The intersection axiom of conditional independence: some “new” results

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\[(X \perp Y \mid Z) \& (X \perp Z \mid Y) \implies X \perp (Y, Z)\]

Algebraic Statistics seminar, Leiden, 27 February 2019;
Combinatorics seminar 2019, SJTU, 2 October 2019

X is independent of Y given Z and X is independent of Z given Y, implies X is independent of Y and Z
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Intersection axiom. Well known to be neither true nor even an axiom.

X is independent of Y given Z and X is independent of Z given Y, implies X is independent of Y and Z
Comfort zones

All variables have:

- Finite outcome space [Nice for algebraic geometry]
- Countable outcome space
- Continuous joint density with respect to sigma-finite product measures [Usually not used rigorously]
- Outcome spaces are Polish ❤

Other “convenience” assumptions: Strictly positive joint density
Multivariate normal also allows algebraic geometry approach
Algebraic Statistics

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Abstract. Algebraic statistics uses tools from algebraic geometry, commutative algebra, combinatorics, and their computational sides to address problems in statistics and its applications. The starting point for this connection is the observation that many statistical models are semialgebraic sets. The algebra/statistics connection is now over twenty years old–this book presents the first comprehensive and introductory treatment of the subject. After background material in probability, algebra, and statistics, the book covers a range of topics in algebraic statistics including algebraic exponential families, likelihood inference, Fisher’s exact test, bounds on entries of contingency tables, design of experiments, identifiability of hidden variable models, phylogenetic models, and model selection. The book is suitable for both classroom use and independent study, as it has numerous examples, references, and over 150 exercises.
The (semi-)graphoid axioms of (conditional) independence

1. Symmetry \( X \perp Y \implies Y \perp X \)

2. Decomposition \( X \perp (Y, Z) \implies X \perp Y \)

3. Weak union \( X \perp (Y, Z) \implies X \perp Y \mid Z \)

4. Contraction \( (X \perp Z \mid Y \& X \perp Y) \implies X \perp (Y, Z) \)

5. Intersection \( (X \perp Y \mid Z \& X \perp Z \mid Y) \implies X \perp (Y, Z) \)

1–5: (with further global conditioning): the graphoid axioms. Phil Dawid (1980).
1–4: (…): the semi-graphoid axioms
So called because of similarity to *graph separation* for subgraphs of a simple undirected graph: A is separated from B by C
• The intersection axiom (nr 5):

\[(X \perp Y \mid Z) \& (X \perp Z \mid Y) \quad \implies \quad X \perp (Y, Z)\]
• “New” result:

\[
(X \perp Y \mid Z) \& (X \perp Z \mid Y) \iff X \perp (Y, Z) \mid W
\]

where \(W := f(Y) = g(Z)\) for some \(f, g\)
• The intersection axiom:

$$(X \perp Y \mid Z) \& (X \perp Z \mid Y) \implies X \perp (Y, Z)$$

• “New” result:

$$[(X \perp Y \mid Z) \& (X \perp Z \mid Y)] \iff X \perp (Y, Z) \mid W$$

where $W := f(Y) = g(Z)$ for some $f$, $g$

• In particular, we can take $W = Law((Y, Z) \mid X)$
• The intersection axiom:

\[(X \perp Y \mid Z) \& (X \perp Z \mid Y) \implies X \perp (Y, Z)\]

• “New” result:

\[\boxed{(X \perp Y \mid Z) \& (X \perp Z \mid Y) \iff X \perp (Y, Z) \mid W}\]

where \(W := f(Y) = g(Z)\) for some \(f, g\)

• In particular, we can take \(W = \text{Law}((Y, Z) \mid X)\)

• If \(f\) and \(g\) are trivial (constant) we obtain “axiom 5”
• The intersection axiom:

\[ (X \perp Y \mid Z) \& (X \perp Z \mid Y) \implies X \perp (Y, Z) \]

• “New” result:

\[ (X \perp Y \mid Z) \& (X \perp Z \mid Y) \iff X \perp (Y, Z) \mid W \]

where \( W := f(Y) = g(Z) \) for some \( f, g \)

• In particular, we can take \( W = \text{Law}((Y, Z) \mid X) \)

• If \( f \) and \( g \) are trivial (constant) we obtain “axiom 5”

• Also “new”: Nontrivial \( f, g \) exist such that \( f(Y) = g(Z) \) a.e. iff \( A, B \) exist with probabilities strictly between 0 and 1 s.t.

\[
\Pr(Y \in A \& Z \in B^C) = 0 = \Pr(Y \in A^C \& Z \in B)
\]

Call such a joint law decomposable
Construction of counter example
More elaborate counter example
Leading to the general theorem
Discrete case

\[ y, z \text{ each have countable support} \]

\[ \text{Support}(y) \]

\[ \text{Support}(z) \]

\[ y \sim z \iff p(y, z) > 0 \]
Comfort zones

- All variables have finite support (Algebraic Geometry)
- All variables have countable support
- All variables have continuous joint probability densities (many applied statisticians)
- All densities are strictly positive
- All distributions are non-degenerate Gaussian
- All variables take values in Polish spaces (My favourite)

Polish space: a topological space which can be given a metric making it complete and separable
Please recall

- The joint probability distribution of $X$ and $Y$ can be **disintegrated** into the **marginal** distribution of $X$ and a **family** of **conditional** distributions of $Y$ given $X = x$

- The disintegration is unique up to almost everywhere equivalence

- Conditional independence of $X$ and $Y$ given $Z$ is just ordinary independence within each of the joint laws of $X$ and $Y$ conditional on $Z = z$

- For me, $0/0 = \text{“undefined”}$ and $0 \times \text{“undefined”} = 0$ (probability times number)

  - So: conditional distributions **do exist** if we **condition on zero probability** events; they’re just not uniquely defined.

