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Well-posedness of Initial Value Problems
for Functional Differential-Algebraic Equations
of Mixed Type



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Initial value problems

Prototype initial value problem:

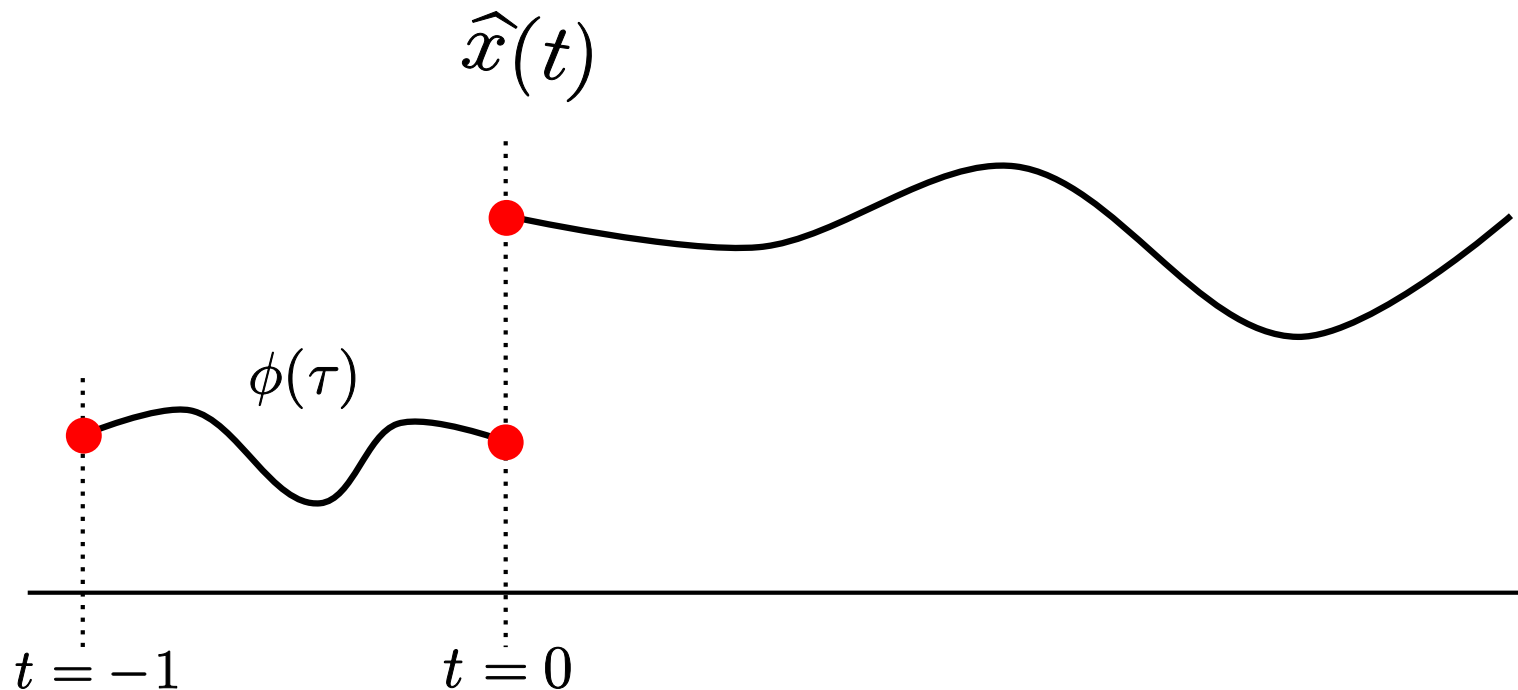
$$\begin{aligned}\mathcal{I}x'(t) &= x(t) + \int_{-1}^1 x(t + \sigma)d\sigma + f(x(t)) && \text{for all } t \geq 0, \\ x(\tau) &= \phi(\tau) && \text{for all } -1 \leq \tau \leq 0.\end{aligned}$$

- Matrix \mathcal{I} diagonal: singular and invertible both allowed.
- Dependence both on 'past' and 'future' arguments of x
- If \mathcal{I} invertible: mixed type functional differential equation (MFDE).
- If \mathcal{I} singular: mixed type differential-algebraic equation (MFDAE)
- Does every initial condition ϕ lead to a (bounded) solution?
- Uniqueness of solution for given ϕ ?

Initial value problems

Recall prototype initial value problem:

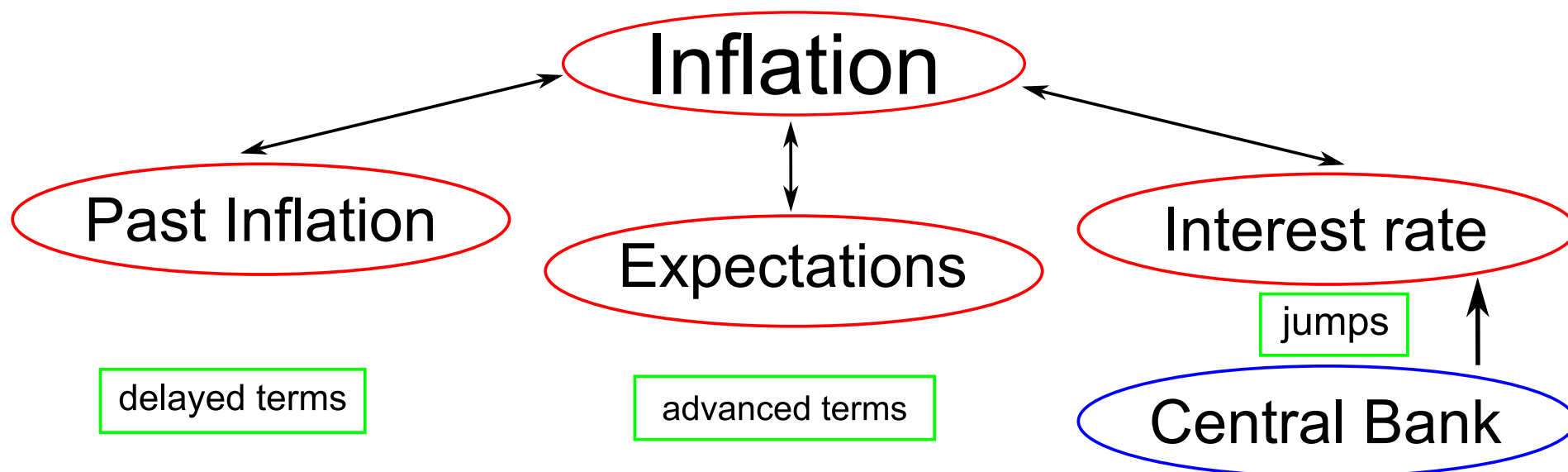
$$\begin{aligned} \mathcal{I}x'(t) &= x(t) + \int_{-1}^1 x(t + \sigma) d\sigma + f(x(t)) && \text{for all } t \geq 0, \\ x(\tau) &= \phi(\tau) && \text{for all } -1 \leq \tau \leq 0. \end{aligned}$$



- Solution $x = \hat{x}(t)$ may have jump at $t = 0$; similar to impulsive equations [Liu, Ballinger]

Motivation

Direct motivation comes from economic modelling.



- Can central bank stabilize inflation by jump in interest rate?
- Do multiple self-fulfilling paths exist?

Model Equations

Model system given by

$$\begin{aligned}\Lambda(R(t))R'(t) &= \pi(t) + r - R(t) \\ \pi^b(t) &= \int_{-1}^0 e^{\beta^b \sigma} \pi(\sigma) d\sigma \\ \pi^f(t) &= \int_0^1 e^{\beta^f \sigma} \pi(\sigma) d\sigma \\ \pi(t) &= f(R(t)) - \pi^b(t) - \pi^f(t)\end{aligned}$$

Differential equation coupled with algebraic equations.

- Interest rate: $R(t)$.
- Inflation rate: $\pi(t)$.
- Past inflation: $\pi^b(t)$.
- Inflation expectation: $\pi^f(t)$.

Variable $\pi(t)$ can be eliminated, leaving three independent variables.

Initial values for R , π^b and π^f given on $[-1, 0]$.

Delay Equations

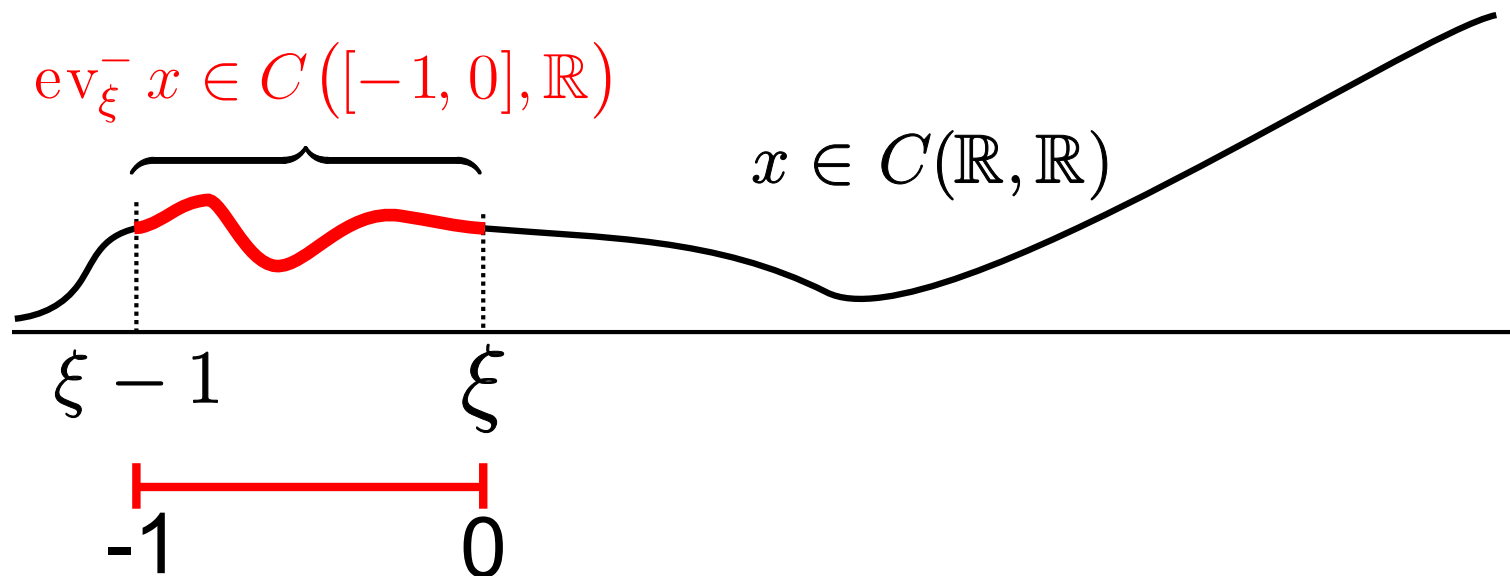
Consider first the linear delay differential equation

$$x'(\xi) = L_- \text{ev}_\xi^- x,$$

where $L_- : C([-1, 0], \mathbb{R}) \rightarrow \mathbb{R}$.

