

EXERCISES *Introduction to Dynamical Systems '18-'19*: Series I

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Exercise 1.

- Ia) Consider $g : [0, \infty) \rightarrow \mathbb{R}$ given by $g(t) = \frac{\cos t^2}{t+1}$: show that $\lim_{t \rightarrow \infty} g(t)$ exists, while $\lim_{t \rightarrow \infty} \dot{g}(t) (= \frac{dg}{dt}(t))$ does not.
- Ib) Consider the autonomous ODE $\dot{x} = f(x)$, $x \in \mathbb{R}^n$, with initial condition $x(0) = x_0$ and $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$ (at least) continuously differentiable. Let $\phi(t; x_0)$ be a solution such that $\lim_{t \rightarrow \infty} \phi(t; x_0) = a$ for a certain $a \in \mathbb{R}^n$. Prove that a must be a critical point of the system.
Warning: Be aware of functions that behave like $g(t)$ in (Ia).
- Ic) Explain why $g(t)$ of (Ia) cannot be a solution of a system as described in (Ib) (with $n = 1$).
- Id) Can $g(t)$ be a solution of a non-autonomous (smooth) system $\dot{x} = f(x, t)$? Explain! Is the situation different from that of (Ib) and (Ic)? Why?
- IIa) Consider the flow $\phi(t; x) : \mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R}^n$. Prove ‘continuous dependence on initial conditions’ for flows, i.e. let the initial condition $x_0 \in \mathbb{R}^n$ be given and show that for all $T > 0$ and $\delta > 0$ there is an $\varepsilon > 0$ such that $\|\phi(T; x_0) - \phi(T; \tilde{x}_0)\| < \delta$ for all \tilde{x}_0 with $\|x_0 - \tilde{x}_0\| < \varepsilon$.
Note: This flow is not necessarily associated to an ODE.
- IIb) Can you improve this result to a version that is uniform in t , i.e. to: for all $T > 0$ and $\delta > 0$ there is an $\varepsilon > 0$ such that $\|\phi(t; x_0) - \phi(t; \tilde{x}_0)\| < \delta$ for all \tilde{x}_0 with $\|x_0 - \tilde{x}_0\| < \varepsilon$ and all $t \in [0, T]$?
- IIc) Now establish the equivalent of (Ib) for flows: assume that $\phi(t; x_0) \rightarrow a \in \mathbb{R}^n$ as $t \rightarrow \infty$ (and x_0 fixed), show that $\phi(t; a) \equiv a$ i.e. that $x = a$ is a fixed point of the flow ϕ .
Hint: Assume that $\phi(t; a) \neq a$ so that $\|\phi(T; a) - a\| = \sigma > 0$ for some σ and T and apply (IIa).

Exercise 2.

Consider for $n \in \mathbb{N}$, $n \geq 1$, the planar – thus 2-dimensional – system,

$$\ddot{x} + x^n = 0 \quad \text{or} \quad \begin{cases} \dot{x} &= y, \\ \dot{y} &= -x^n. \end{cases} \quad (1)$$

This system defines a flow $\phi(t; x, y) : \mathbb{R} \times \mathbb{R}^2 \rightarrow \mathbb{R}^2$, parameterized by time t (a priori $\in \mathbb{R}$); solutions of (1) with initial condition (x_0, y_0) are denoted by $(x(t; x_0, y_0), y(t; x_0, y_0))$, orbits of the flow are denoted by $\Gamma(x_0, y_0)$.

- a) Explain why neither Theorem 4.6 nor Theorem 4.8 (in section 4.3 of the book) can be applied to system (1) on the unbounded domain \mathbb{R}^2 to conclude that solutions of (1) exist for all $t \in \mathbb{R}$, i.e. to conclude that (1) generates a complete flow.
Note: Theorems 4.6 and 4.8 in the revised edition of the book correspond to Theorems 4.3 and 4.5 in the original version of the book.
- b) System (1) is integrable with Hamiltonian H , i.e. orbits of (1) are given as level sets of a function $H(x, y)$. Determine $H(x, y)$.
Hint: Apply the standard procedure: multiply $\ddot{x} + x^n = 0$ by $\dot{x} (= y)$ and integrate over time.
- c) Consider n odd: show that (1) generates a complete flow, i.e. show that all solutions $(x(t; x_0, y_0), y(t; x_0, y_0))$ of (1) exist for all $t \in \mathbb{R}$.
Hint: Give a sketch of the phase portrait of (1) – or equivalently, of the orbits of the flow generated by (1) – and conclude that all orbits $\Gamma(x_0, y_0)$ – with $(x_0, y_0) \neq (0, 0)$ – are closed. What does this mean?
- d) Consider n even: define $\mathcal{S}_+ \subset \mathbb{R}^2$ as the set of all initial conditions such that the limit of $t \rightarrow \infty$ for solutions $(x(t; x_0, y_0), y(t; x_0, y_0))$ of (1) with $(x_0, y_0) \in \mathcal{S}_+$ exists (note that \mathcal{S}_+ coincides with the orbits $\Gamma(x_0, y_0)$ with $(x_0, y_0) \in \mathcal{S}_+$). Determine \mathcal{S}_+ explicitly. Do the same for $\mathcal{S}_- \subset \mathbb{R}^2$ – the set of all initial conditions such that the limit $t \rightarrow -\infty$ of solutions $(x(t; x_0, y_0), y(t; x_0, y_0))$ of (1) exists.
- e) (n even) Give a sketch of the phase portrait of (1), including \mathcal{S}_+ and \mathcal{S}_- .
- f) (n even) The solutions $(x(t; x_0, y_0), y(t; x_0, y_0))$ of (1) with $(x_0, y_0) \in \mathcal{S}_-$ can be determined explicitly. Show that these solutions blow up in finite (positive) time.
- g) (n even) Consider the solutions $(x(t; x_0, y_0), y(t; x_0, y_0))$ of (1) with $(x_0, y_0) \notin \mathcal{S}_+$. Show that for all $K > 0$ there is a T such $x(t; x_0, y_0) < -K$ and $y(t; x_0, y_0) < -K$ for all $t \geq T$.
- h) (n even) Show that – except for the trivial, critical point, solution $(x(t; 0, 0), y(t; 0, 0)) \equiv (0, 0)$ – there are no solutions $(x(t; x_0, y_0), y(t; x_0, y_0))$ of (1) that exist for all $t \in \mathbb{R}$.