- The non-uniqueness is harmless
Some new notation

• I’ll denote by “law(\(X\))” the probability distribution (law) of \(X\), where \(X\) is a random variable which takes values in a space \(\mathcal{X}\). So \(\text{law}(X)\) is a probability distribution on \(\mathcal{X}\).

• In the finite, discrete case, a “law” is just a vector of real numbers, non-negative, adding to one.

• In the Polish case, the set of probability laws on a given Polish space is itself a Polish space under, e.g., the Wasserstein metric. Disintegrations exist, Everything is nice.

• The family of conditional distributions of \(X\) given \(Y\), \((\text{law}(X \mid Y = y))_{y \in \mathcal{Y}}\) can be thought of as a function of \(y \in \mathcal{Y}\). In the Polish case, the function is Borel measurable.

• As a function of the random variable \(Y\), we can consider it as a random variable, or as a random vector taking values in an affine space.

• By Law(\(X \mid Y\)) I’ll denote that random variable, taking values in the space of probability laws on \(\mathcal{X}\).

Note distinction: Law vs. law
Crucial lemma

\[ X \perp Y \mid \text{Law}(X \mid Y) \]
Lemma: $X \perp Y \mid \text{Law}(X \mid Y)$

$\Delta_d = \text{probability simplex, dimension } d$

capital $L = \text{Law}(X \mid Y)$, a random probability measure

Small $\ell$ ("ell") is a possible realisation

Proof of lemma, discrete case

Recall, $X \perp Y \mid Z \iff p(x, y, z) = g(x, z) h(y, z)$

Thus $X \perp Y \mid L \iff$ we can factor $p(x, y, l)$ this way

Given function $p(x, y)$, pick any $x \in \mathcal{X}, y \in \mathcal{Y}, \ell \in \Delta_{|X|-1}$

$$p(x, y, \ell) = p(x, y) \cdot 1\{\ell = p(\cdot, y)/p(y)\}$$

$$= \ell(x)p(y)1\{\ell = p(\cdot, y)/p(y)\}$$

$$= \text{Eval}(\ell, x) \cdot p(y)1\{\ell = p(\cdot, y)/p(y)\}$$

Proof of lemma, Polish case

Similar, but a tiny bit different – we don’t assume existence of joint densities!
Proof of forwards implication

• $X \perp Y \mid Z \implies \text{Law}(X \mid Y, Z) = \text{Law}(X \mid Z)$

• $X \perp Z \mid Y \implies \text{Law}(X \mid Y, Z) = \text{Law}(X \mid Y)$

• So we have $w(Y, Z) = g(Z) = f(Y) =: W$ for some functions $w, g, f$

• By our lemma, $X \perp (Y, Z) \mid \text{Law}(X \mid (Y, Z))$

• We found functions $g, f$ such that $g(Z) = f(Y)$ and, with $W := w(Y, Z) = g(Z) = f(Y)$, $X \perp (Y, Z) \mid W$
Proof of reverse implication

- Suppose $X \perp (Y, Z) \mid W$ where $W = g(Z) = f(Y)$ for some functions $g, f$
- By axiom 3, $X \perp Y \mid (W, Z)$
- So $X \perp Y \mid (g(Z), Z)$
- So $X \perp Y \mid Z$
- Similarly, $X \perp Z \mid Y$
Sullivant

- Uses primary decomposition of toric ideals to come up with a nice parametrisation of the model “Axiom 5”

- Given: finite sets $X$, $Y$, $Z$, what is the set of all probability measures on their product satisfying Axiom 5, and with $p(y) > 0$, $p(z) > 0$, for all $y$, $z$?

- Answer: pick partitions of $Y$, $Z$ which are in 1-1 correspondence with one another. Call one of them “$W$”. Pick a positive probability distribution on $W$. Pick indecomposable probability distributions on the products of corresponding partition elements of $Y$ and $Z$. Pick probability distributions on $X$, also corresponding to the preceding, not necessarily all different

- Now put them together: in simulation terms: generate r.v. $W = w \in W$. Generate $(Y,Z)$ given $W = w$ and independently thereof generate $X$ given $W = w$. 
Polish spaces

• Exactly same construction ... just replace “partition” by a Borel measurable map \textit{onto} another Polish space

• “Corresponding partitions” ... Borel measurable maps onto \textit{same} Polish space
Questions

• Does algebraic geometry provide any further “statistical” insights?

• Can some of you join me to turn all these ideas into a nice joint paper?

• Could there be a category theoretical meta-theorem?
References

Sullivant, book, ch. 4, esp. section 4.3.1

Mathias Drton, Bernd Sturmfels, and Seth Sullivant, 


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