Characteristic function given by

$$\Delta_{L_-}(z) = z - L_- e^z.$$



Delay Equations

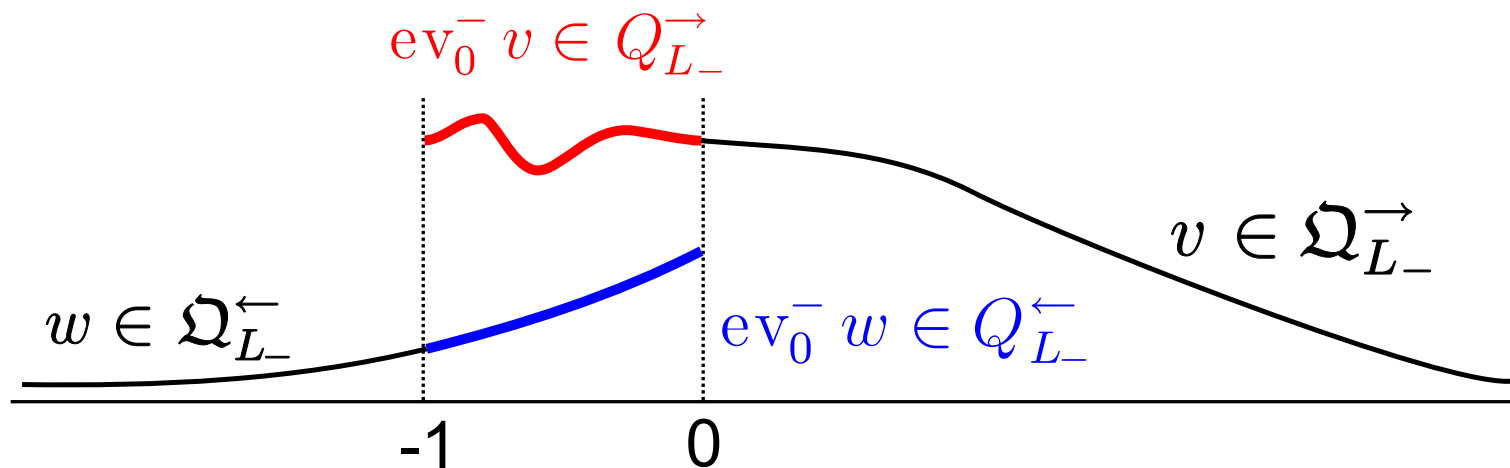
We are interested in solution spaces

$$\mathfrak{Q}_{L_-}^{\leftarrow} = \{w \in BC((-\infty, 0], \mathbb{R}) : w'(\xi) = L_- \text{ev}_{\xi}^- w \text{ for all } \xi \leq 0\},$$

$$\mathfrak{Q}_{L_-}^{\rightarrow} = \{v \in BC([-1, \infty), \mathbb{R}) : v'(\xi) = L_- \text{ev}_{\xi}^- v \text{ for all } \xi \geq 0\}.$$

We also use 'initial segment' spaces

$$Q_{L_-}^{\leftarrow} = \text{ev}_0^- (\mathfrak{Q}_{L_-}^{\leftarrow}), \quad Q_{L_-}^{\rightarrow} = \text{ev}_0^- (\mathfrak{Q}_{L_-}^{\rightarrow}).$$

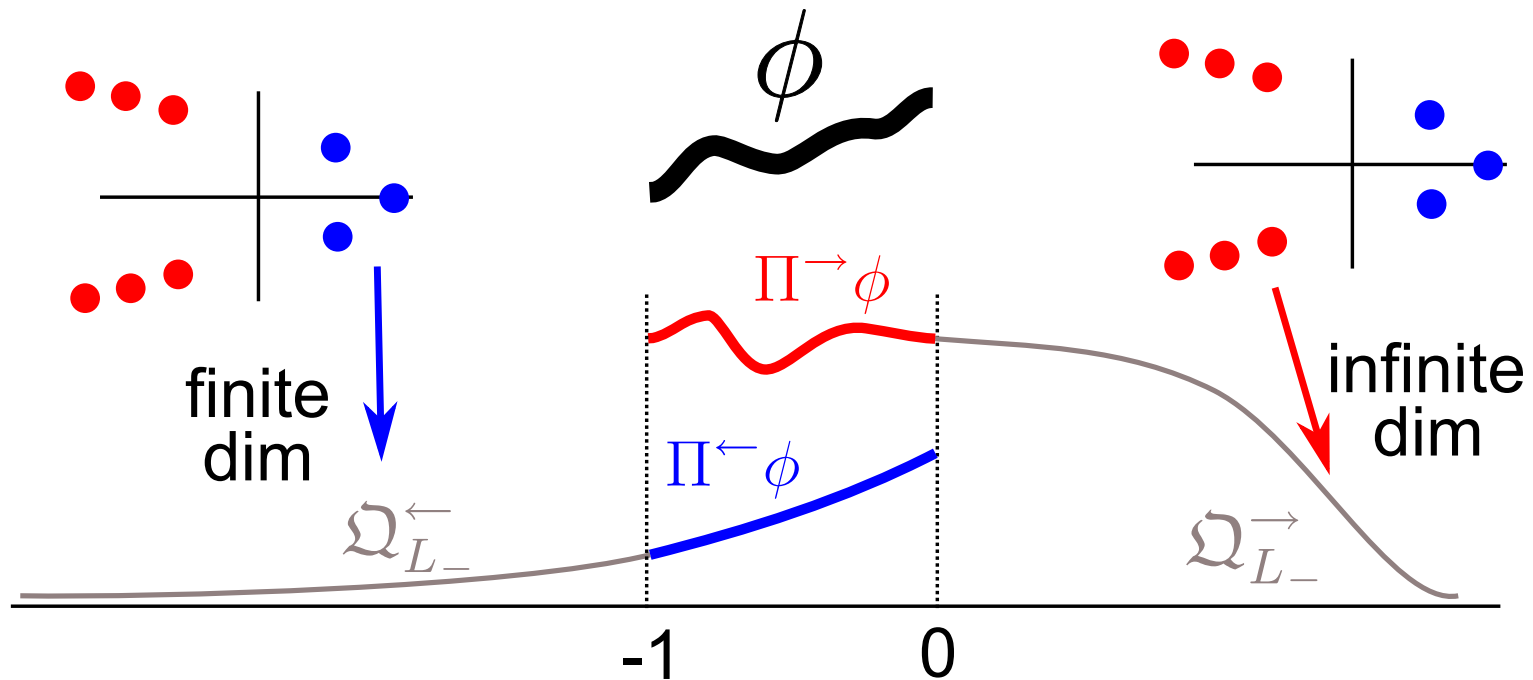


Delay Equations

Thm. If $\Delta_{L_-}(z) = 0$ has no roots on imag. axis, then

$$C([-1, 0], \mathbb{C}) = Q_{L_-}^{\leftarrow} \oplus Q_{L_-}^{\rightarrow}.$$

$Q_{L_-}^{\leftarrow}$ is finite dimensional, spanned by eigenfunctions for roots $\Delta_{L_-}(z) = 0$ with $\operatorname{Re} z > 0$.



