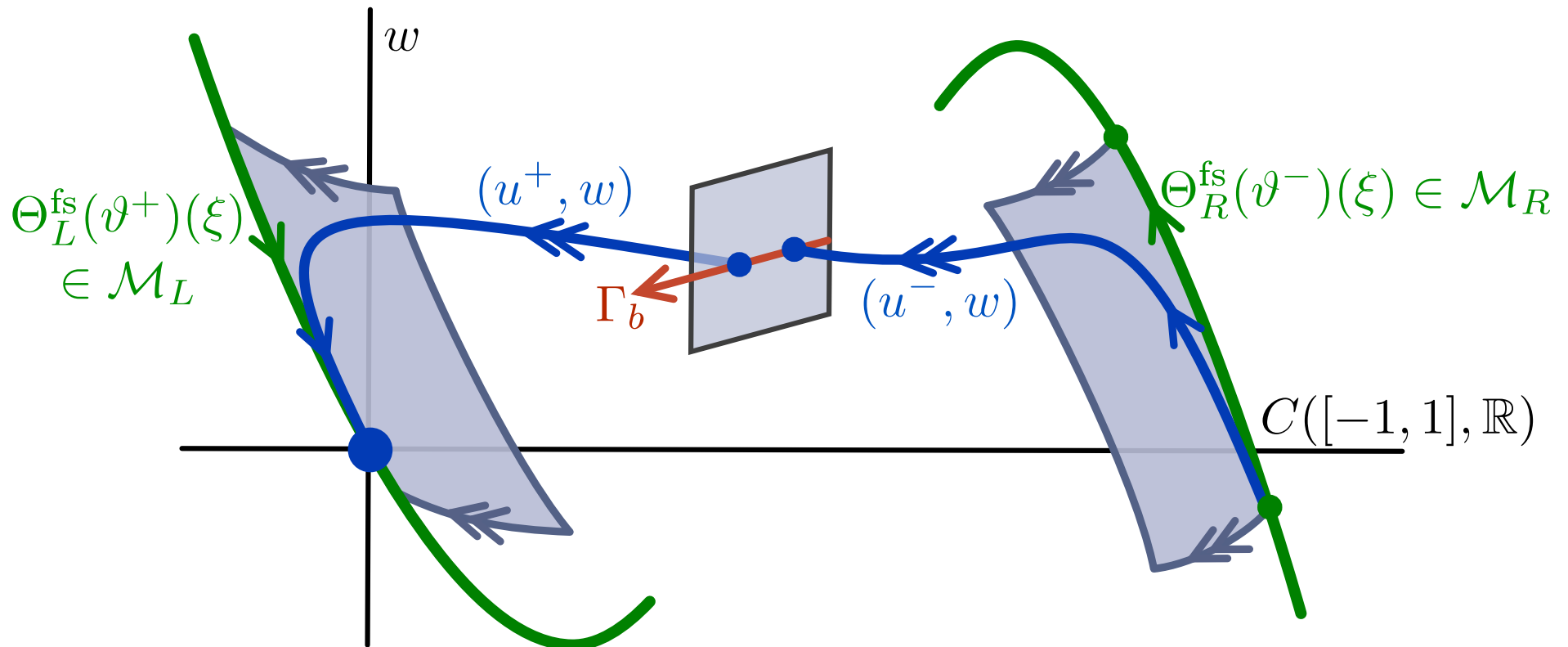
In summary, we have constructed **quasi-front** solutions to the travelling wave equation for  $\epsilon \approx 0$  and  $c \approx c_*$ .



## The program: Step 2 - Breaking the back

Similarly, can construct **quasi-back** solutions to the travelling wave equation for  $\epsilon \approx 0$ ,  $c \approx c_*$  and **extra** degree of freedom  $w_0 \approx w_*$ .

This extra d.o.f. used to specify  $w(0) = w_0$  (lift quasi-back up and down).



## The program: Step 3 - Exchange Lemma

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The quasi-fronts and quasi-backs need to be tied together near  $\mathcal{M}_R(c, \epsilon)$ .

Primary parameter: time  $T$  that solution spends near  $\mathcal{M}_R(c, \epsilon)$ .

Note that  $\epsilon = 0$  is not a useful parameter, since quasi-fronts and quasi-backs do not connect when  $\epsilon = 0$ .