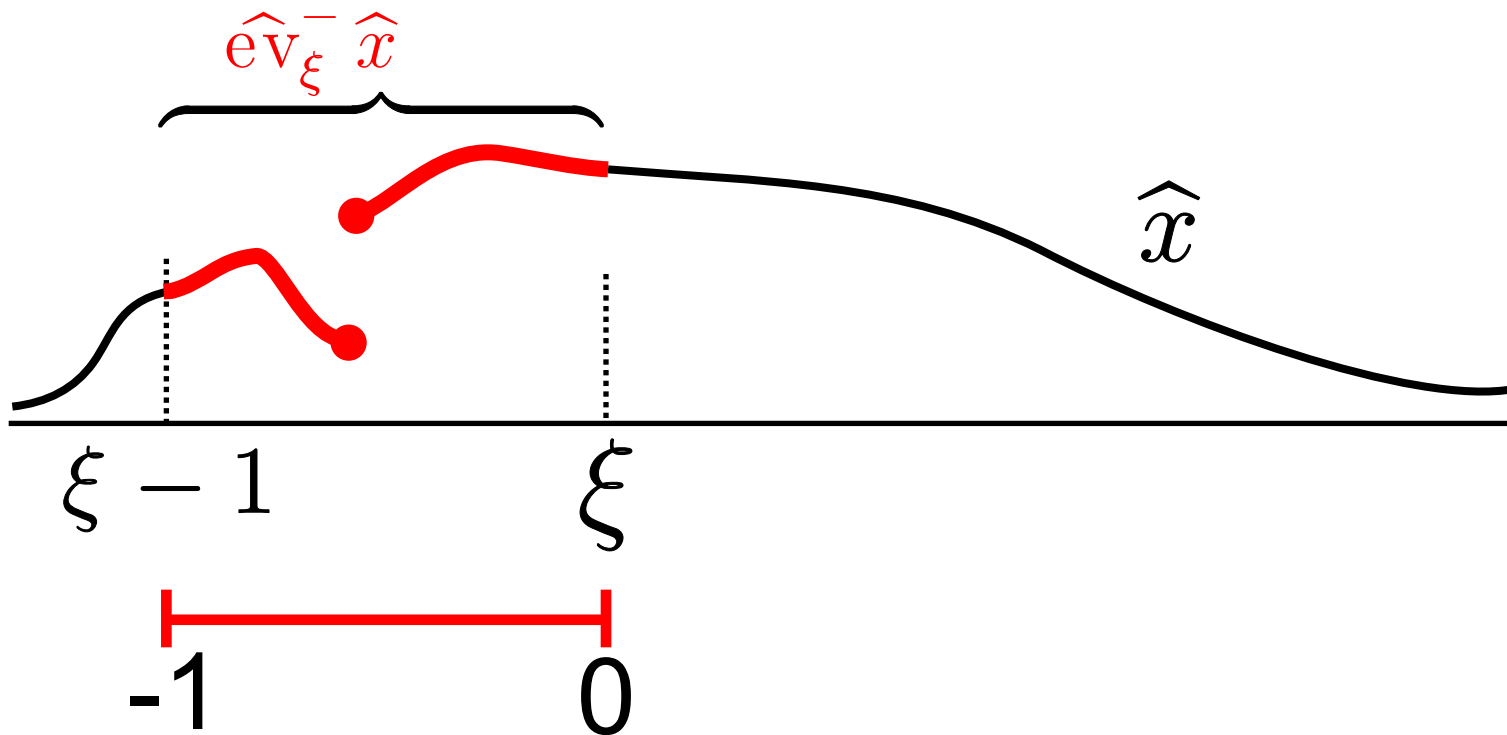
Spectral projections explicitly give projections Π^{\rightarrow} and Π^{\leftarrow} .

Delay Equations - Jumps

Consider now the linear delay differential equation

$$x'(\xi) = L_- \widehat{v}_\xi^- x,$$

where $L_- : PC([-1, 0], \mathbb{R}) \rightarrow \mathbb{R}$.



Look for solutions \widehat{x} with single discontinuity at $\xi = 0$.

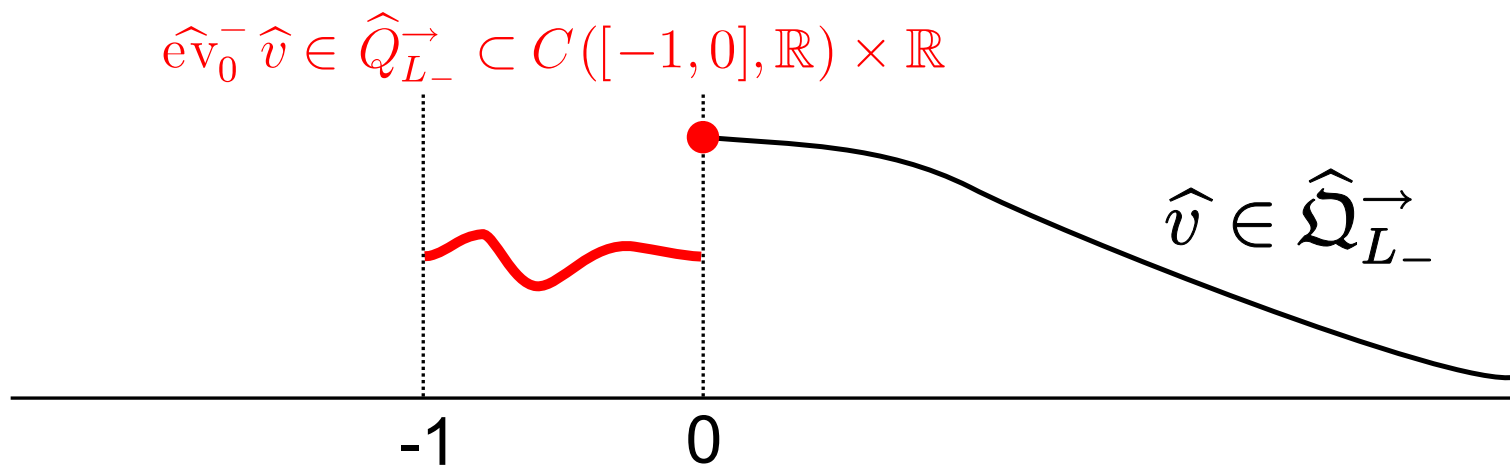
Delay Equations

Interested in solution spaces

$$\widehat{\mathfrak{Q}}_{L_-}^{\rightarrow} = \{ \widehat{v} \in C([-1, 0], \mathbb{R}) \times C([0, \infty), \mathbb{R}) : \widehat{v}'(\xi) = L_- \widehat{e}v_{\xi}^- \widehat{v} \text{ for almost all } \xi \geq 0 \}.$$

We also use 'initial segment' space

$$\widehat{Q}_{L_-}^{\rightarrow} = \widehat{e}v_0^- (\mathfrak{Q}_{L_-}^{\rightarrow}) \subset C([-1, 0], \mathbb{R}) \times \mathbb{R}.$$

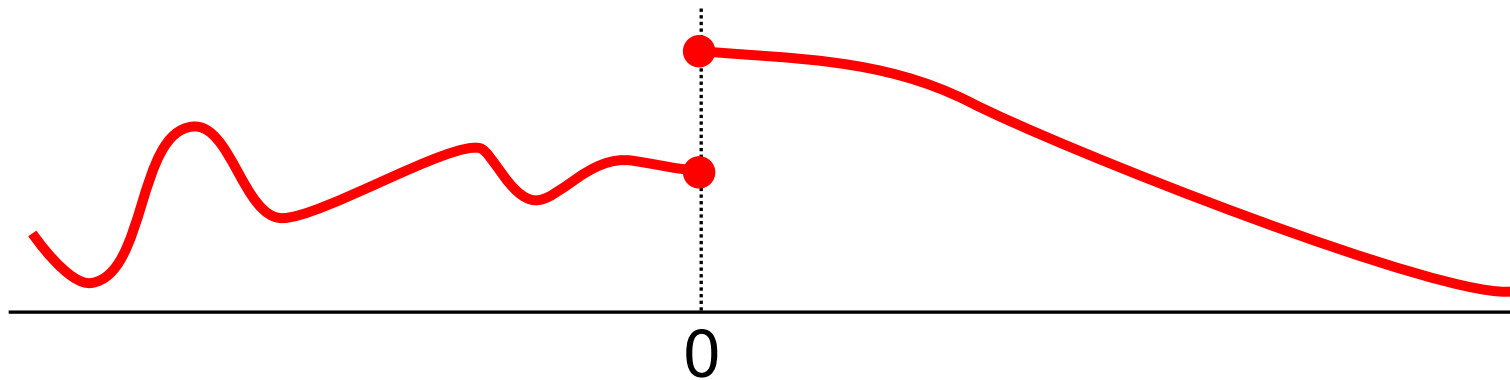


Delay Equations

Question: how to link jump-solutions $\widehat{\mathcal{Q}}_{L_-}^{\rightarrow}$ with continuous solutions $\mathcal{Q}_{L_-}^{\rightarrow}$.

Answer: Green's function $\widehat{G}_{L_-}(\xi) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{i\nu\xi} \Delta_{L_-}(i\nu)^{-1} d\nu$.

$$\widehat{G}_{L_-} \in C(\mathbb{R}_-, \mathbb{R}) \times C(\mathbb{R}_+, \mathbb{R})$$



\widehat{G}_{L_-} continuous except for discontinuity at $\xi = 0$; solves

$$\widehat{G}'_{L_-}(\xi) = L_- \widehat{v}_\xi^- \widehat{G}_{L_-} + \delta(\xi)$$

This gives us

$$\widehat{\mathcal{Q}}_{L_-}^{\rightarrow} = \mathcal{Q}_{L_-}^{\rightarrow} \oplus \text{span}\{\widehat{G}_{L_-}\}.$$

Delay Equations

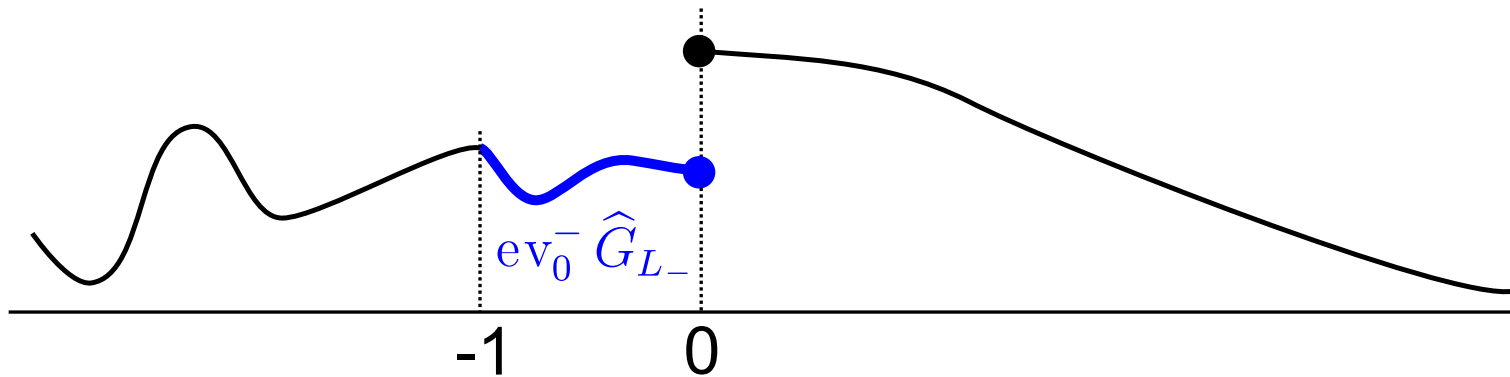
Starting from

$$\widehat{\mathcal{Q}}_{L-}^{\rightarrow} = \mathcal{Q}_{L-}^{\rightarrow} \oplus \text{span}\{\widehat{G}_{L-}\},$$

what are consequences for initial segments

$$\widehat{Q}_{L-}^{\rightarrow} \quad \text{vs} \quad Q_{L-}^{\rightarrow}$$

$$\widehat{G}_{L-} \in C(\mathbb{R}_-, \mathbb{R}) \times C(\mathbb{R}_+, \mathbb{R})$$



Need to understand relation

$$\text{ev}_0^- \widehat{G}_{L-} \quad \text{vs} \quad Q_{L-}^{\rightarrow}.$$

Delay Equations

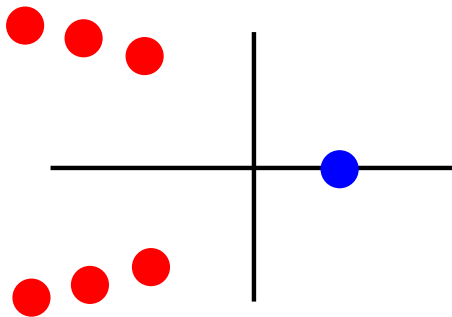
Use spectral projections to understand relation

$$\text{ev}_0^- \widehat{G}_{L_-} \quad \text{vs} \quad Q_{L_-}^{\rightarrow}.$$

Prop. If $\Delta_{L_-}(z_*) = 0$ with $\text{Re } z_* > 0$, then we have

$$\Pi^{\text{sp}}(z_*) \text{ev}_0^- \widehat{G}_{L_-} = -\text{Res}_{z=z_*} e^{z \cdot} \Delta_{L_-}(z)^{-1}.$$

Example



We have $Q_{L_-}^{\rightarrow} \neq C([-1, 0], \mathbb{R})$. But: any $\phi \in C([-1, 0], \mathbb{R})$ can be extended to a bounded solution \widehat{x} , where the jump at zero depends directly (and explicitly) on ϕ .

Delay Equations

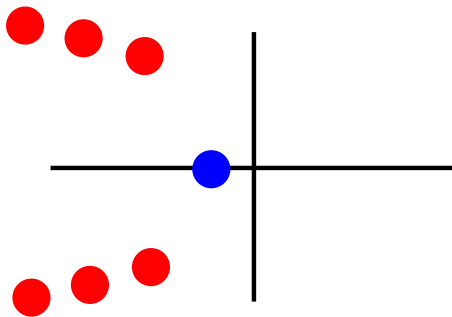
Use spectral projections to understand relation

$$\text{ev}_0^- \widehat{G}_{L_-} \quad \text{vs} \quad Q_{L_-}^{\rightarrow}.$$

Prop. If $\Delta_{L_-}(z_*) = 0$ with $\text{Re } z_* > 0$, then we have

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Example 2

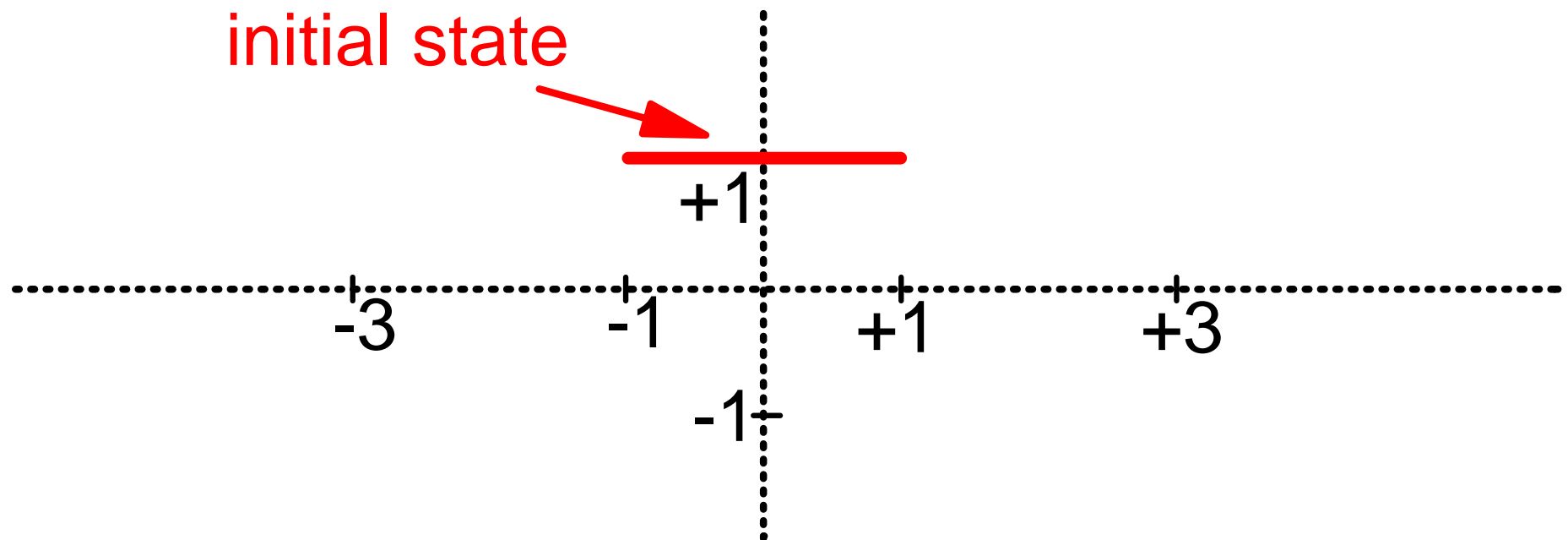


We have $Q_{L_-}^{\rightarrow} = C([-1, 0], \mathbb{R})$. Any $\phi \in C([-1, 0], \mathbb{R})$ can be extended **in multiple ways** to a bounded solution \widehat{x} , where the jump at zero can be chosen arbitrarily.

MFDE - Ill-posedness

Moving on to mixed type equations, consider the MFDE

$$v'(\xi) = v(\xi - 1) + v(\xi + 1).$$

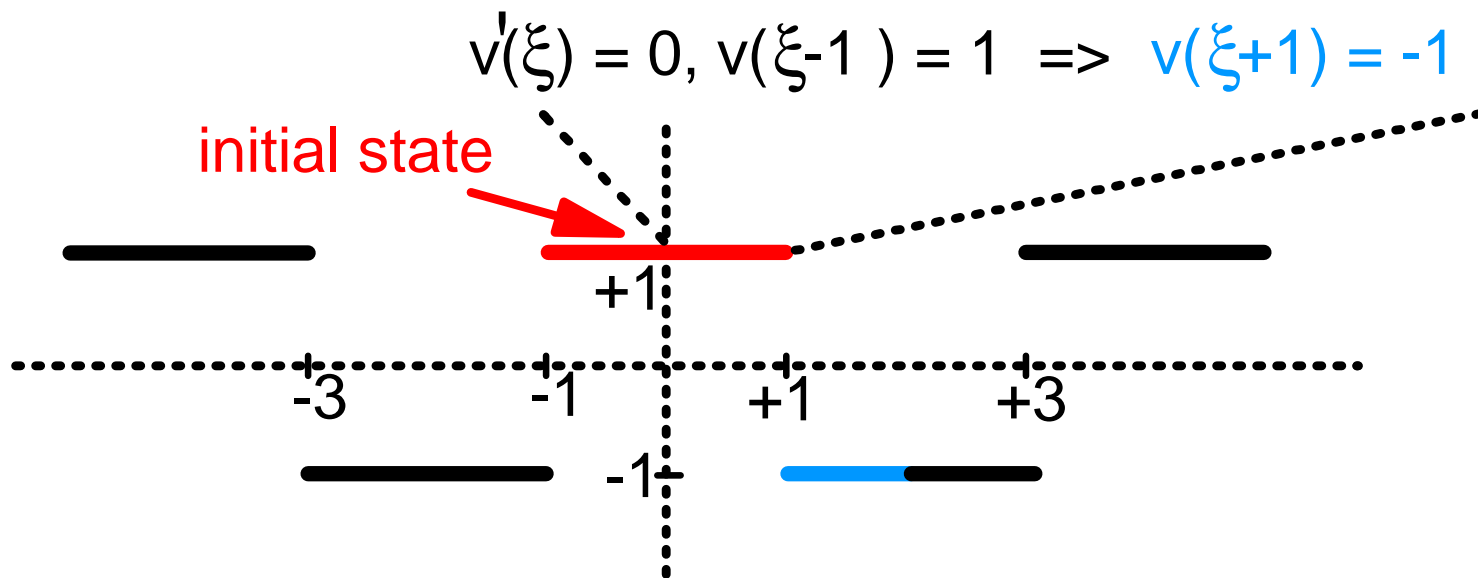


(Example due to Rustichini)