Write  $\Theta_R^{\text{sl}}(\vartheta, c, \epsilon)$  for unique solution of ODE

$$\Theta'(\zeta) = [s_R(\Theta(\zeta), c, \epsilon) - \gamma\Theta(\zeta)], \quad \Theta(0) = \vartheta,$$

which describes flow along  $\mathcal{M}_R(c, \epsilon)$  in terms of **slow** time scale.

Slow time  $T_*^{\text{sl}}$  uniquely defined by

$$\Theta_R^{\text{sl}}(0, c_*, 0)(T_*^{\text{sl}}) = w_*$$

We will need  $\epsilon T \approx T_*^{\text{sl}}$ ; introduce new variable  $T^{\text{sl}} = \epsilon T$ .

Independent parameters are now  $(c, T^{\text{sl}}, T)$  taken near  $(c_*, T_*^{\text{sl}}, \infty)$ .

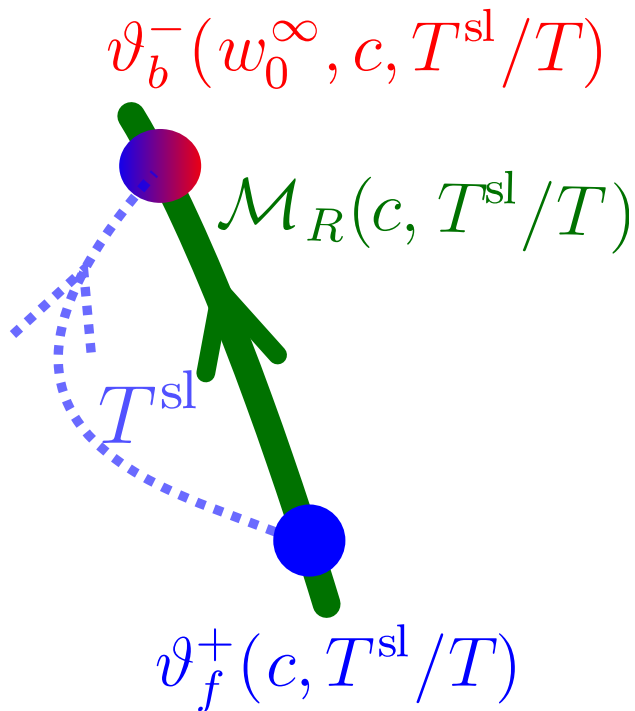
## The program: Step 3 - Exchange Lemma

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Recall the fibre  $\vartheta_f^+(c, \epsilon)$  that was selected by the quasifront.

Recall also the fibre  $\vartheta_b^-(w_0, c, \epsilon)$  selected by the quasiback.

Want to make sure fibres match.



• Define  $w_0^\infty(c, T^{\text{sl}}, T)$  by the following identity:

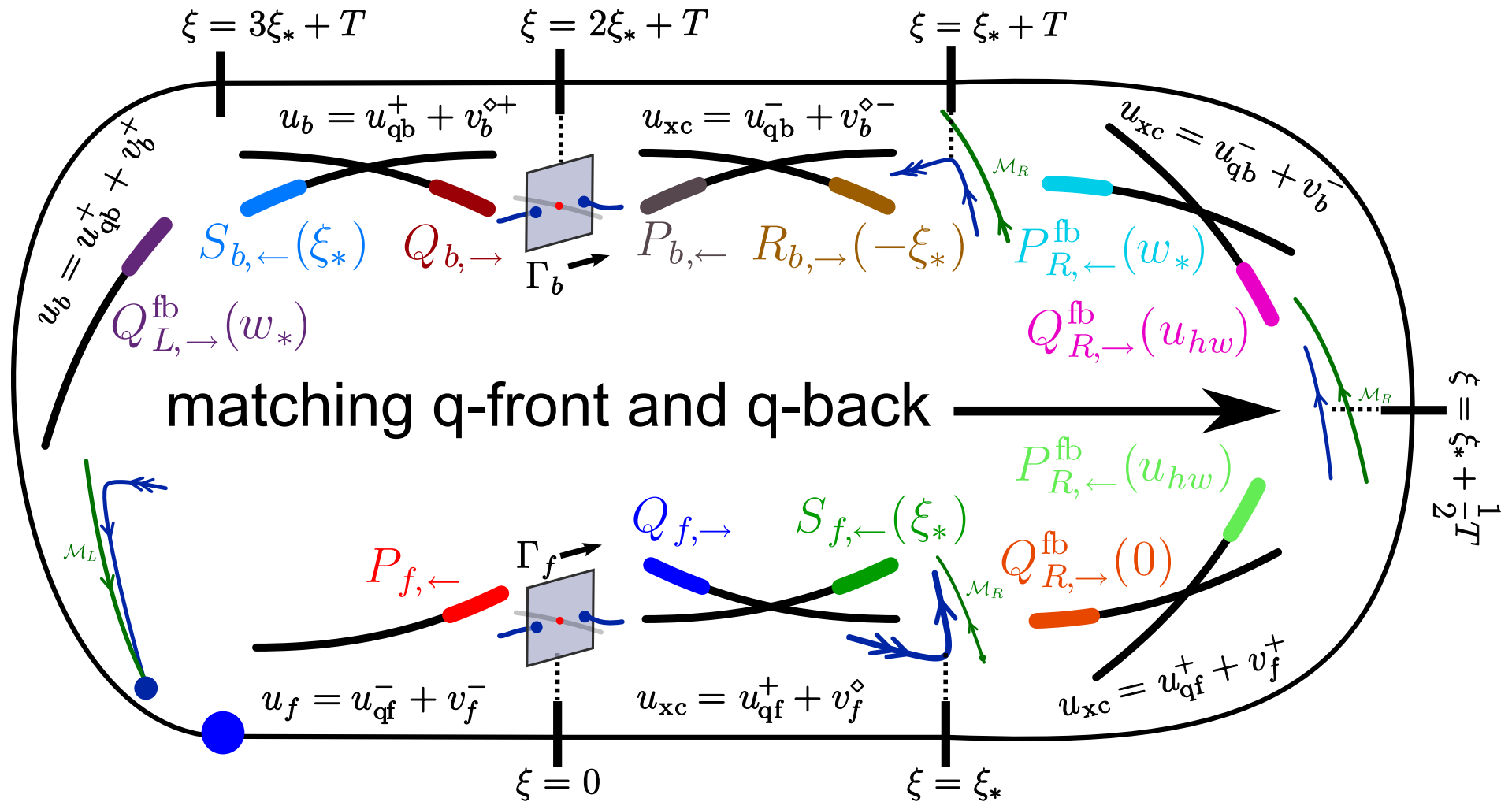
$$\vartheta_b^-(w_0^\infty, c, T^{\text{sl}}/T) = \Theta_R^{\text{sl}}(\vartheta_f^+(c, T^{\text{sl}}/T), c, T^{\text{sl}}/T)(T^{\text{sl}})$$

$$\text{for } (c, T^{\text{sl}}, T) \approx (c_*, T_*^{\text{sl}}, \infty).$$

Consequence: at "half-way" point, quasi-front and quasi-back miss each other by  $O(e^{-\frac{1}{2}\eta_* T})!$