Ill-posedness

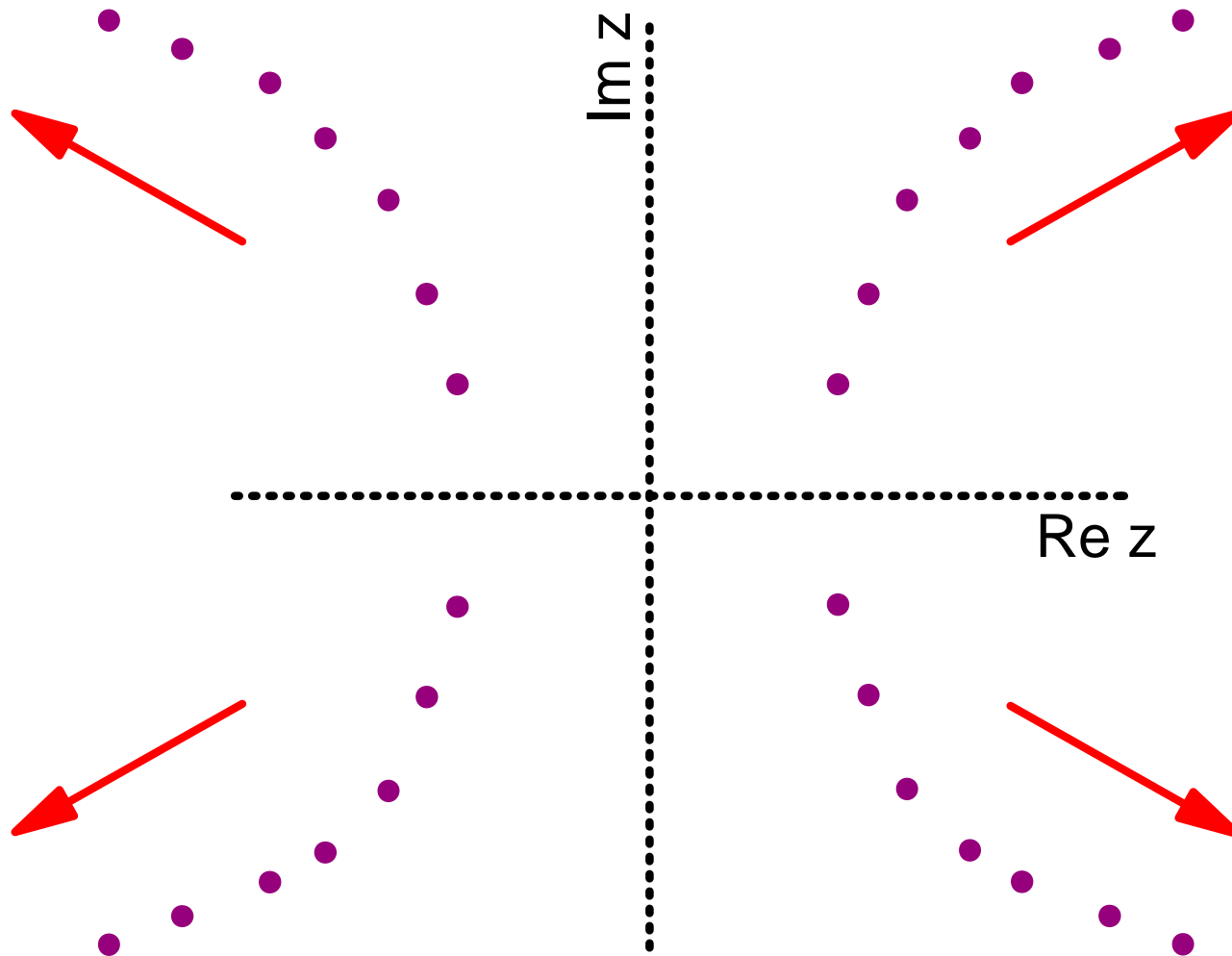
Moving on to mixed type equations, consider the MFDE

$$v'(\xi) = v(\xi - 1) + v(\xi + 1).$$



- Continuity lost \implies ill-posed as an initial value problem with initial conditions in the 'mathematical' state space $C([-1, 1], \mathbb{R})$.

Ill-posedness: What is going on?



Substitution of $e^{z\xi}$ into

$$v'(\xi) = v(\xi - 1) + v(\xi + 1),$$

yields the characteristic equation

$$\Delta(z) := z - e^{-z} - e^z = 0.$$

- No exponential bound possible for solutions, at both $\pm\infty$ (unlike delay equations)!

MFDEs

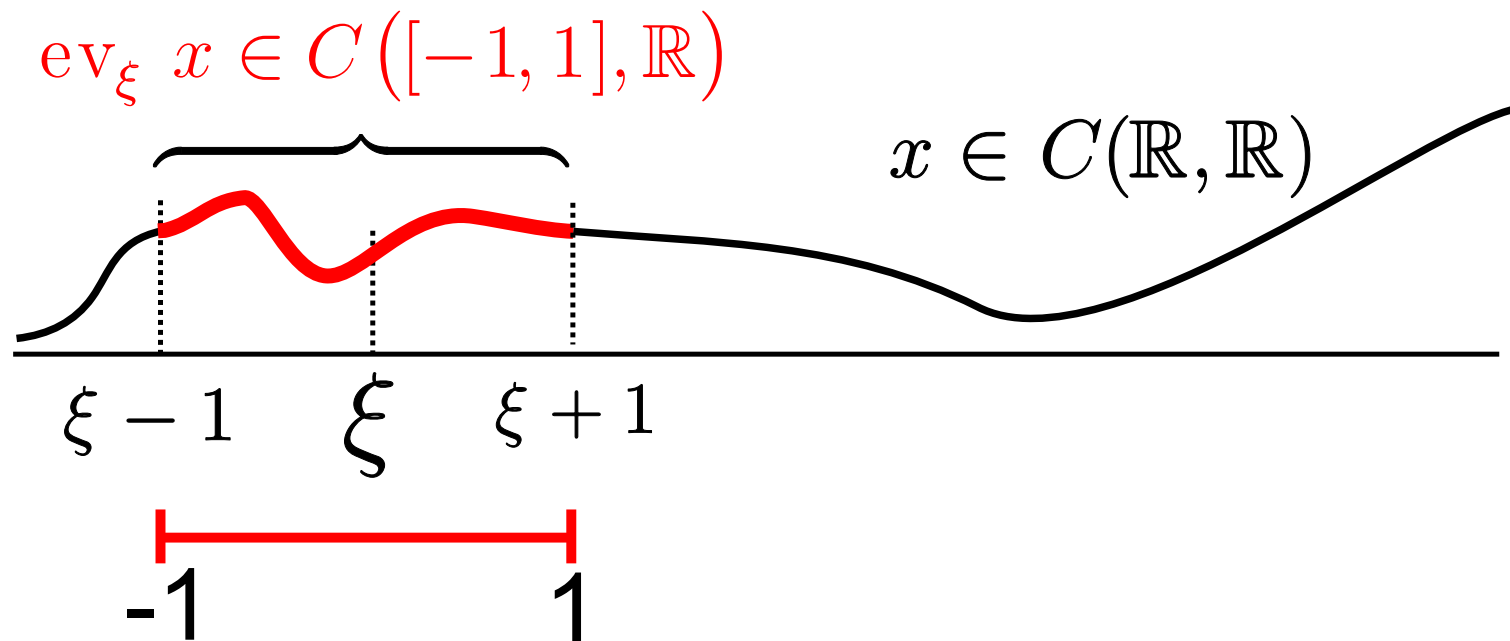
Consider the linear mixed-type equation (MFDE)

$$x'(\xi) = L \operatorname{ev}_\xi x,$$

where $L : C([-1, 1], \mathbb{R}) \rightarrow \mathbb{R}$.

Characteristic function given by:

$$\Delta_L(z) = z - L e^z.$$



MFDEs

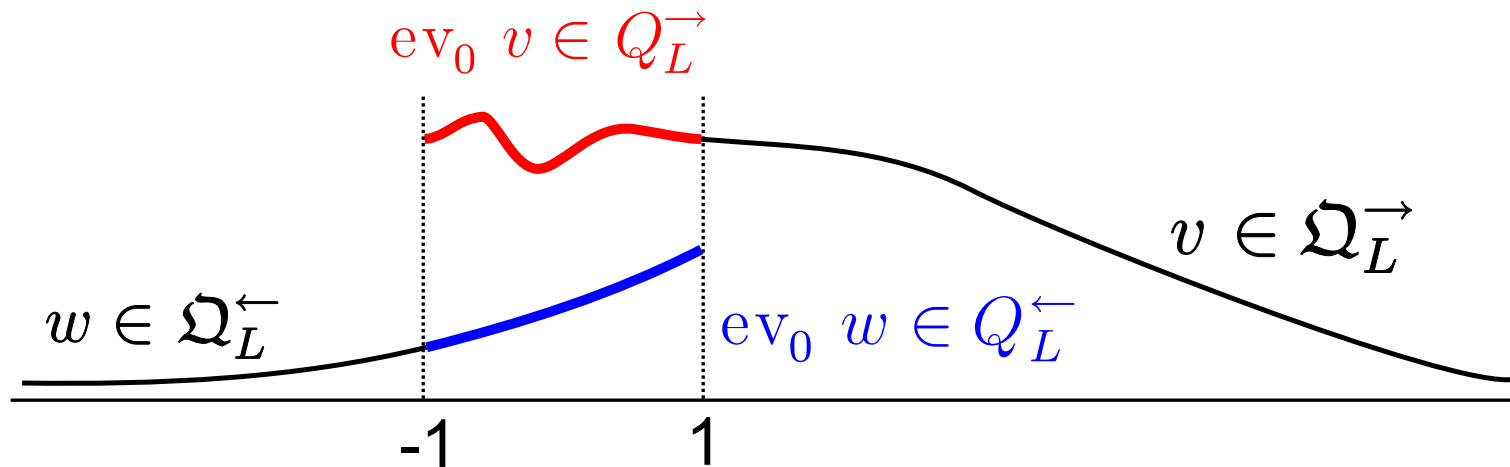
We are interested in solution spaces

$$\mathfrak{Q}_L^{\leftarrow} = \{w \in BC((-\infty, 1], \mathbb{R}) : w'(\xi) = L \operatorname{ev}_\xi w \text{ for all } \xi \leq 0\},$$

$$\mathfrak{Q}_L^{\rightarrow} = \{v \in BC([-1, \infty), \mathbb{R}) : v'(\xi) = L \operatorname{ev}_\xi v \text{ for all } \xi \geq 0\}.$$

We also use 'initial segment' spaces

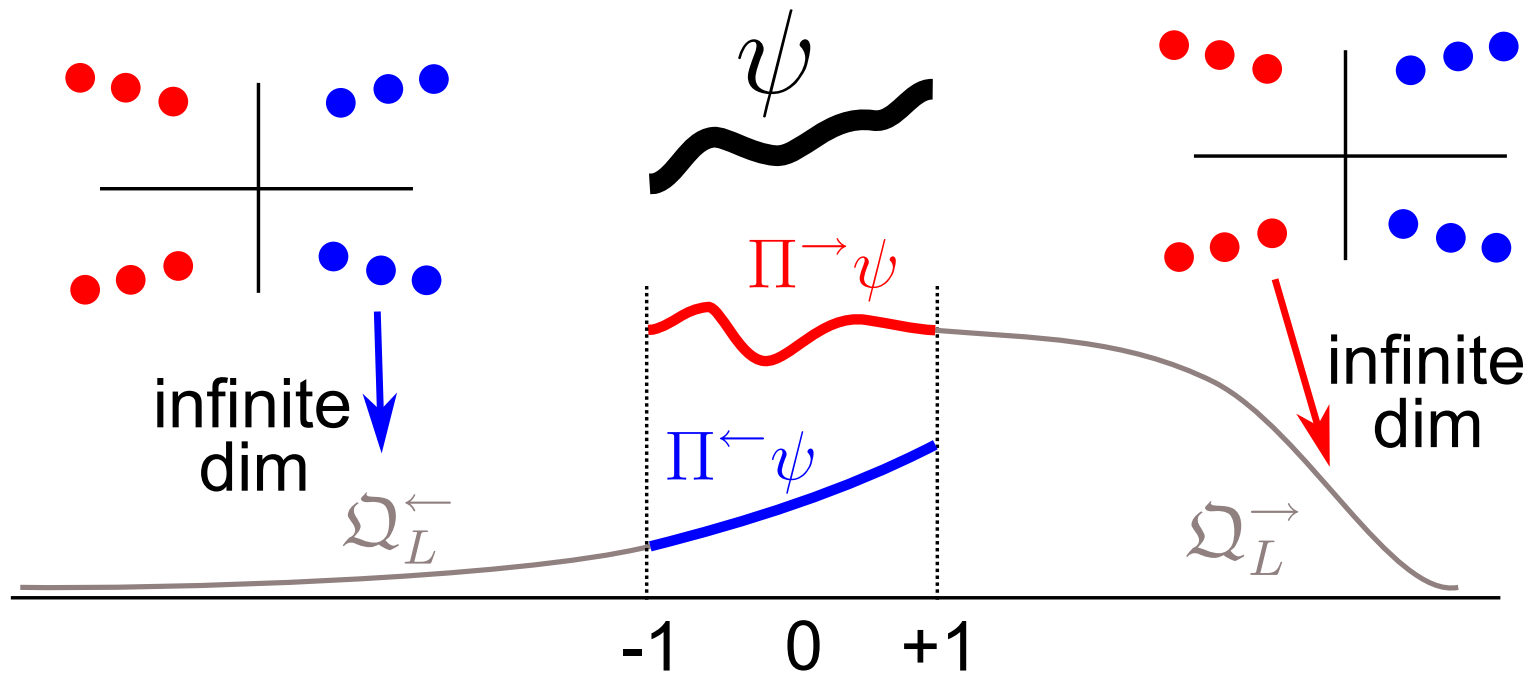
$$Q_L^{\leftarrow} = \operatorname{ev}_0(\mathfrak{Q}_L^{\leftarrow}), \quad Q_L^{\rightarrow} = \operatorname{ev}_0(\mathfrak{Q}_L^{\rightarrow}).$$



MFDEs

Thm. [Verduyn-Lunel+Mallet-Paret, Rustichini] If $\Delta_L(z) = 0$ has no roots on imag. axis, then

$$C([-1, 1], \mathbb{C}) = Q_L^{\leftarrow} \oplus Q_L^{\rightarrow}.$$



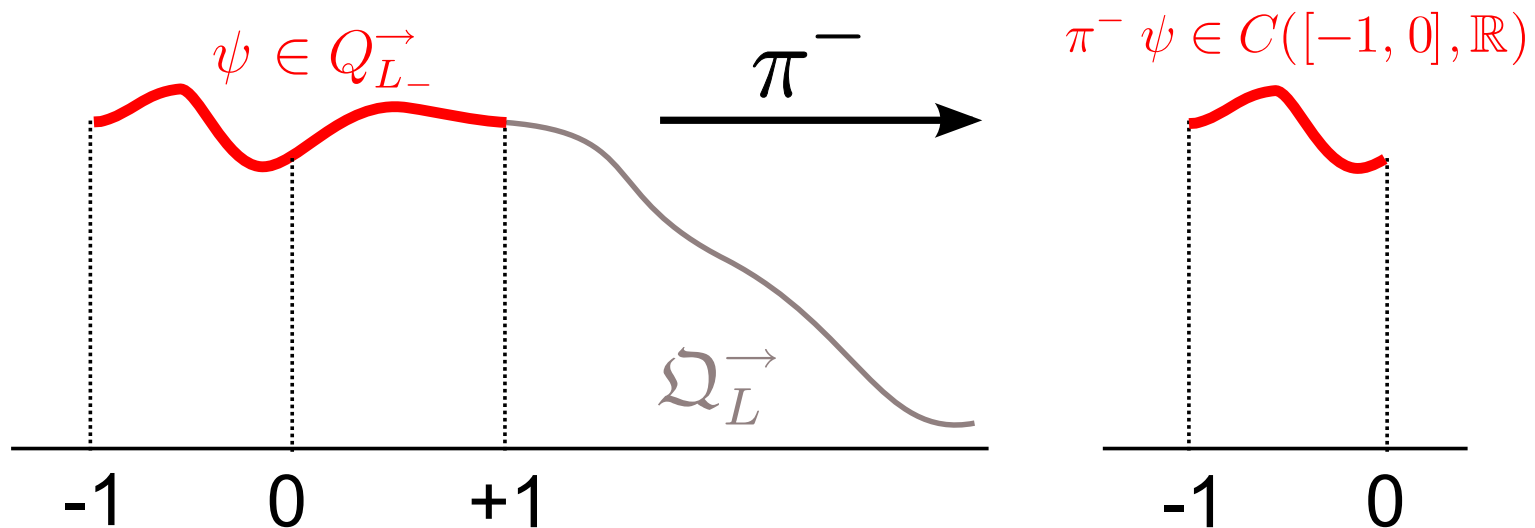
Can no longer use spectral projections to define projections Π^{\leftarrow} and Π^{\rightarrow} .

MFDEs

'Mathematical' state space $C([-1, 1], \mathbb{R})$, but 'modelling' state space $C([-1, 0], \mathbb{R})$.

Restriction operators:

$$\pi^- : Q_L^{\vec{}} \rightarrow C([-1, 0], \mathbb{R}), \quad \psi \mapsto \text{ev}_0^- \psi = \psi_{[-1, 0]}$$



Thm. [Verduyn-Lunel+Mallet-Paret] π^- is Fredholm.

MFDEs

Recall Fredholm restriction operator:

$$\pi^- : Q_L^- \rightarrow C([-1, 0], \mathbb{R}), \quad \psi \mapsto \text{ev}_0^- \psi = \psi_{[-1, 0]}$$

and write

$$R = \text{Range } \pi^- \subset C([-1, 0], \mathbb{R}), \quad K = \text{Ker } \pi^- \subset C([-1, 1], \mathbb{R})$$

R has finite codimension and determines **possibility** of extending initial condition $\phi \in C([-1, 0], \mathbb{R})$.

K has finite dimension and determines **uniqueness** of such an extension.

Unfortunately, no direct way to characterize R and K .

MFDEs - Wiener-Hopf Factorization

Thm. [Verduyn-Lunel+Mallet-Paret; slightly generalized by H.+Augeraud-Veron]
Pick $\alpha > 0$. There exist (non-unique) linear operators

$$L_- : C([-1, 0], \mathbb{C}) \rightarrow \mathbb{C}, \quad L_+ : C([0, 1], \mathbb{C}) \rightarrow \mathbb{C}$$

such that

$$\Delta_{L_-}(z)\Delta_{L_+}(z) = (z + \alpha)\Delta_L(z).$$

The integer

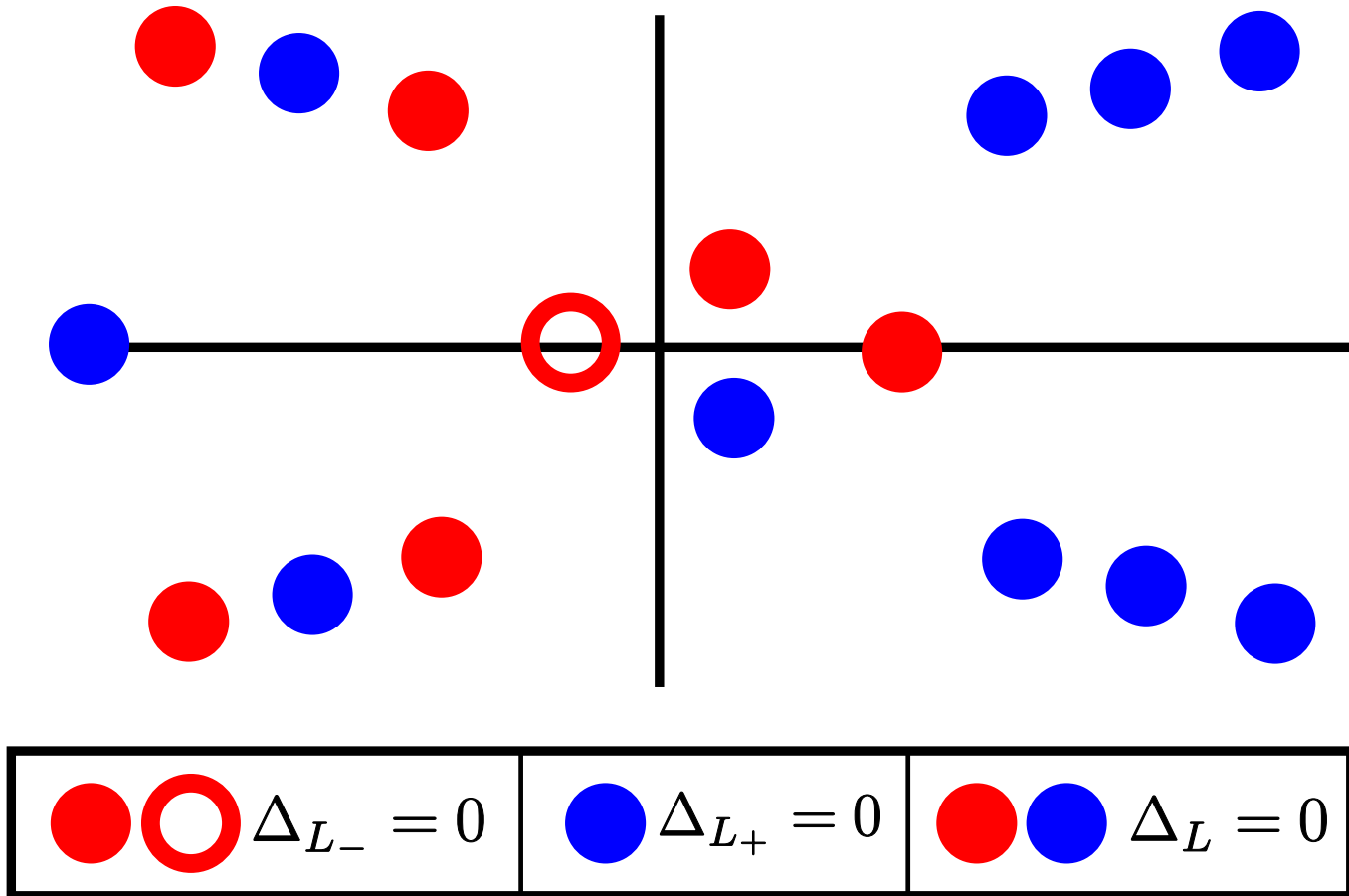
$$n_L^\# = \{z : \Delta_{L_+}(z) = 0 \text{ and } \operatorname{Re} z < 0\} - \{z : \Delta_{L_-}(z) = 0 \text{ and } \operatorname{Re} z > 0\}$$