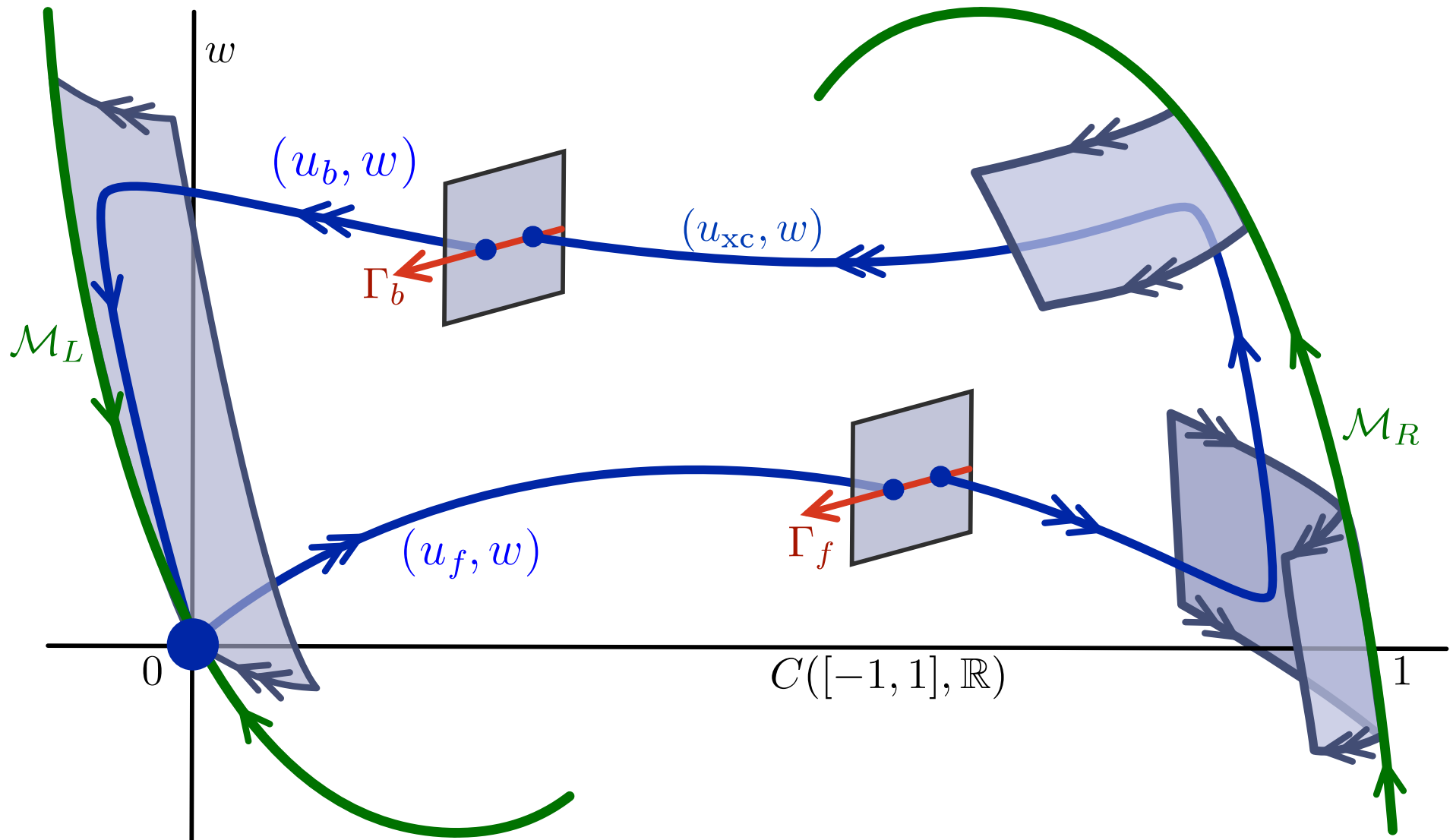
# The program: Step 3 - Exchange Lemma

Match the quasi-front and quasi-back at halfway-point along  $\mathcal{M}_R$ . Split into seven distinct intervals.



# The program: Step 3 - Exchange Lemma

Quasi-front and quasi-back can be matched up to two one-dimensional jumps.





## The program: Step 4 - Bifurcation equations

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The independent parameters are  $(c, T^{\text{sl}}, T)$  taken near  $(c_*, T_*^{\text{sl}}, \infty)$ .

The jumps in  $\Gamma_f$  and  $\Gamma_b$  can be split into two parts:

- Construction of quasi-fronts and quasi-backs
- Modification due to Exchange Lemma

The Exchange Lemma contribution + derivatives are of order  $O(e^{-\eta_* T})$ .

System to solve is hence, to first order,

$$\begin{aligned}M_c^f(c - c_*) &= -M_\epsilon^f T^{\text{sl}}/T \\M_c^b(c - c_*) &= -M_w^b(T^{\text{sl}} - T_*^{\text{sl}}) - M_\epsilon^b T^{\text{sl}}/T\end{aligned}$$

The sign of the  $M$ -constants can be read off from Melnikov integrals.

Three unknowns; two equations  $\longrightarrow$  curve of solutions  $(\epsilon, c(\epsilon))$ .

# Outlook

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Recall FHN-LDE:

$$\begin{aligned}\dot{U}_j(t) &= \alpha[U_{j+1}(t) + U_{j-1}(t) - 2U_j(t)] + g(U_j(t); a) - W_j(t), \\ \dot{W}_j(t) &= \epsilon[U_j(t) - \gamma W_j(t)].\end{aligned}$$

Number of issues open to explore:

- Stability of the fast pulses: same singular perturbation setup should yield results.
- What happens to fast pulses as propagation failure region is encountered?
- For  $a \approx \frac{1}{2}$ , can one Taylor expand in the Exchange Lemma and connect slow and fast pulses [as in Krupa, Sandstede, Szmolyan (1997) ]?
- Multi-pulses, homoclinic blow-up etc in other singularly perturbed lattice problems.