does not depend on specific pair L_-, L_+ . Finally,

$$\operatorname{codim} R = \max\{1 - n_L^\#, 0\}, \quad \dim K = \max\{n_L^\# - 1, 0\}$$

MFDEs - Wiener-Hopf Factorization

Integer $n_L^\#$ counts roots of $\Delta_{L_-}(z) = 0$ and $\Delta_{L_+}(z) = 0$ that are on 'wrong' side of imaginary axis.



$$(z + \alpha)\Delta_L(z) = \Delta_{L_-}(z)\Delta_{L_+}(z)$$

MFDEs - Wiener-Hopf Factorization

In practice, finding a Wiener-Hopf factorization is intractable.

However, suppose once has a special reference system L_{ref} that one **can** factorize (easier to find).

Construct a path

$$\Gamma : [0, 1] \rightarrow \mathcal{L}(C([-1, 1], \mathbb{C}), \mathbb{C})$$

that connects L_{ref} to L ,

$$\Gamma(0) = L_{\text{ref}}, \quad \Gamma(1) = L.$$

Thm. [H., Augeraud-Veron] Under some nondegeneracy conditions on the path Γ ,

$$n_L^\# = n_{L_{\text{ref}}}^\# - \text{cross}(\Gamma),$$

where $\text{cross}(\Gamma)$ is number of roots that cross imaginary axis from left to right as μ increases from zero to one.

MFDEs with Jumps

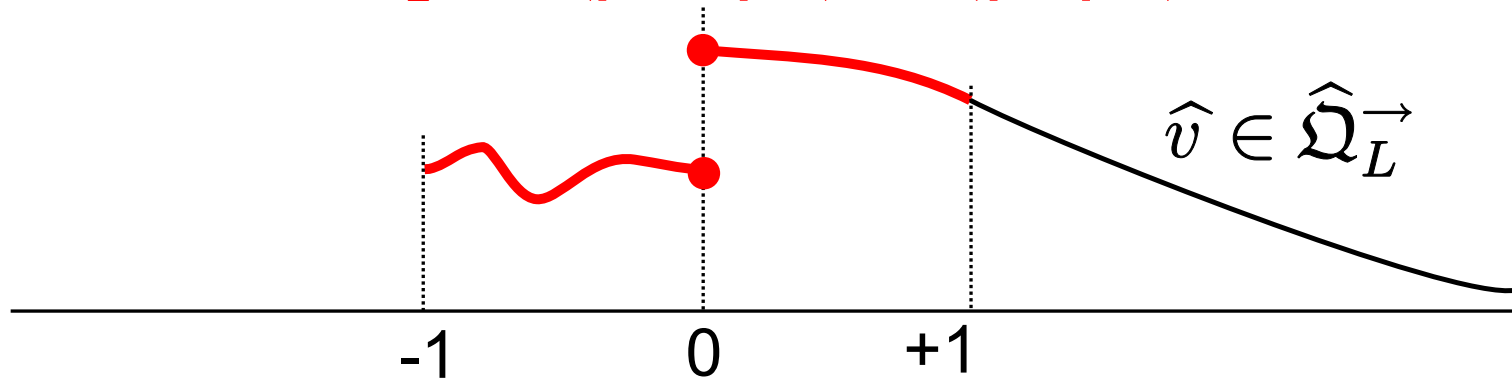
Interested in solution spaces

$$\widehat{\mathcal{Q}}_L^{\rightarrow} = \{ \widehat{v} \in C([-1, 0], \mathbb{R}) \times C([0, \infty), \mathbb{R}) : \widehat{v}'(\xi) = L \widehat{e}v_{\xi} \widehat{v} \text{ for almost all } \xi \geq 0 \}.$$

We also use 'initial segment' space

$$\widehat{Q}_L^{\rightarrow} = \widehat{e}v_0(\mathcal{Q}_L^{\rightarrow}) \subset C([-1, 0], \mathbb{R}) \times C([0, 1], \mathbb{R}).$$

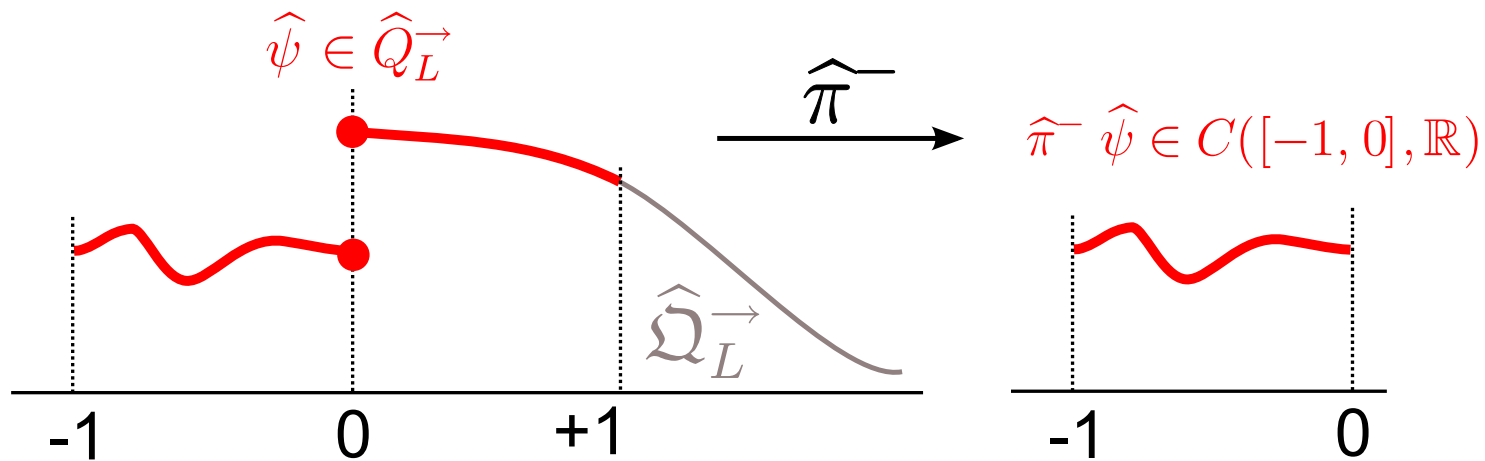
$$\widehat{e}v_0 \widehat{v} \in \widehat{Q}_L^{\rightarrow} \subset C([-1, 0], \mathbb{R}) \times C([0, 1], \mathbb{R})$$



MFDEs with Jumps

Again, introduce restriction

$$\hat{\pi}^- : \hat{Q}_L^{\rightarrow} \rightarrow C([-1, 0], \mathbb{R}), \quad \hat{\psi} \mapsto \text{ev}_0^- \hat{\psi} = \hat{\psi}_{[-1, 0]}$$



Also introduce:

$$\hat{R} = \text{Range } \hat{\pi}^- \in C([-1, 0], \mathbb{R}), \quad \hat{K} = \text{Ker } \hat{\pi}^- \in C([-1, 0], \mathbb{R}) \times C([0, 1], \mathbb{R})$$

\hat{R} determines **possibility** of extending initial condition $\phi \in C([-1, 0], \mathbb{R})$ to bounded solution **with jump**.

\hat{K} determines **uniqueness** of such an extension.

MFDEs - Comparison

Recall **non-jump** setting:

$$\begin{aligned}\pi^- : Q_L^\rightarrow &\rightarrow C([-1, 0], \mathbb{R}), & \psi &\mapsto \psi_{[-1, 0]} \\ R = \text{Range } \pi^- &\subset C([-1, 0], \mathbb{R}), & K = \text{Ker } \pi^- &\in C([-1, 1], \mathbb{R})\end{aligned}$$

with dimensions

$$\text{codim } R = \max\{1 - n_L^\#, 0\}, \quad \dim K = \max\{n_L^\# - 1, 0\}$$

Recall **jump** setting:

$$\begin{aligned}\hat{\pi}^- : \hat{Q}_L^\rightarrow &\rightarrow C([-1, 0], \mathbb{R}), & \hat{\psi} &\mapsto \text{ev}_0^- \hat{\psi} = \hat{\psi}_{[-1, 0]} \\ \hat{R} = \text{Range } \hat{\pi}^- &\in C([-1, 0], \mathbb{R}), & \hat{K} = \text{Ker } \hat{\pi}^- &\in C([-1, 0], \mathbb{R}) \times C([0, 1], \mathbb{R})\end{aligned}$$

Thm.[H., Augeraud-Veron] The operator $\hat{\pi}^-$ is Fredholm and we have

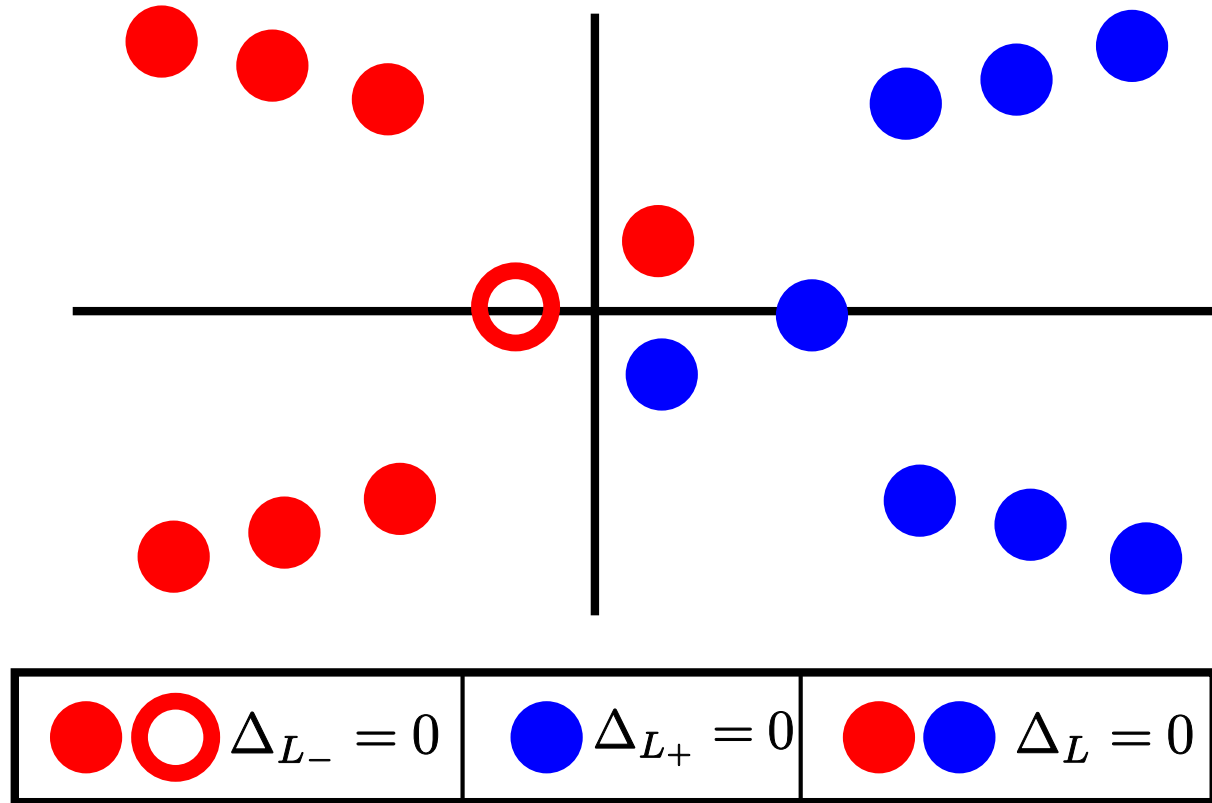
$$\text{codim } \hat{R} = \max\{-n_L^\#, 0\}, \quad \dim \hat{K} = \max\{n_L^\#, 0\}$$

Conclusion: presence of jump introduces one extra d.o.f. for initial value problem.

MFDEs - Sketch of Proof

We again have $\widehat{\mathcal{Q}}_L^{\rightarrow} = \mathcal{Q}_L^{\rightarrow} \oplus \text{span}\{\widehat{G}_L\},$

with \widehat{G}_L the Green's function for MFDE. Use special ordered Wiener-Hopf factorization:



In this case, relation between $\text{ev}_0^- \widehat{G}_L$ and $\pi^-(\mathcal{Q}_L^{\rightarrow})$ can be determined by using spectral projections **of operator** L_- .

Differential-Algebraic Equations

We now turn to the differential-algebraic equation

$$\mathcal{I}x'(\xi) = M \operatorname{ev}_\xi x,$$

where $M : C([-1, 1], \mathbb{R}^n) \rightarrow \mathbb{R}^n$ and \mathcal{I} is diagonal and typically singular.

Characteristic equation given by

$$\delta_{\mathcal{I}, M}(z) = \mathcal{I}z - M e^z.$$

Main Assumption: There exists $L : C([-1, 1], \mathbb{R}^n) \rightarrow \mathbb{R}^n$ so that solutions satisfy

$$x'(\xi) = L \operatorname{ev}_\xi x.$$

Differential-Algebraic Equations - Example

Example: Consider algebraic equation

$$0 = -x(\xi) + \int_{-1}^1 x(\xi + \sigma) d\sigma, \quad (1)$$

which after a single differentiation yields the MFDE

$$x'(\xi) = x(\xi + 1) - x(\xi - 1) \quad (2)$$

Vice versa, if x solves (2) **and** has $x(0) = \int_{-1}^1 x(\sigma) d\sigma$, then x solves (1).

Characteristic function for (1) given by

$$\delta(z) = 1 - \int_{-1}^1 e^{z\sigma} d\sigma = 1 - \frac{1}{z}(e^z - e^{-z})$$

Characteristic function for (2) given by

$$\Delta(z) = z - (e^z - e^{-z})$$

Notice $z\delta(z) = \Delta(z)$.

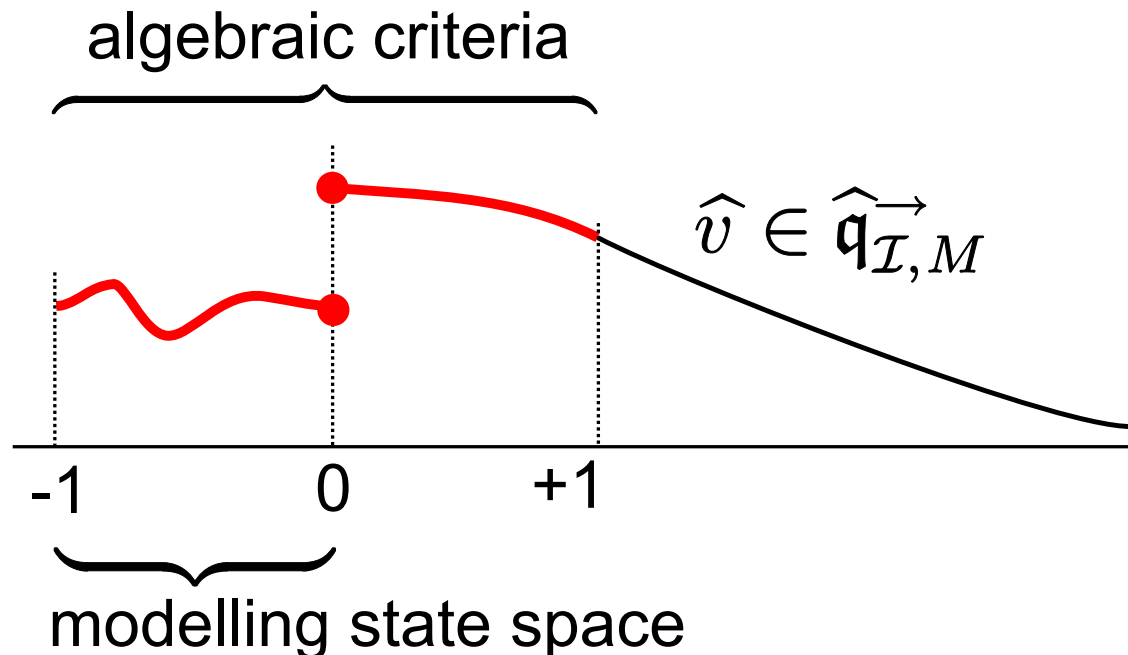
Differential-Algebraic Equations with Jump

Recall 'smooth' differential-algebraic equation (posed on \mathbb{R}^n)

$$\mathcal{I}x'(\xi) = M \text{ev}_\xi x.$$

Interested in solution spaces

$$\begin{aligned} \widehat{\mathfrak{q}}_{\mathcal{I},M} &= \{ \widehat{v} \in C([-1, 0], \mathbb{R}^n) \times C([0, \infty), \mathbb{R}^n) : \\ &\quad \mathcal{I}\widehat{v}'(\xi) = M \widehat{\text{ev}}_\xi \widehat{v} \text{ for 'almost' all } \xi \geq 0 \}. \end{aligned}$$



Differential-Algebraic Equations

Recall 'smooth' differential-algebraic equation (posed on \mathbb{R}^n)

$$\mathcal{I}x'(\xi) = M \text{ev}_\xi x.$$

Thm. [H. + Augeraud-Veron] Pick any $\gamma > 0$. There exist non-negative integers ℓ_1, \dots, ℓ_n and an operator $L(\gamma) : C([-1, 1], \mathbb{R}^n) \rightarrow \mathbb{R}^n$ such that

$$\begin{pmatrix} (z - \gamma)^{\ell_1} & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & (z - \gamma)^{\ell_n} \end{pmatrix} \delta_{\mathcal{I}, M}(z) = \Delta_{L(\gamma)}(z).$$

In addition, we have

$$\widehat{\mathfrak{q}}_{\mathcal{I}, M}^{\rightarrow} = \widehat{\mathfrak{Q}}_{L(\gamma)}^{\rightarrow}.$$

Conclusion: Can use prior results to study $\widehat{\mathfrak{q}}_{\mathcal{I}, M}^{\rightarrow}$.

Outlook

- Linear results can be lifted to local nonlinear results.
- Jumps allow 'unstable' equilibria to be stabilized.
- Mixed type equations can have non-unique continuations of initial conditions.
- Mixed type equations in more than one dimension still elusive.